

# Interferometry on 2D DAS Arrays

Eileen Martin  
coauthor: Biondo Biondi

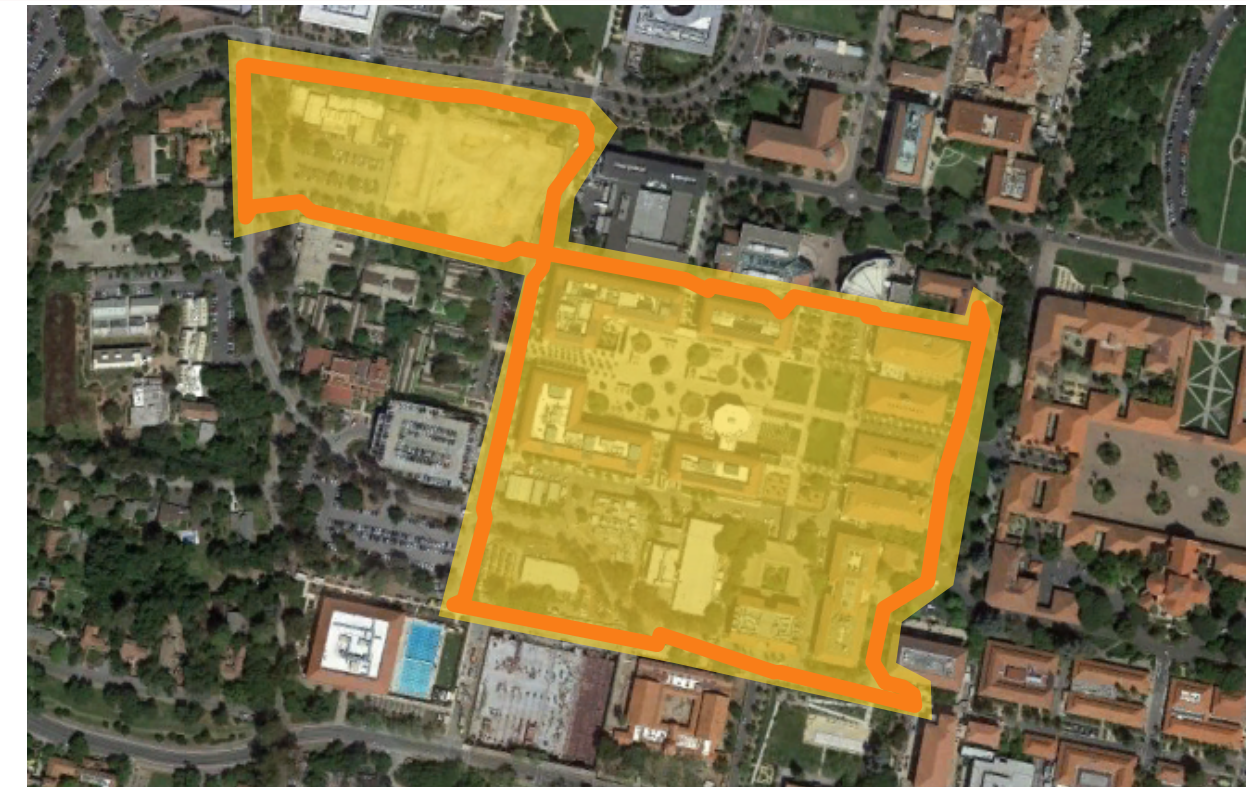
Richmond Field  
Station (LBL,  
Corps of Engineers)



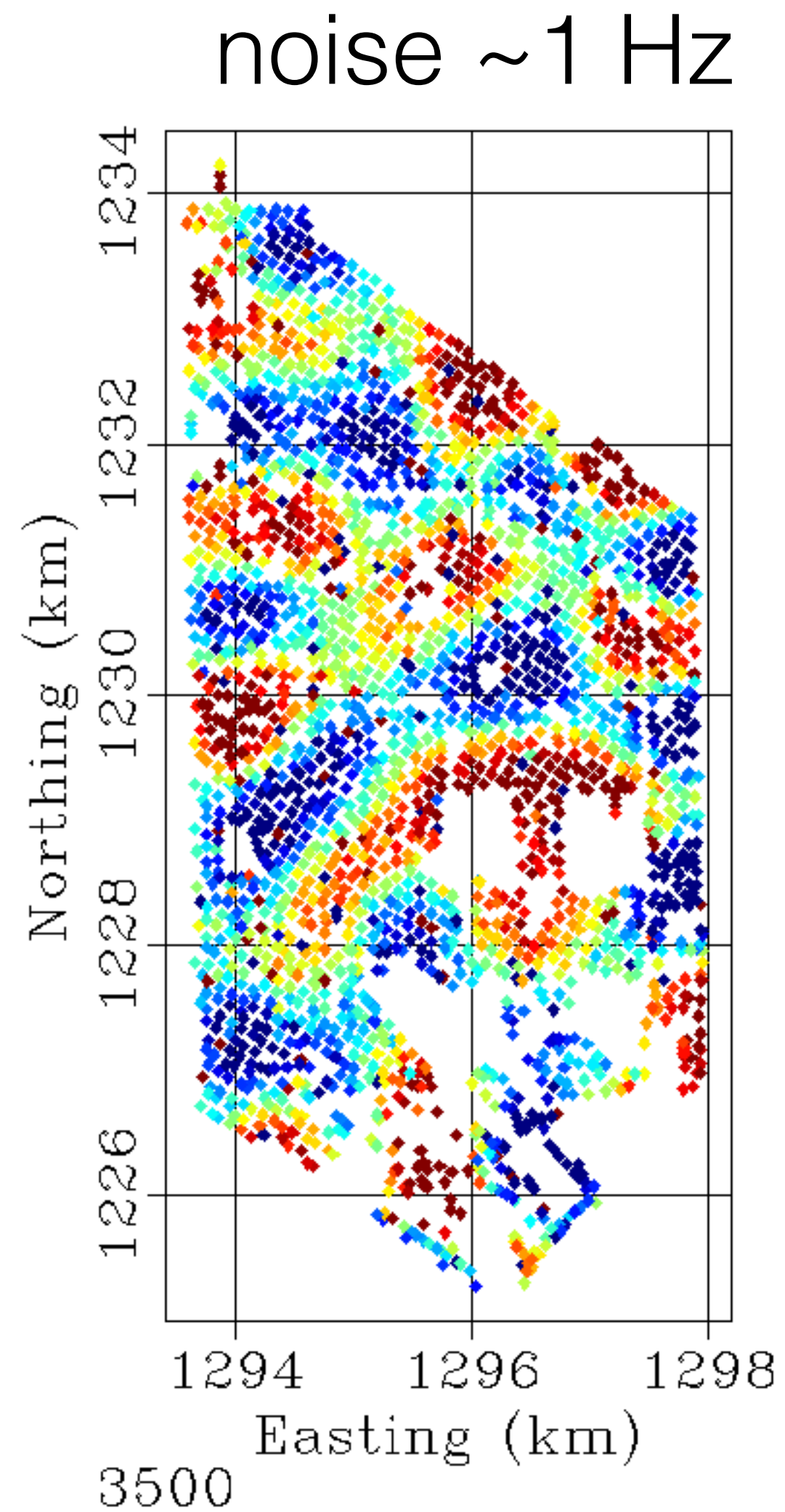
Fairbanks, AK (LBL,  
Corps of Engineers)



SDASA-1



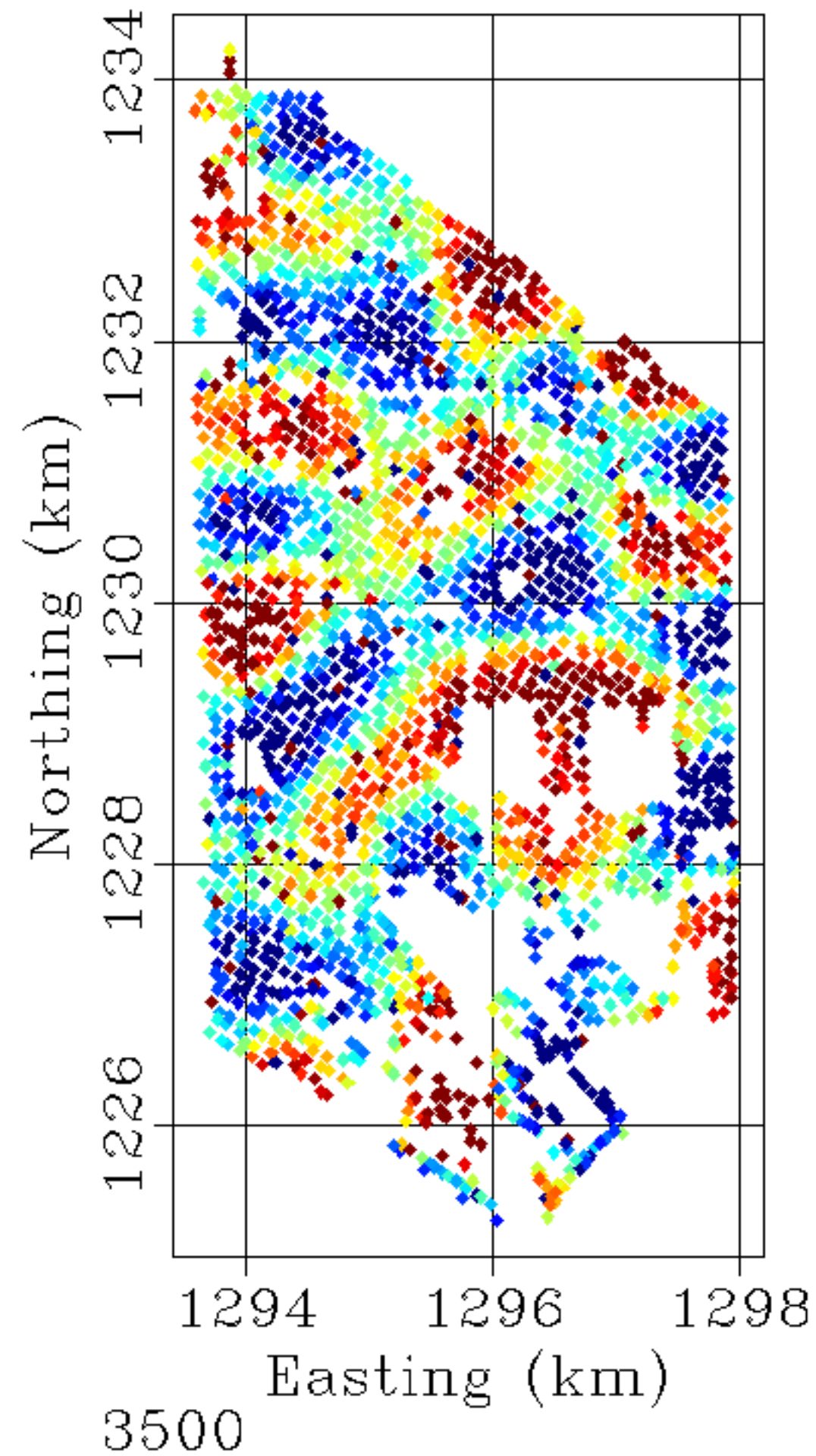
# Ambient noise interferometry can reduce costs



Example from Jason Chang (Stanford), data c/o Nodal Seismic

# Ambient noise interferometry can reduce costs

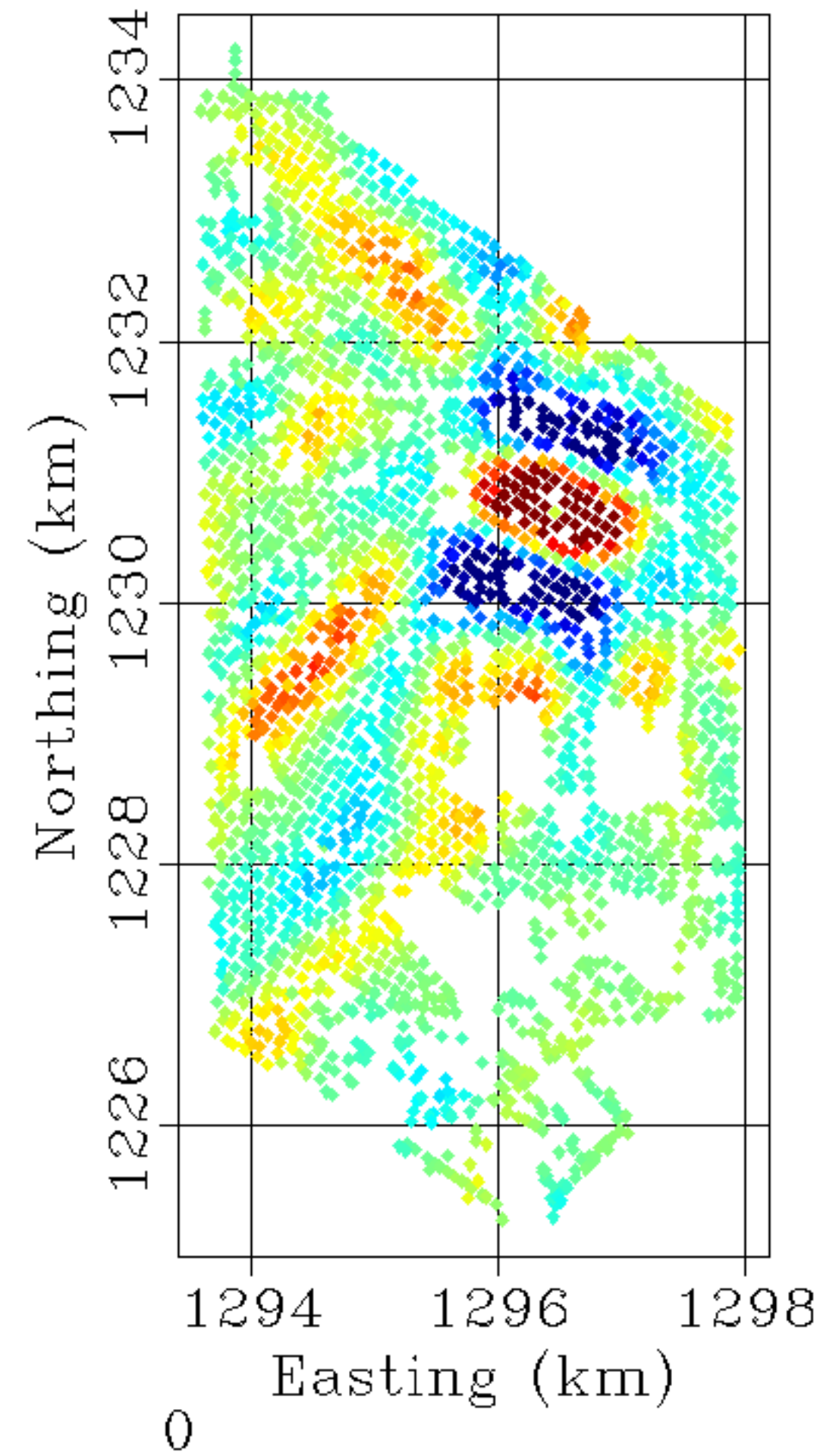
noise ~1 Hz



correlations  
between windows  
of noise



signal mimicking  
active survey

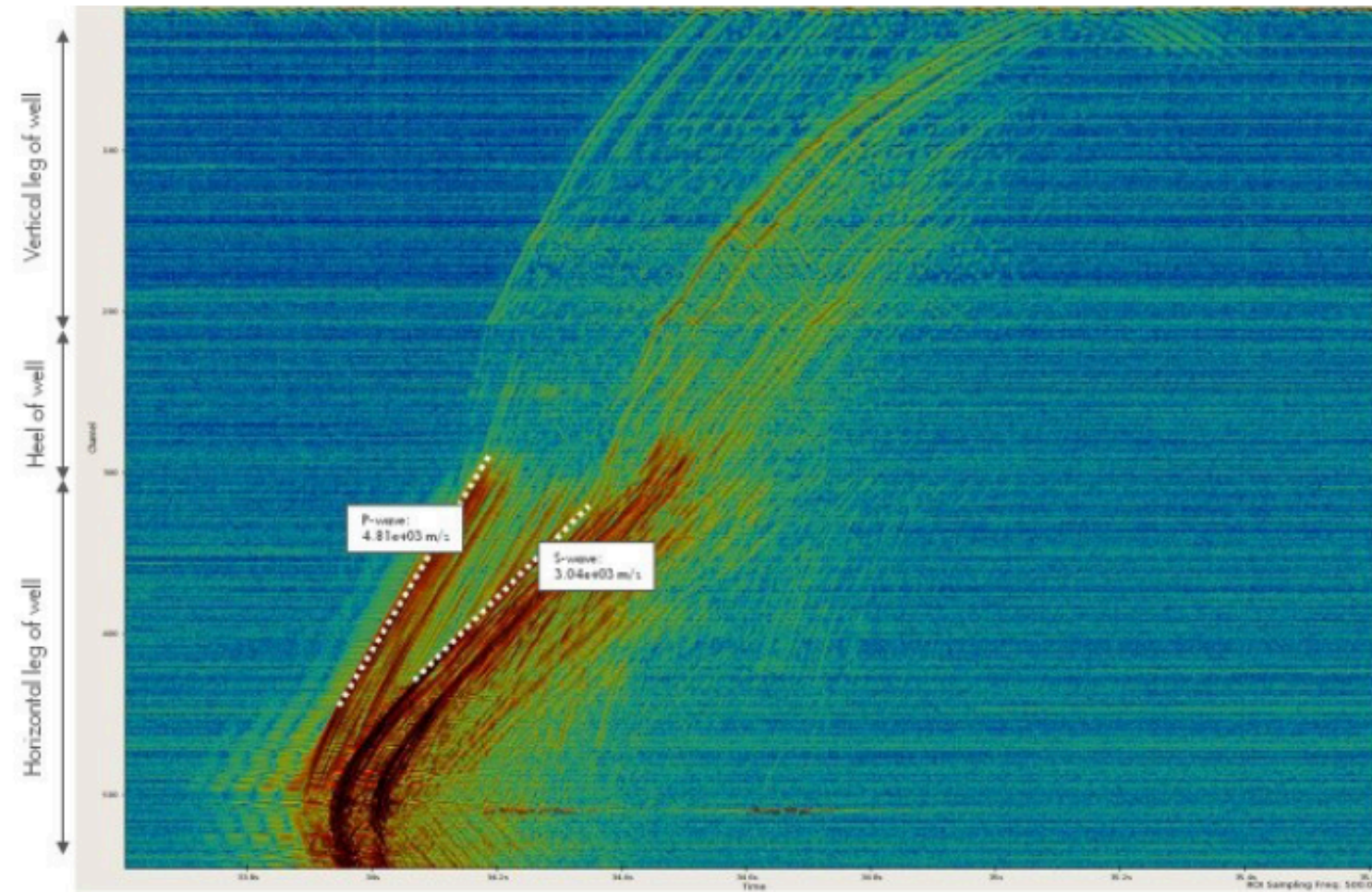


benefits:

no source crew cost

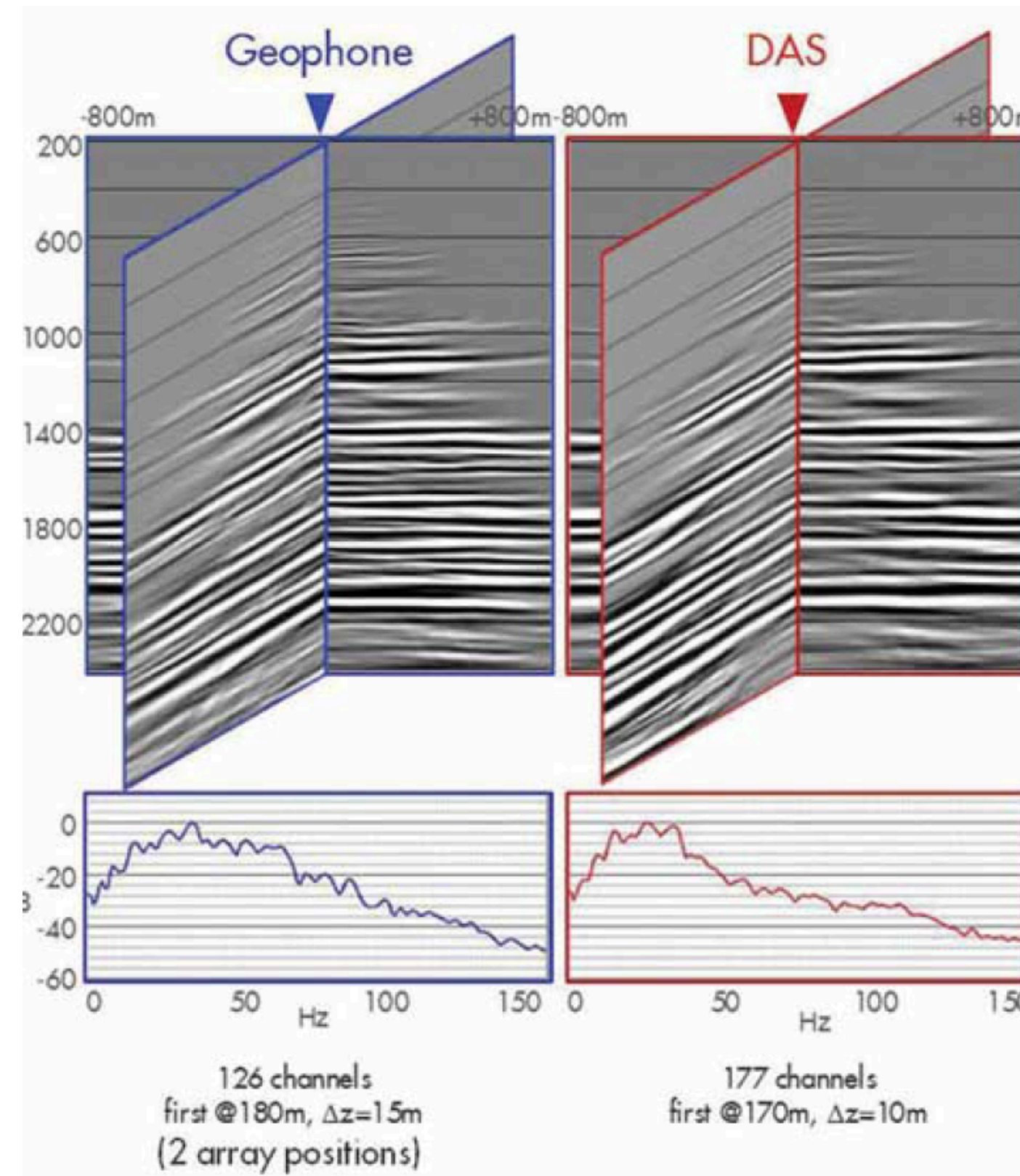
less time than  
waiting for  
earthquakes

# DAS is being used to lower costs in oil & gas



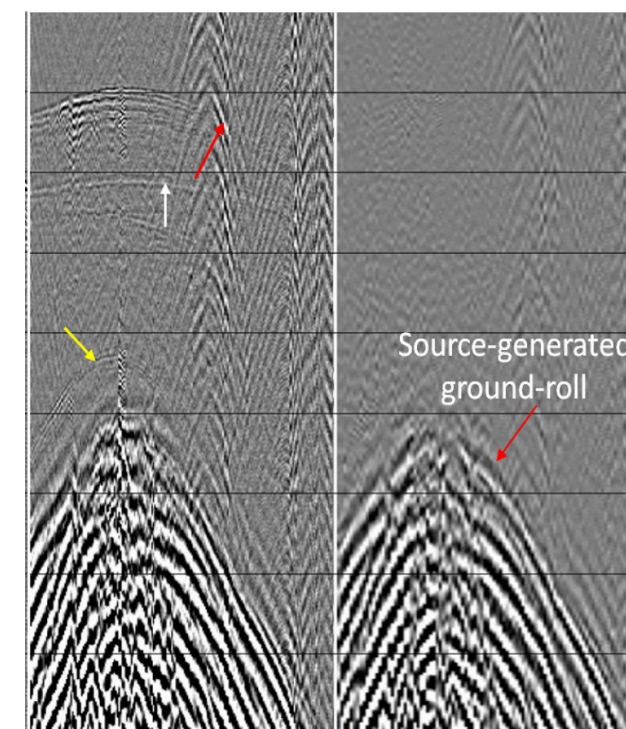
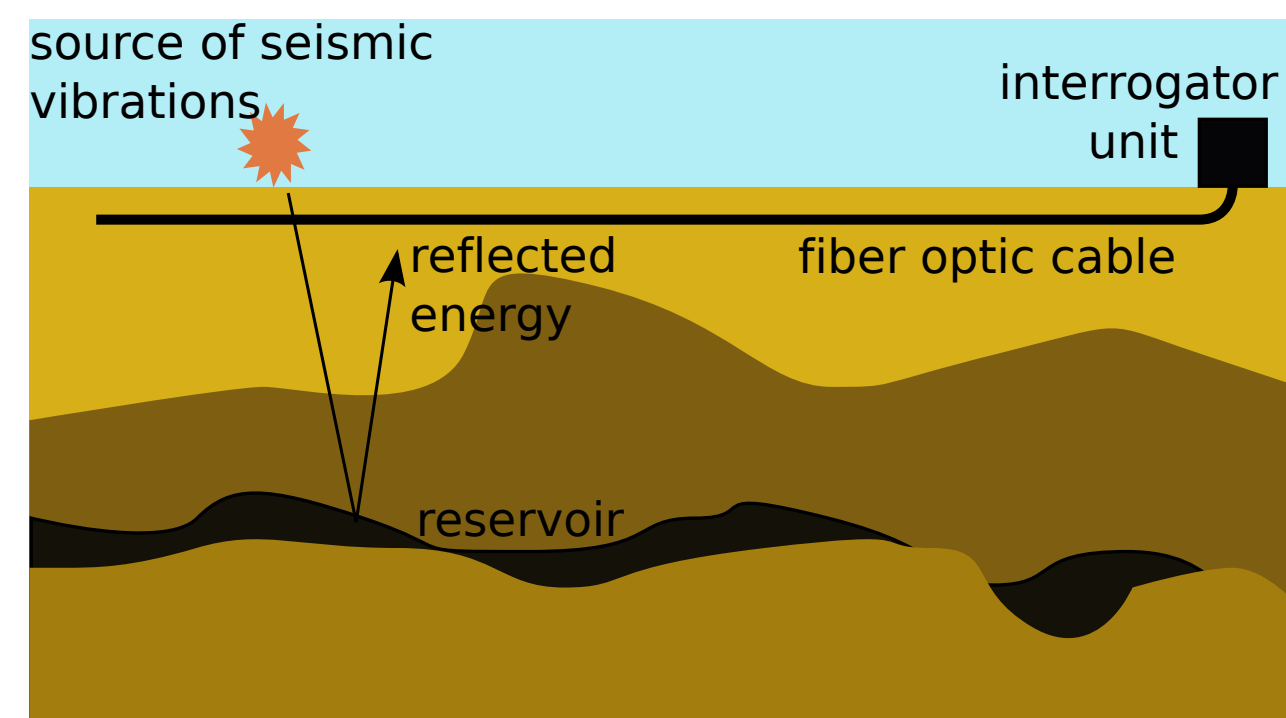
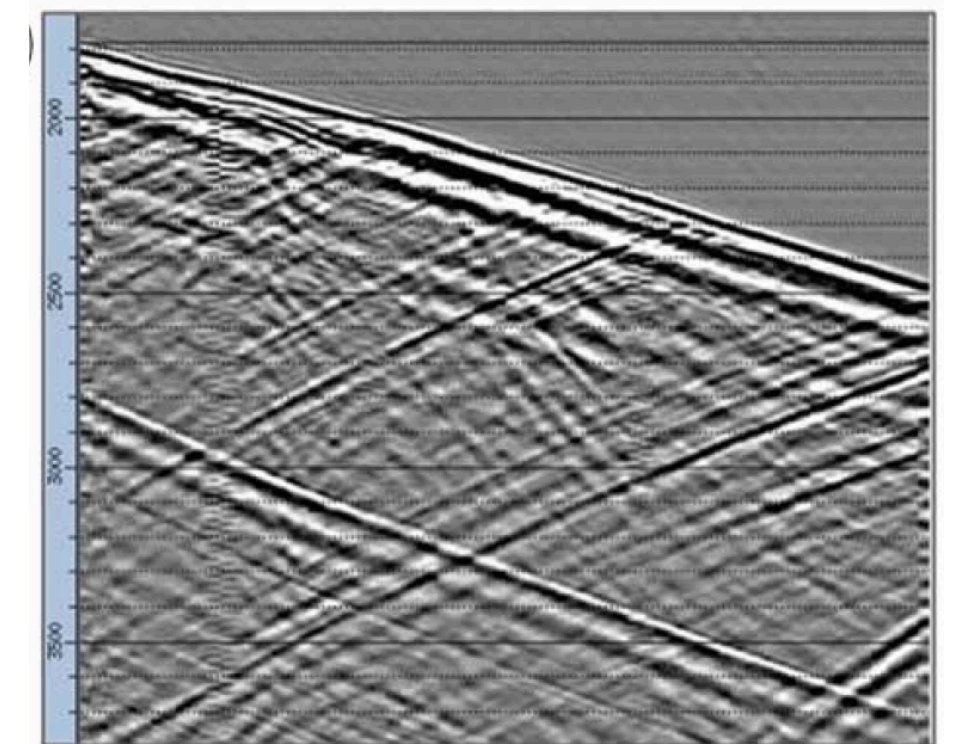
Microseismic monitoring with full well coverage

Webster et al. 2013 SEG Extended Abstracts



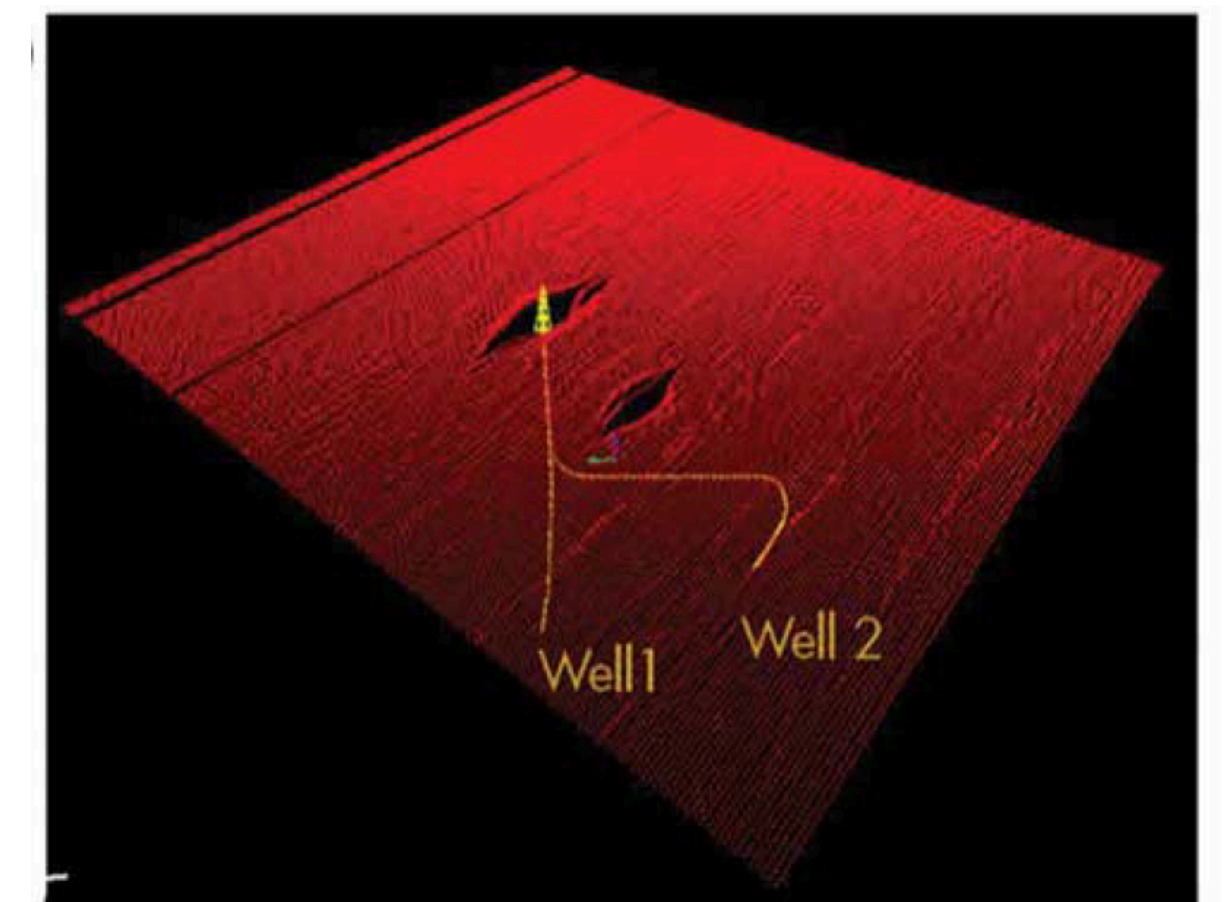
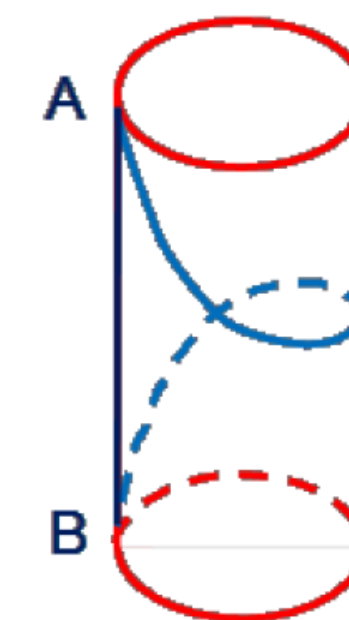
Repeatable 4D seismic offshore and onshore with fiber covering full well

Mateeva et al. 2013 The Leading Edge

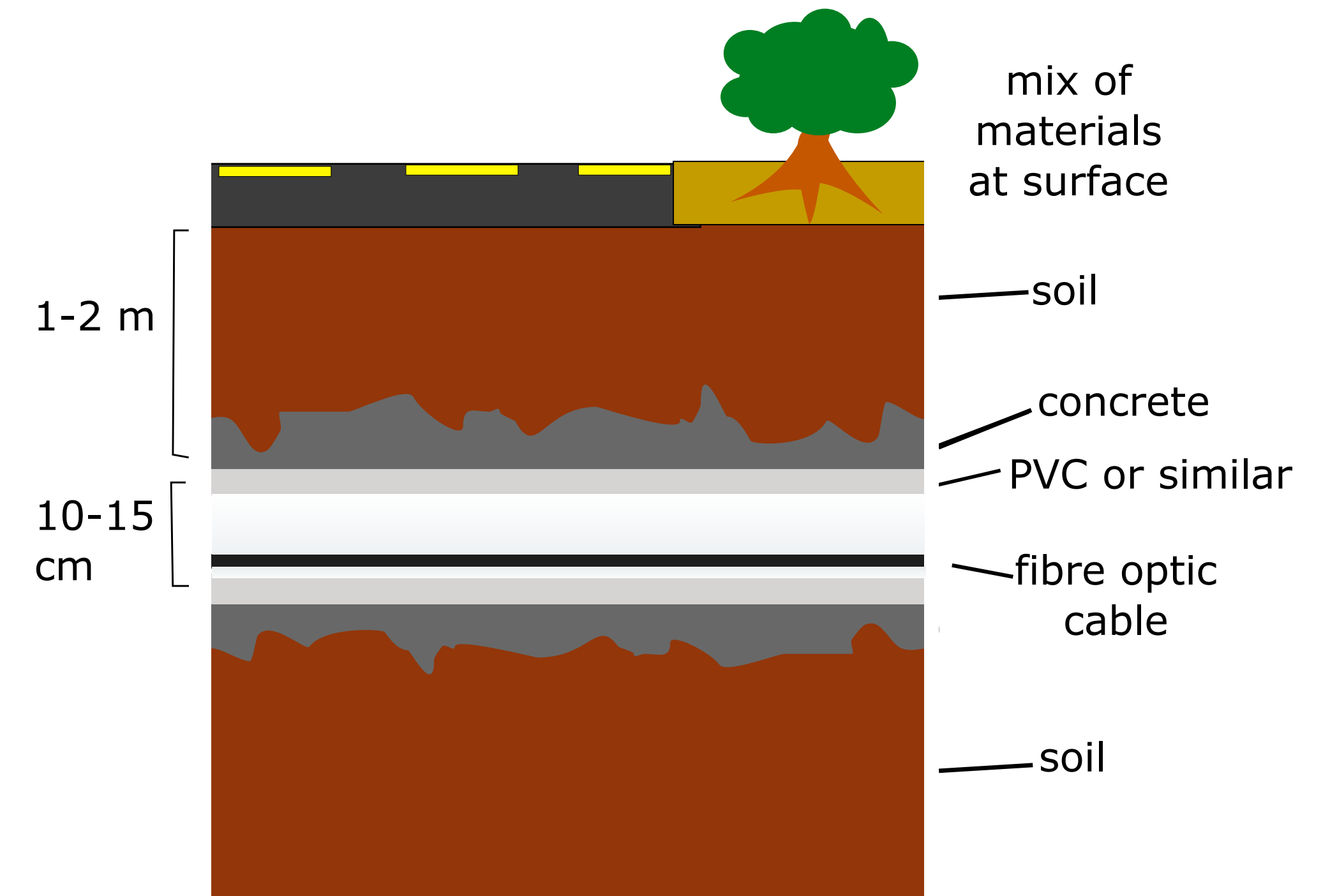
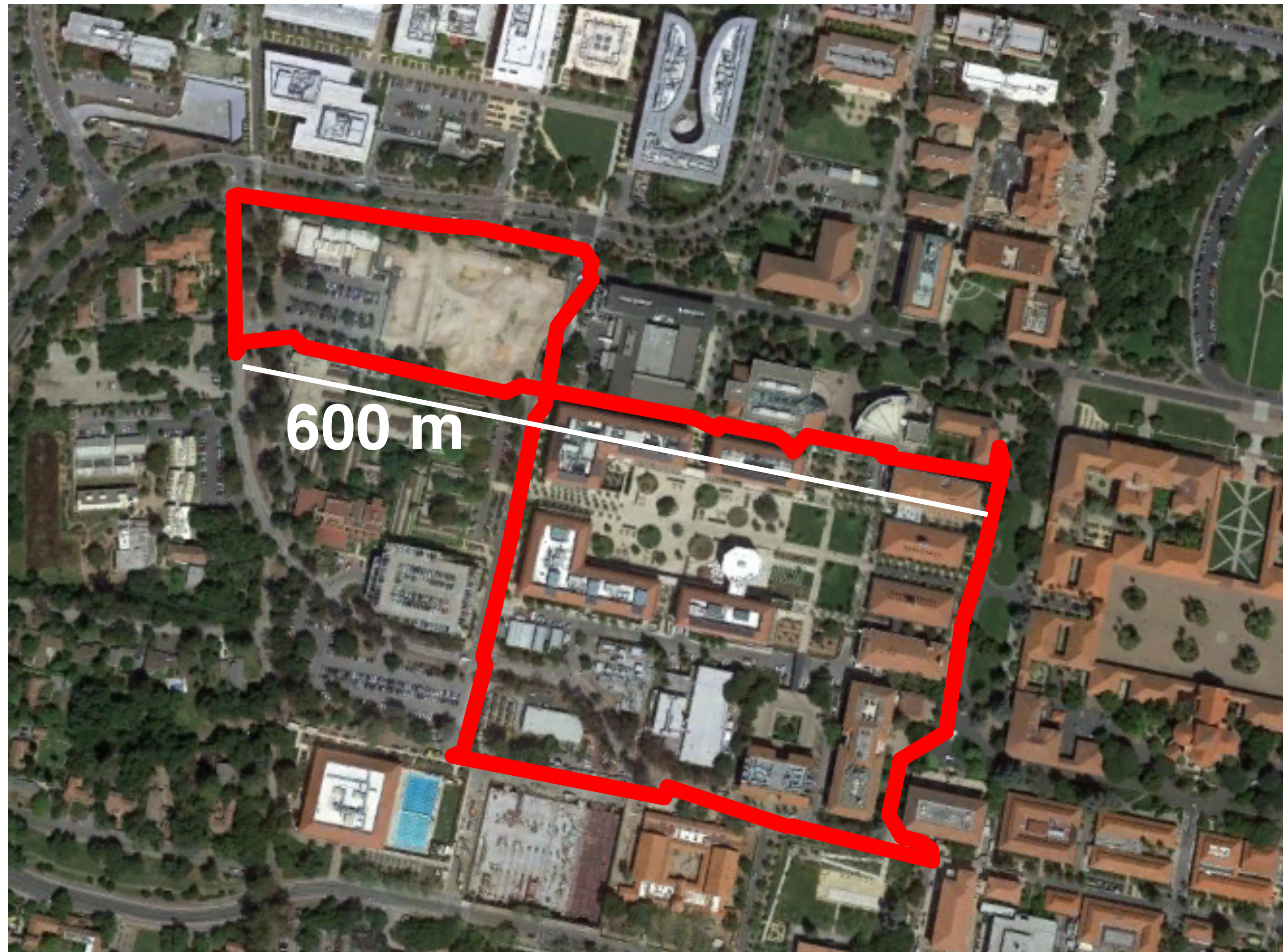


Reflection seismology with helical fibers

Hornman et al. 2013 EAGE Conference Abstracts



# Stanford DAS Array-1 (SDASA-1)

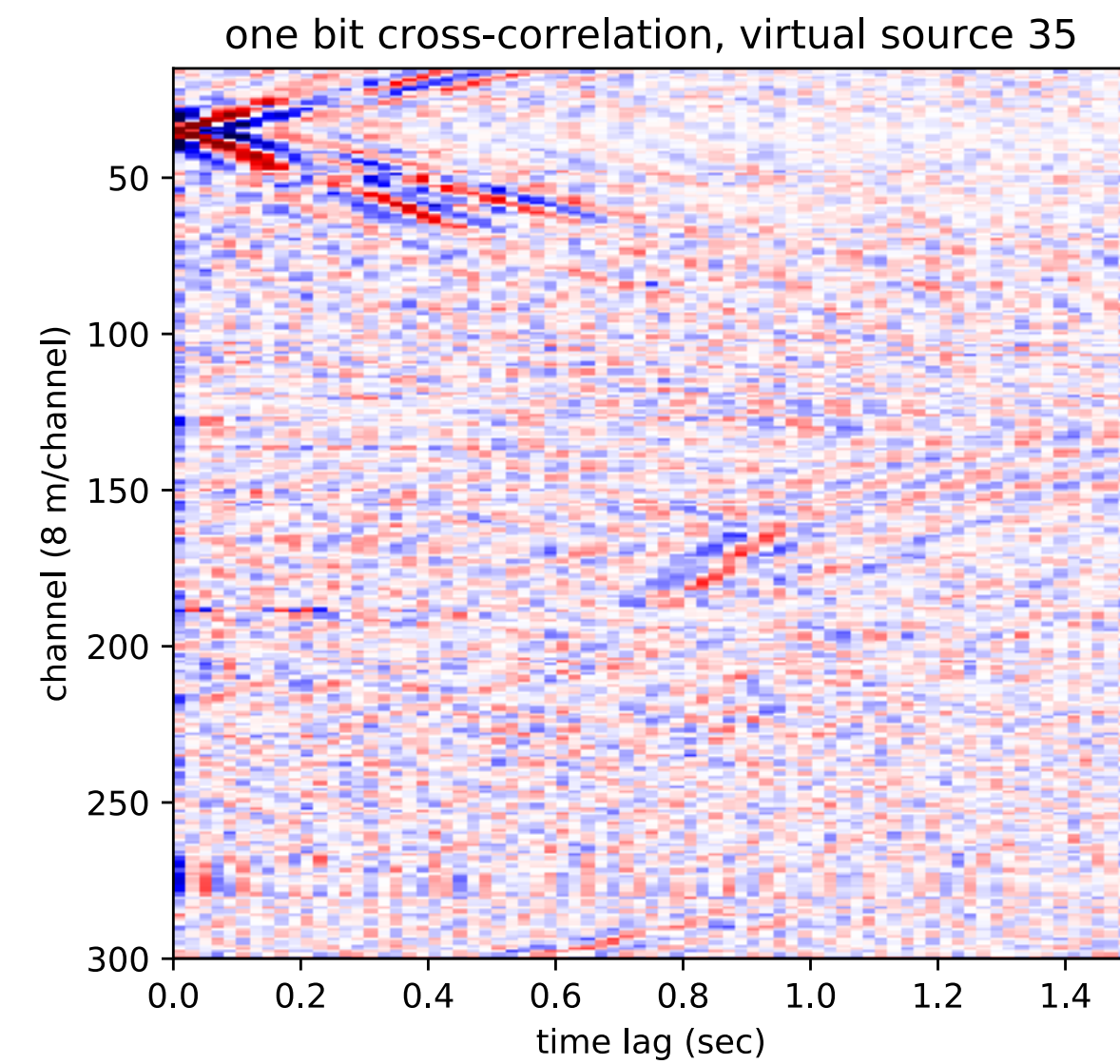


collaboration with Martin Karrenbach and Steve Cole

at **OptaSense**<sup>®</sup>  
a QinetiQ company

# Objectives of SDASA-1

ambient noise  
tomography for  
near-surface  
imaging

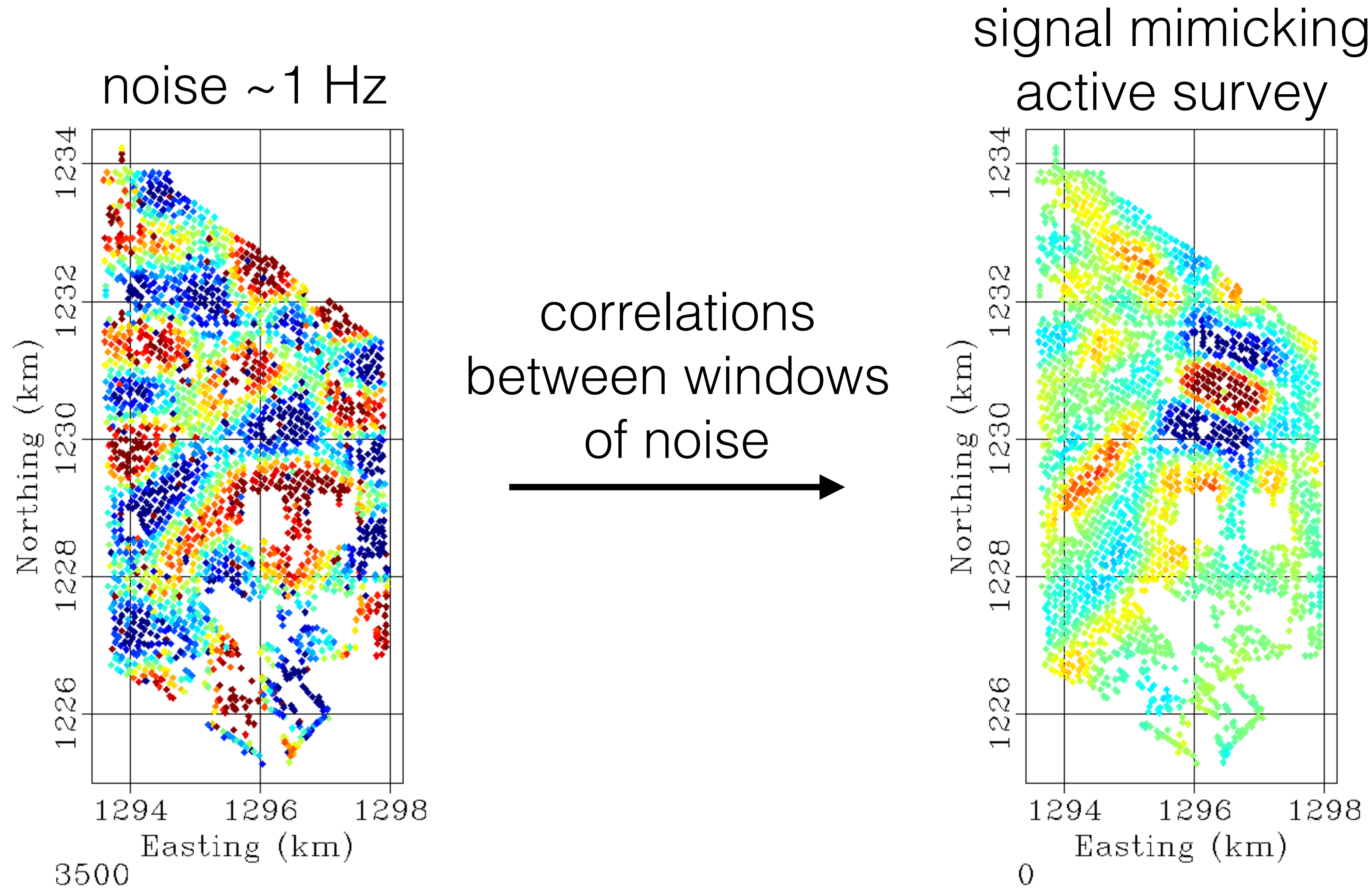








# Ambient noise interferometry can reduce costs

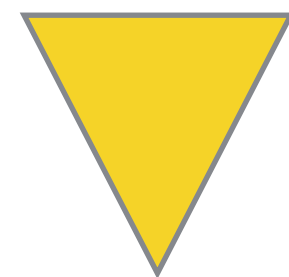
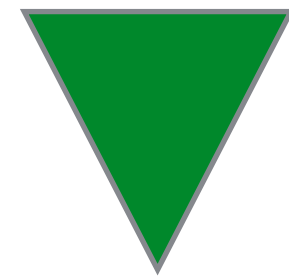
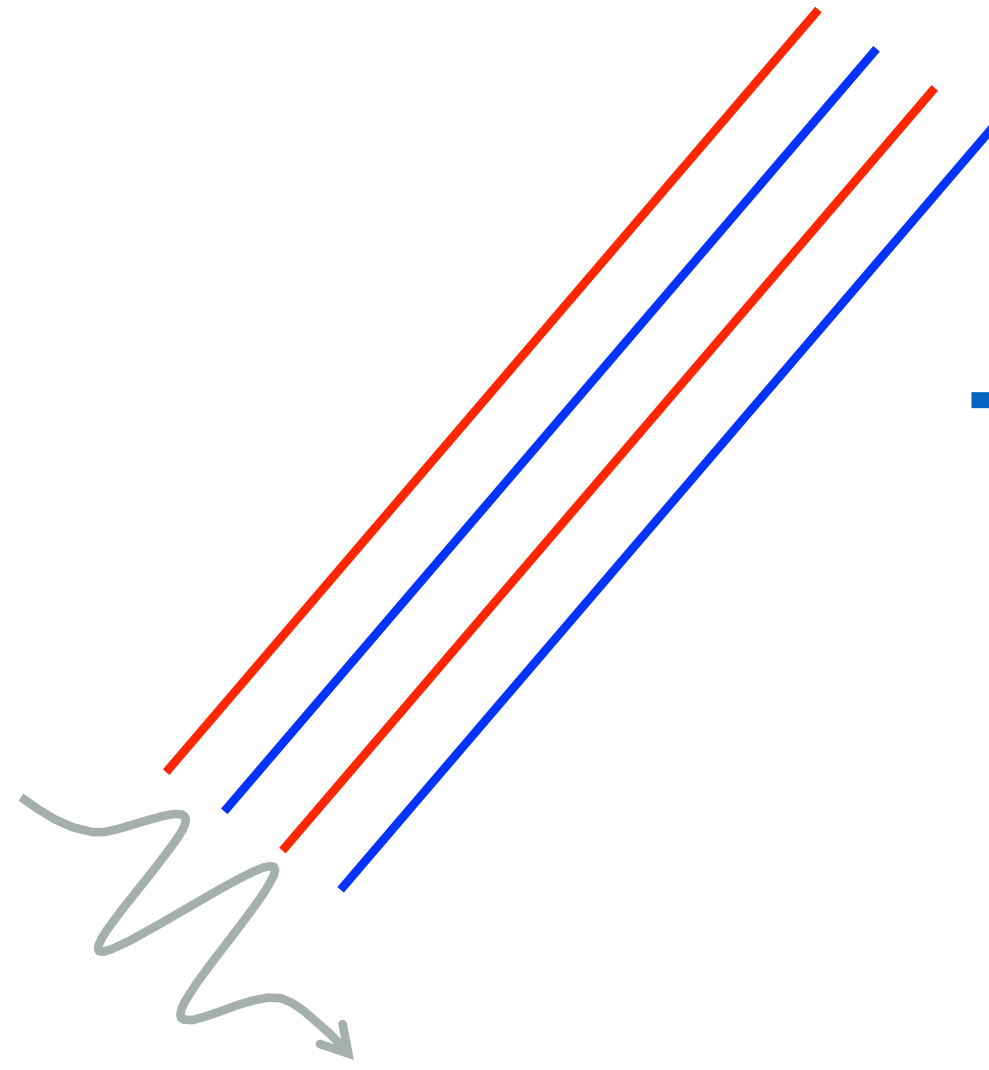


Example from Jason Chang (Stanford), data c/o Nodal Seismic

# How cross-correlation works

for real time series , cross-correlation is a time-lagged dot product

$$C(\tau) = \int_{-\infty}^{\infty} \underline{d(x_r, t)} \underline{d(x_v, t + \tau)} dt$$

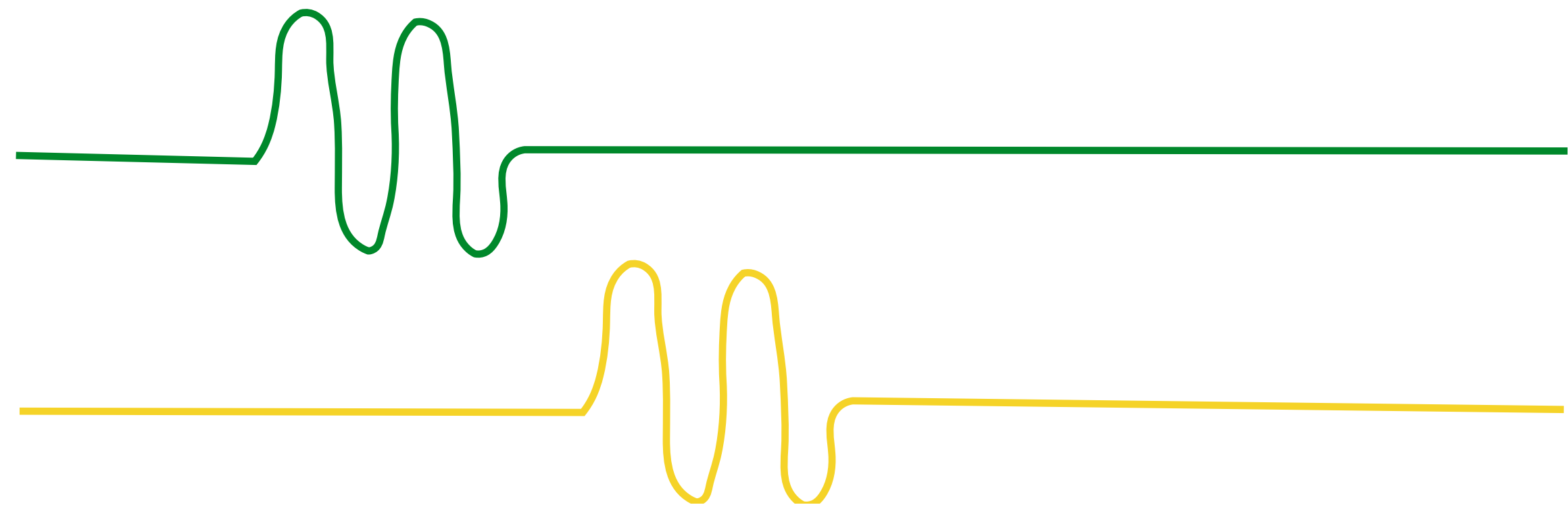
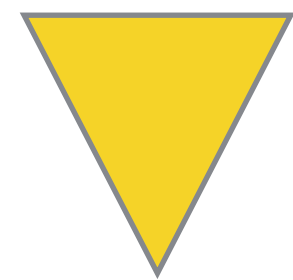
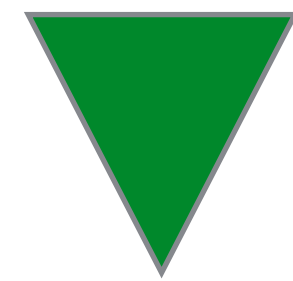


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$$\underline{C(\tau)} = \int_{-\infty}^{\infty} \underline{d(x_r, t)} \underline{d(x_v, t + \tau)} dt$$

$\tau = 0$  ,  $C = 0$



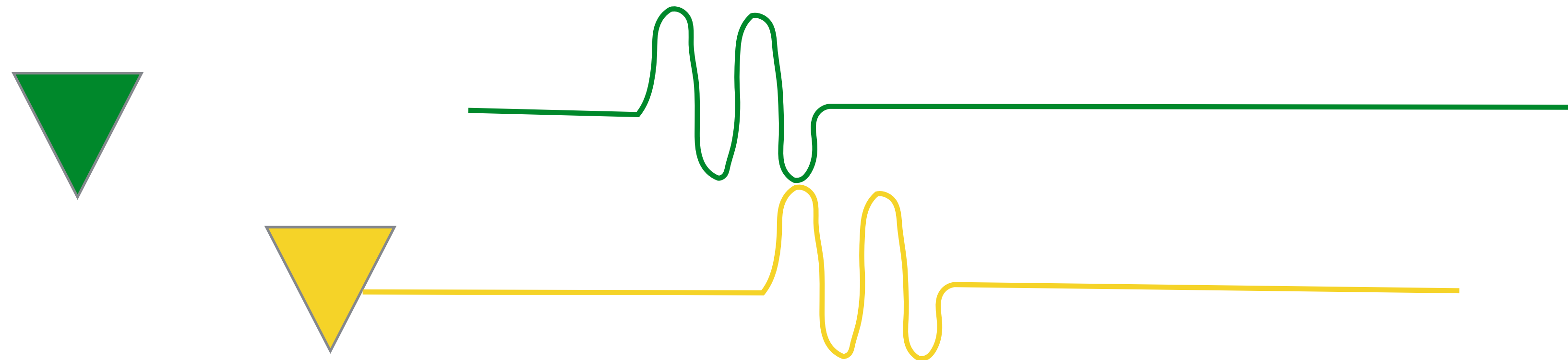
cross-correlation  $C =$  —

# How cross-correlation works

for real time series, cross-correlation is a time-lagged dot product

$$\underline{C(\tau)} = \int_{-\infty}^{\infty} \underline{d(x_r, t)} \underline{d(x_v, t + \tau)} dt$$

$\tau > 0, C < 0$

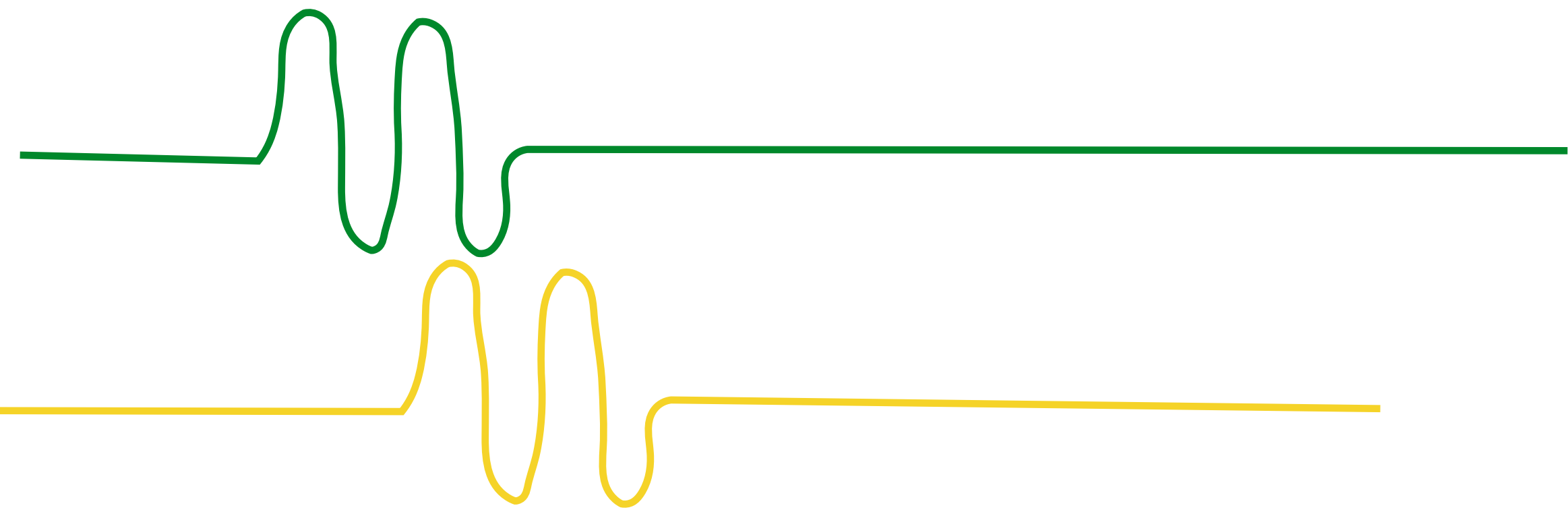
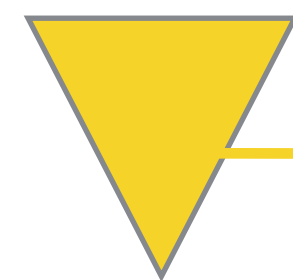
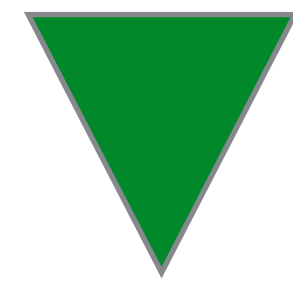


cross-correlation  $C =$  

# How cross-correlation works

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$$\underline{C(\tau)} = \int_{-\infty}^{\infty} \underline{d(x_r, t)} \underline{d(x_v, t + \tau)} dt$$



**C = 0**

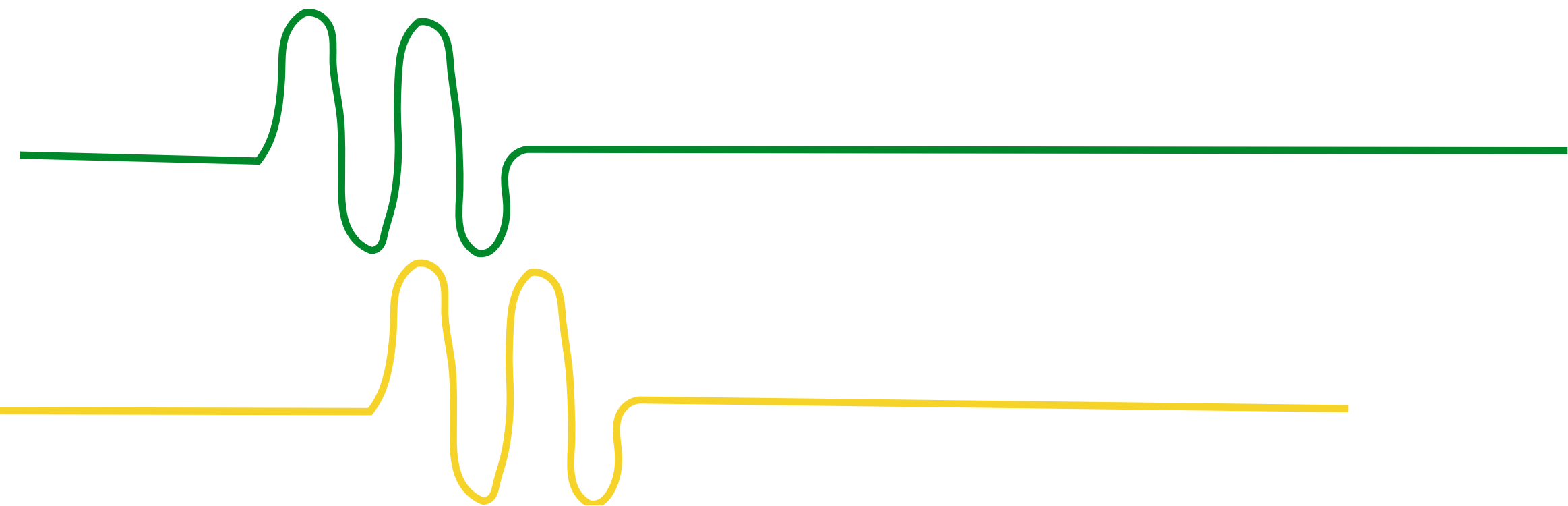
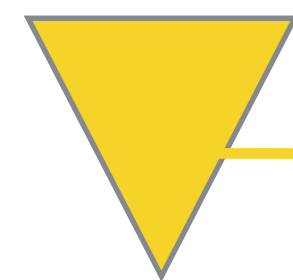
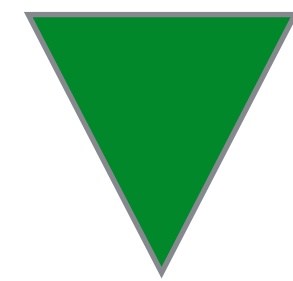
peaks and 0s line up

cross-correlation  $C =$  A blue line that starts flat at a baseline level, then has a sharp downward-pointing curve, and then returns to the baseline.

# How cross-correlation works

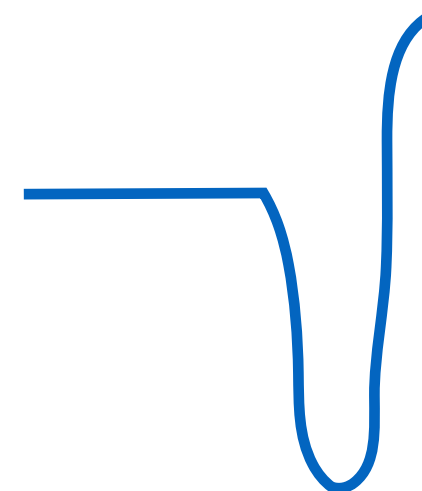
for real time series , cross-correlation is a time-lagged dot product

$$\underline{C(\tau)} = \int_{-\infty}^{\infty} \underline{d(x_r, t)} \underline{d(x_v, t + \tau)} dt$$



$C > 0$

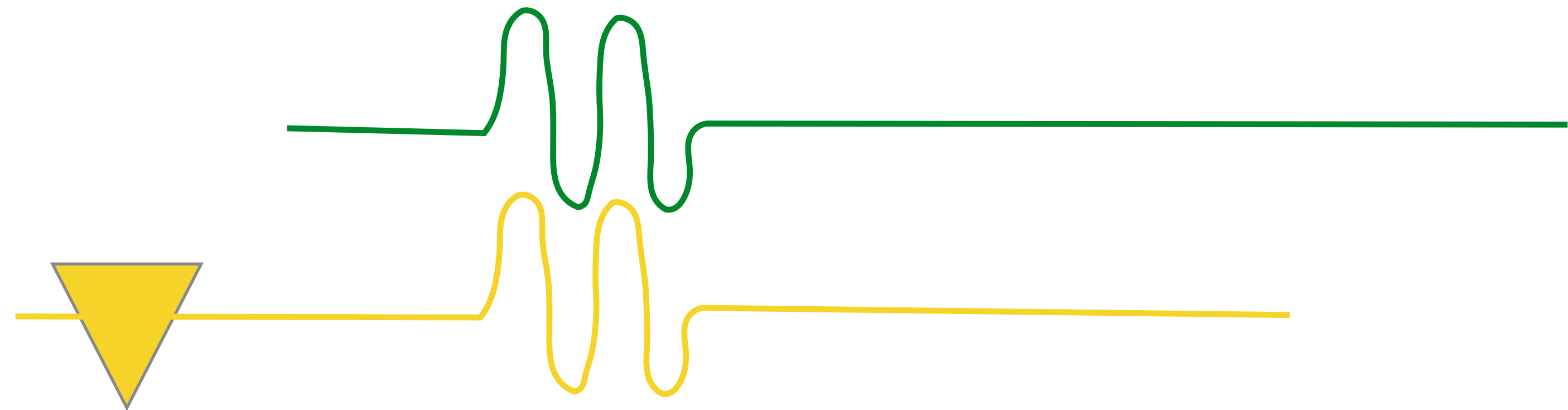
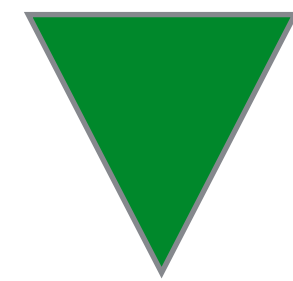
cross-correlation  $C =$



# How cross-correlation works

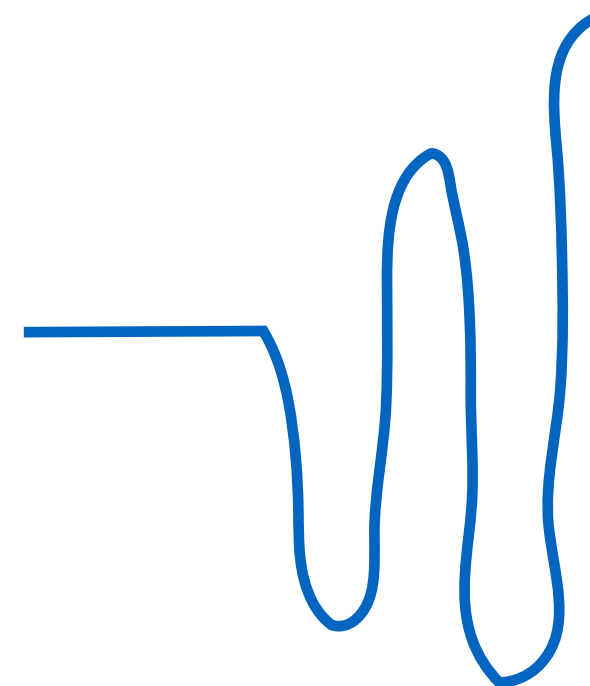
for real time series , cross-correlation is a time-lagged dot product

$$\underline{C(\tau)} = \int_{-\infty}^{\infty} \underline{d(x_r, t)} \underline{d(x_v, t + \tau)} dt$$



$C \gg 0$

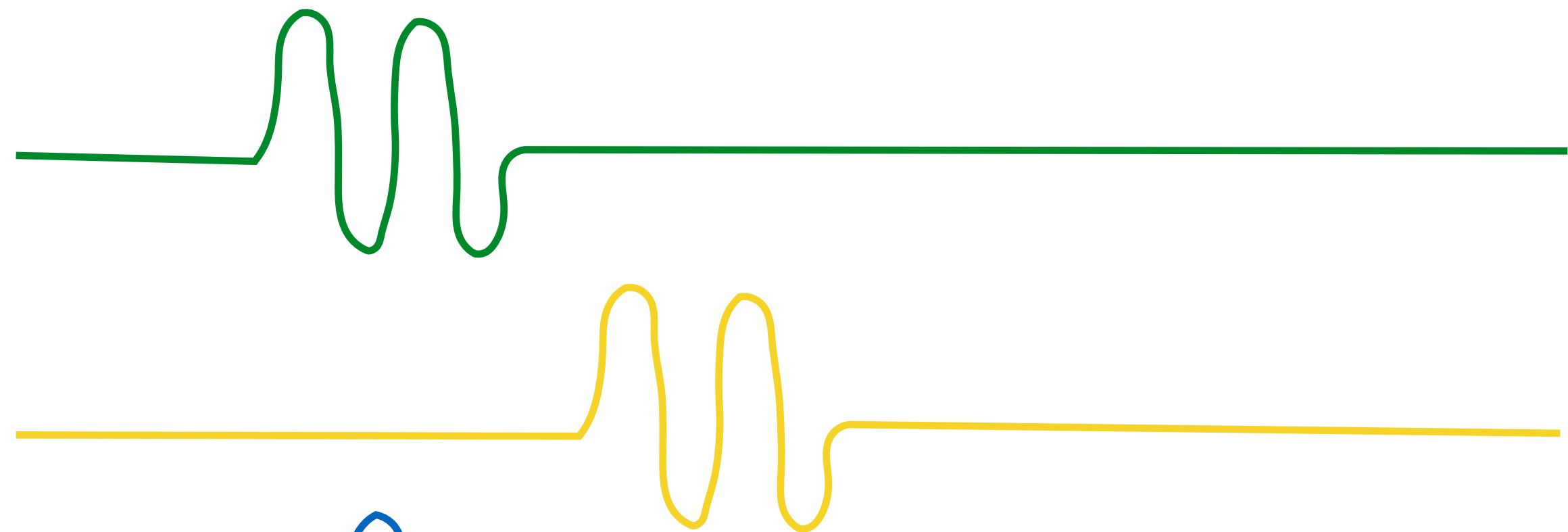
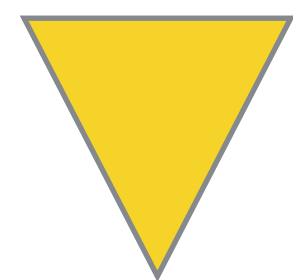
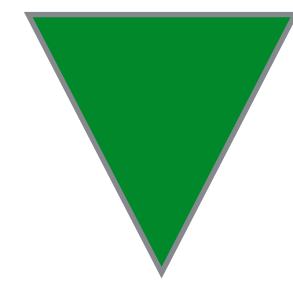
cross-correlation  $C =$



# How cross-correlation works

for real time series , cross-correlation is a time-lagged dot product

$$\underline{C(\tau)} = \int_{-\infty}^{\infty} \underline{d(x_r, t)} \underline{d(x_v, t + \tau)} dt$$



cross-correlation C =



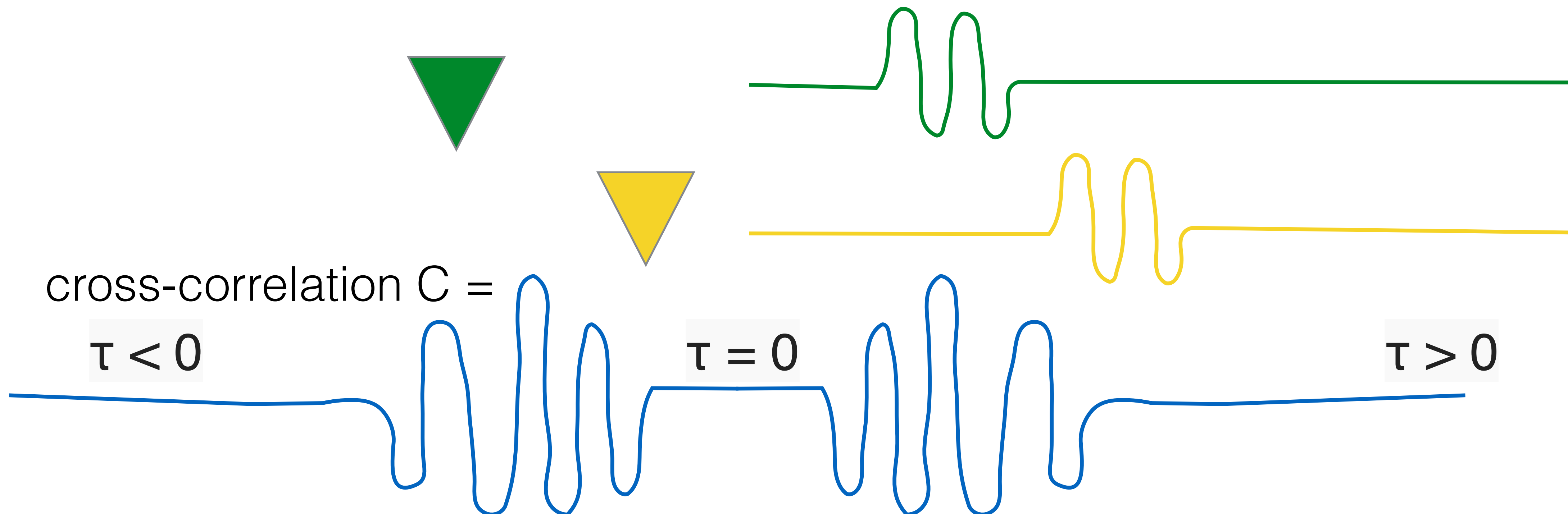


# How cross-correlation works

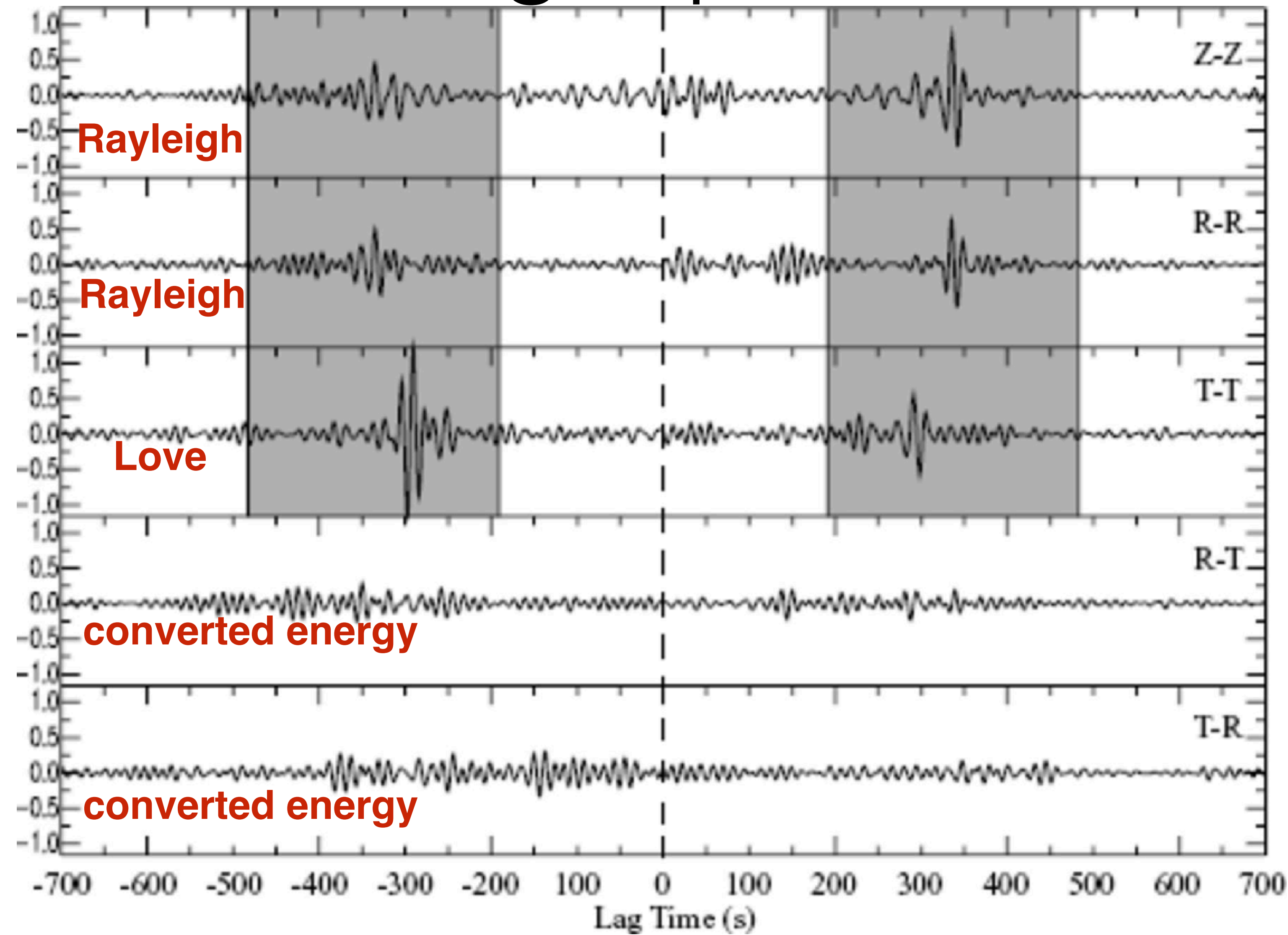
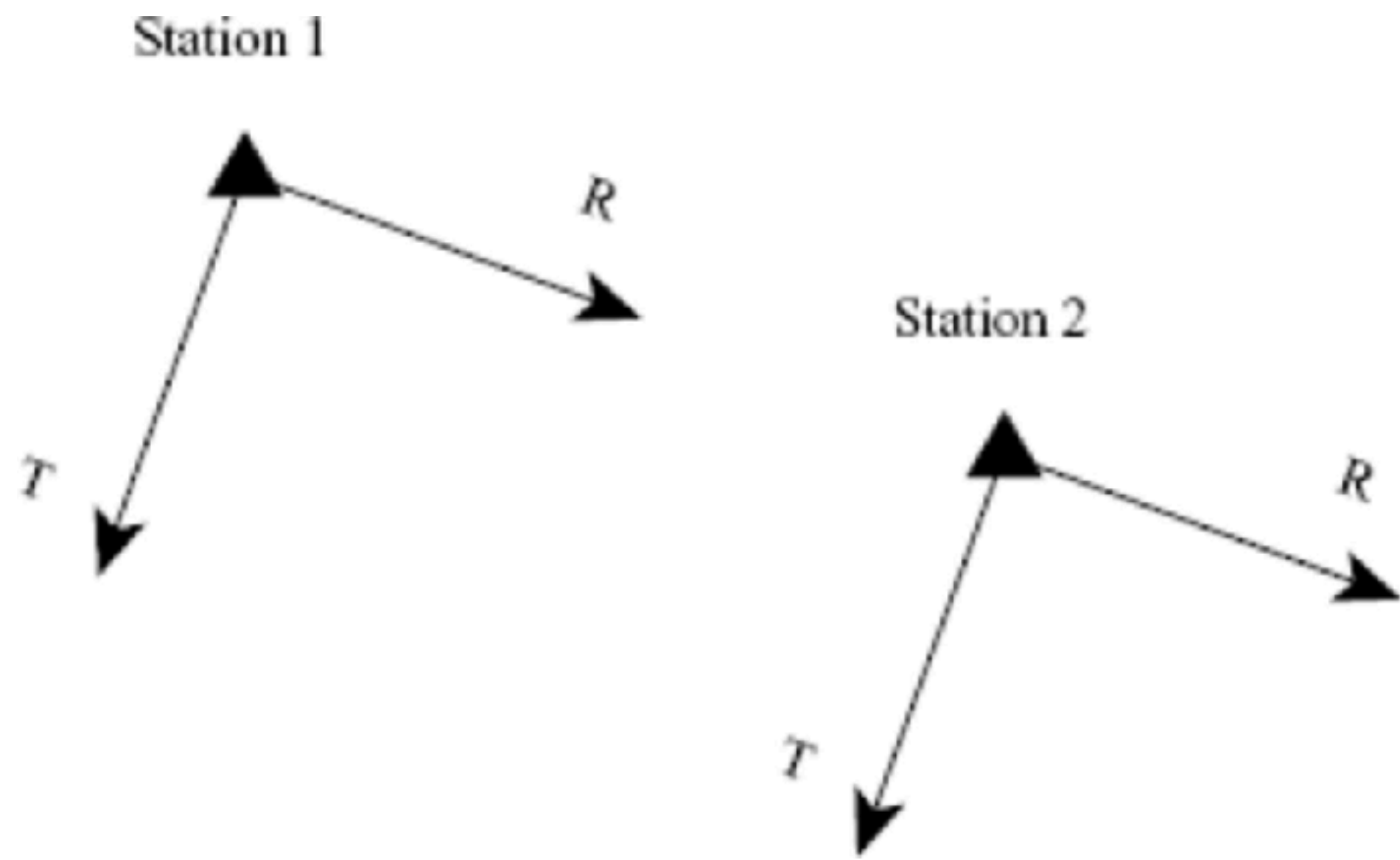
with white, **uncorrelated** spatially homogeneous noise sources on all sides

for real time series, cross-correlation is a time-lagged dot product

$$\underline{C(\tau)} = \int_{-\infty}^{\infty} \underline{d(x_r, t)} \underline{d(x_s, t + \tau)} dt$$



# Ambient noise with 3C geophones



# Collinear Channel Cross-Correlations



$$m(x, t) = d(x + g, t) - d(x, t) \quad \text{measurement difference of in-line point sensor data}$$

cross-correlation      strains measured

$$C(\tau) = \int m(x_r, t) m(x_{vs}, t + \tau) dt$$

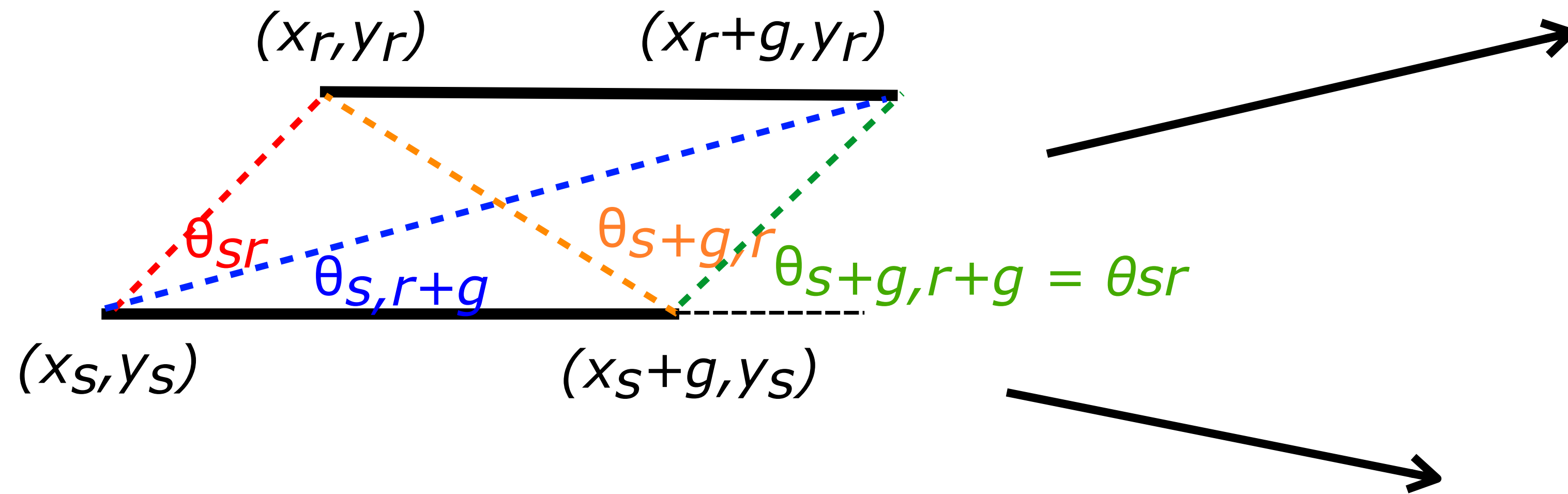
$$= \int d(x_r + g, t) d(x_{vs} + g, t + \tau) dt - \int d(x_r + g, t) d(x_{vs}, t + \tau) dt$$

$$- \int d(x_r, t) d(x_{vs} + g, t + \tau) dt + \int d(x_r, t) d(x_{vs}, t + \tau) dt$$

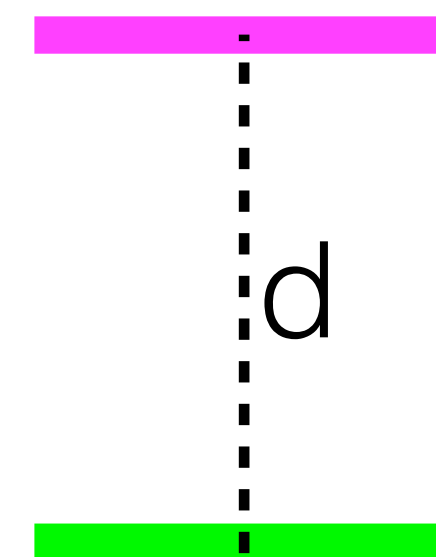
point displacements

$$= C_{r+g,vs+g}(\tau) - C_{r+g,vs}(\tau) - C_{r,vs+g}(\tau) + C_{r,vs}(\tau)$$

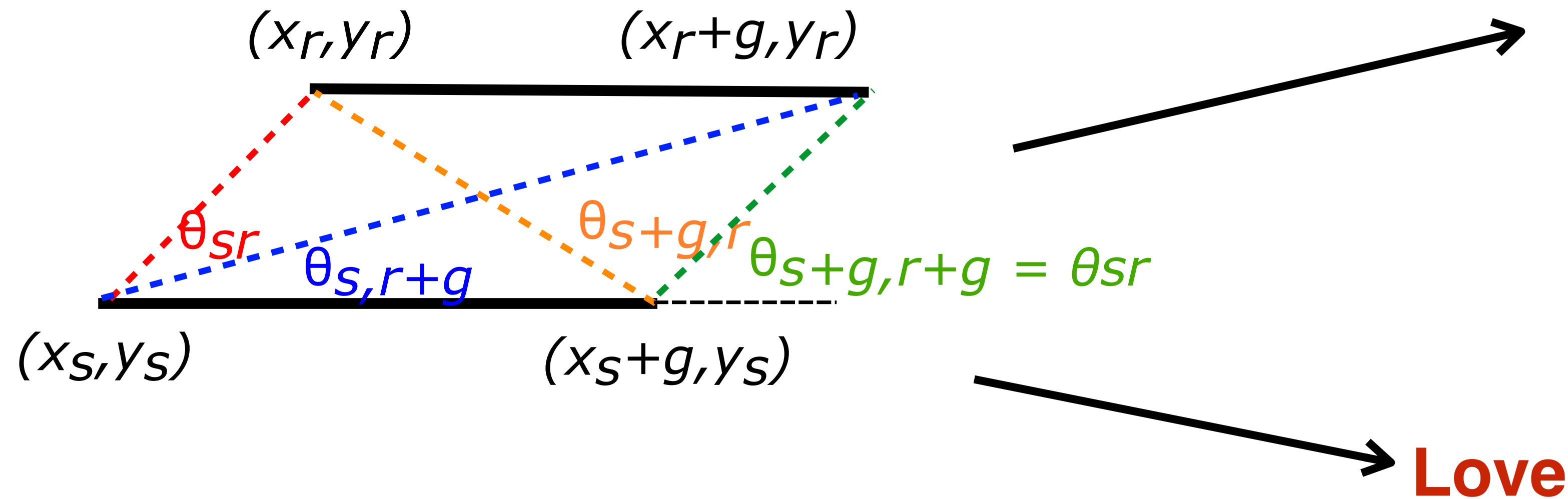
# Parallel Fibers are Simple Case



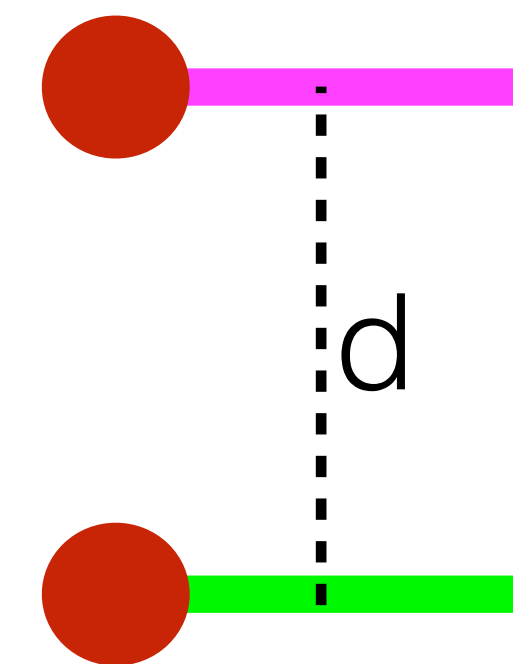
collinear channels yield  
Rayleigh waves



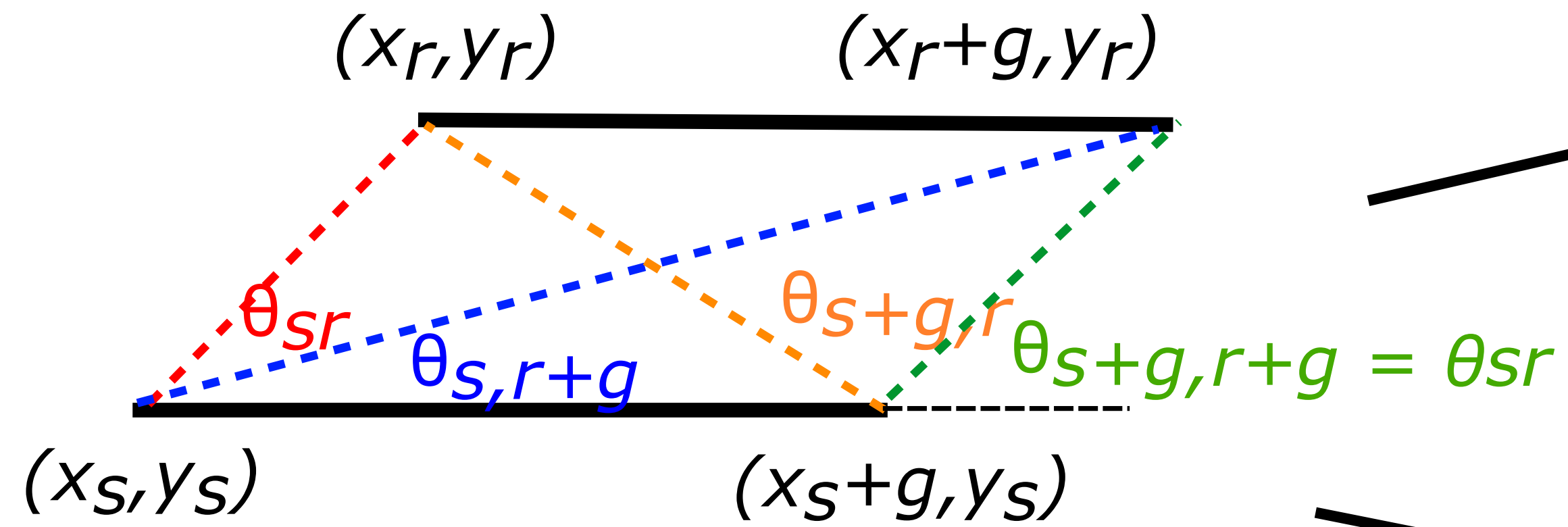
# Parallel Fibers are Simple Case



collinear channels yield  
Rayleigh waves



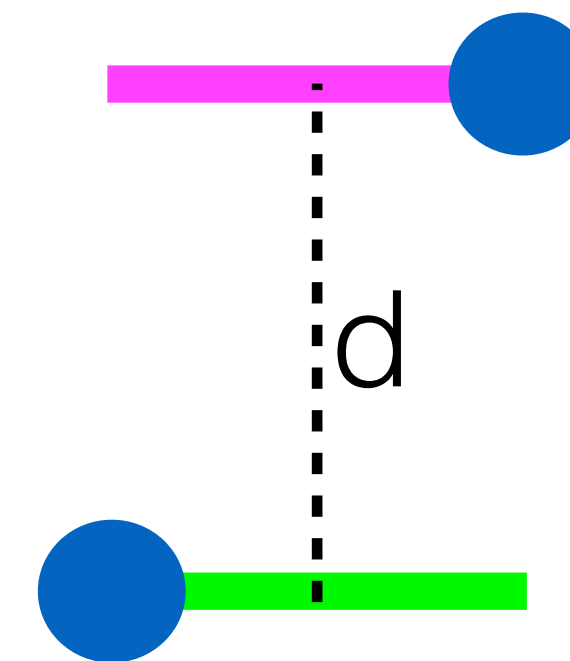
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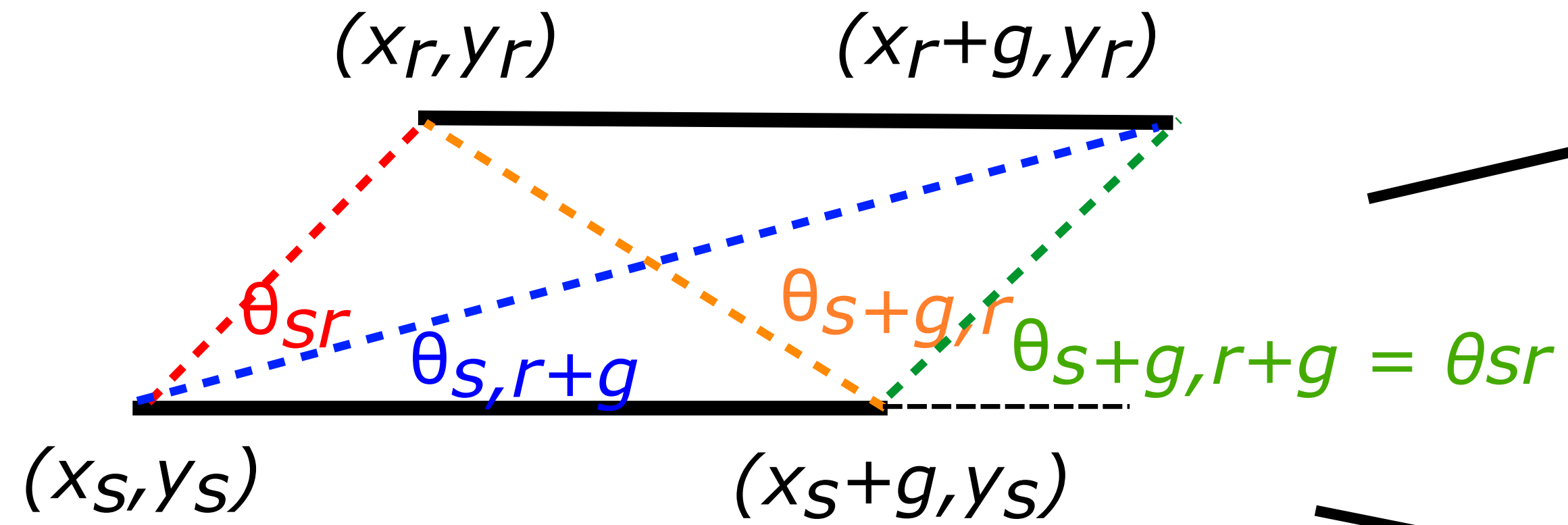
collinear channels yield  
Rayleigh waves



**Love** + **mixed**



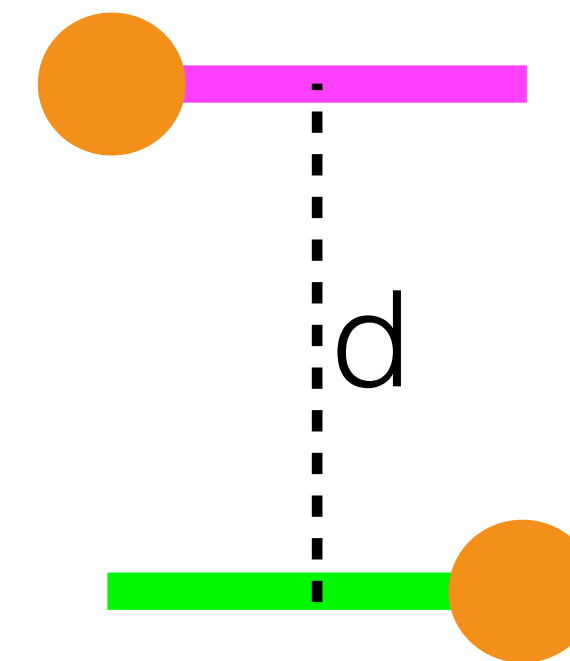
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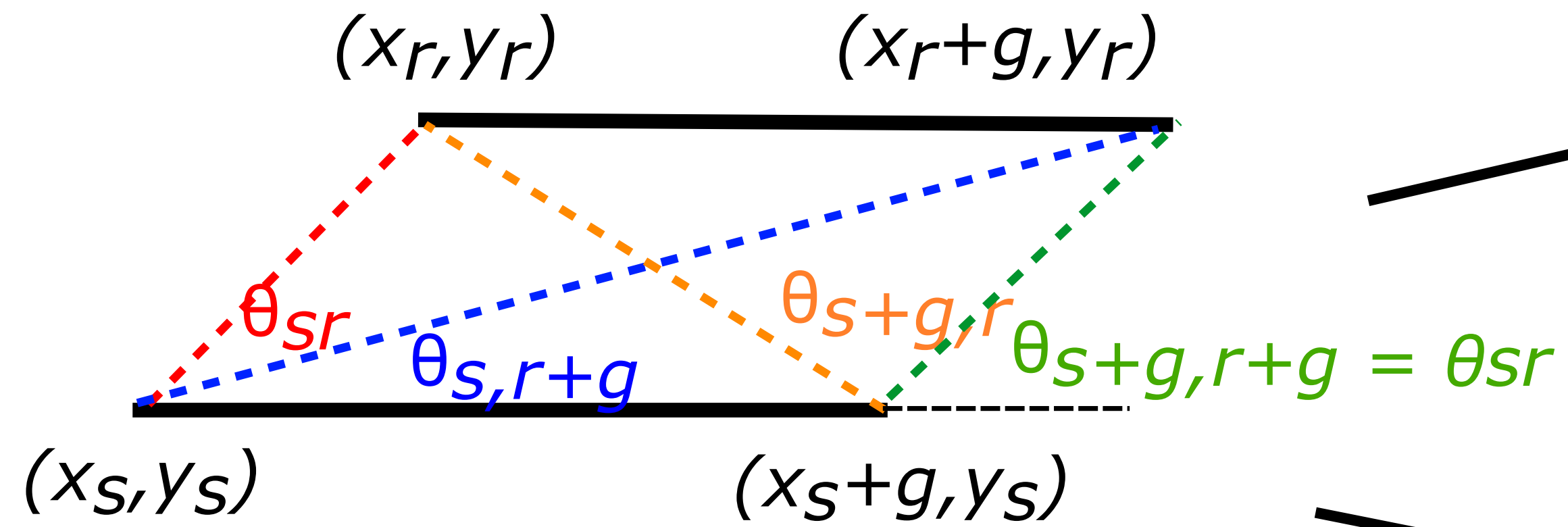
collinear channels yield  
Rayleigh waves



**Love** + **mixed** + **mixed**



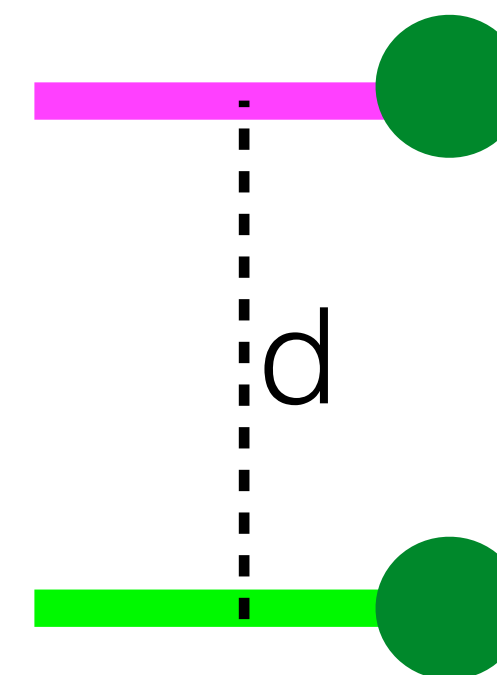
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collinear channels yield  
Rayleigh waves

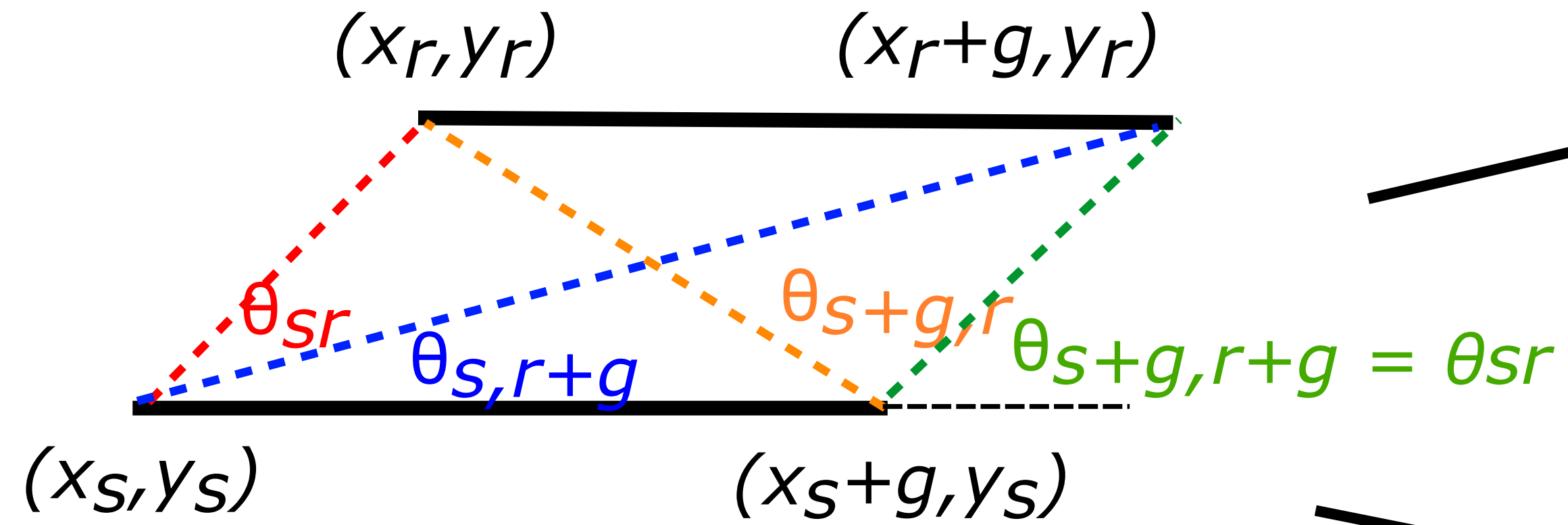


**Love** + **mixed** + **mixed** + **Love**





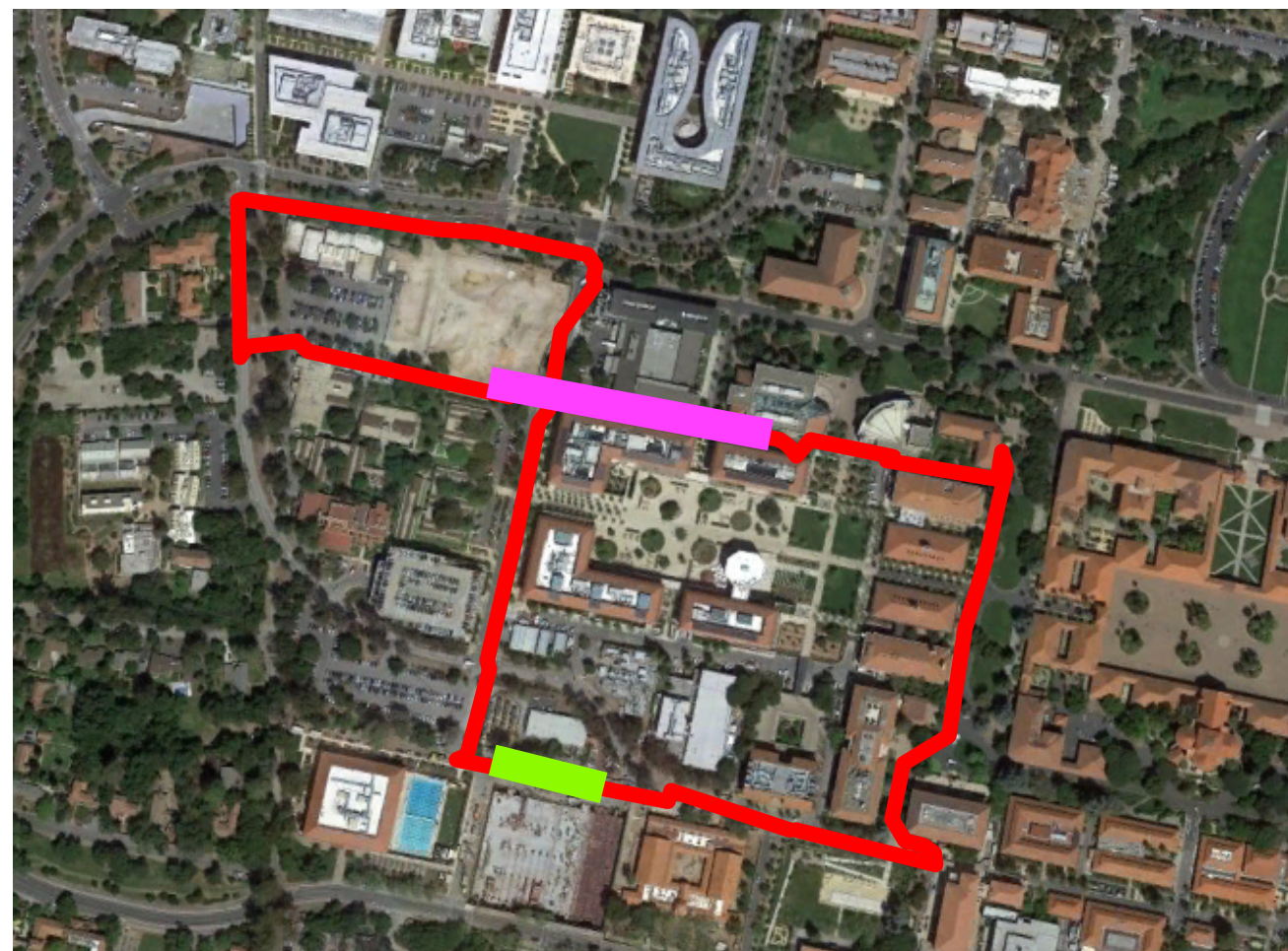
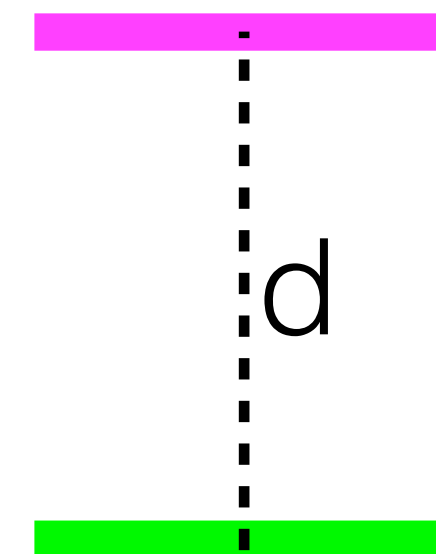
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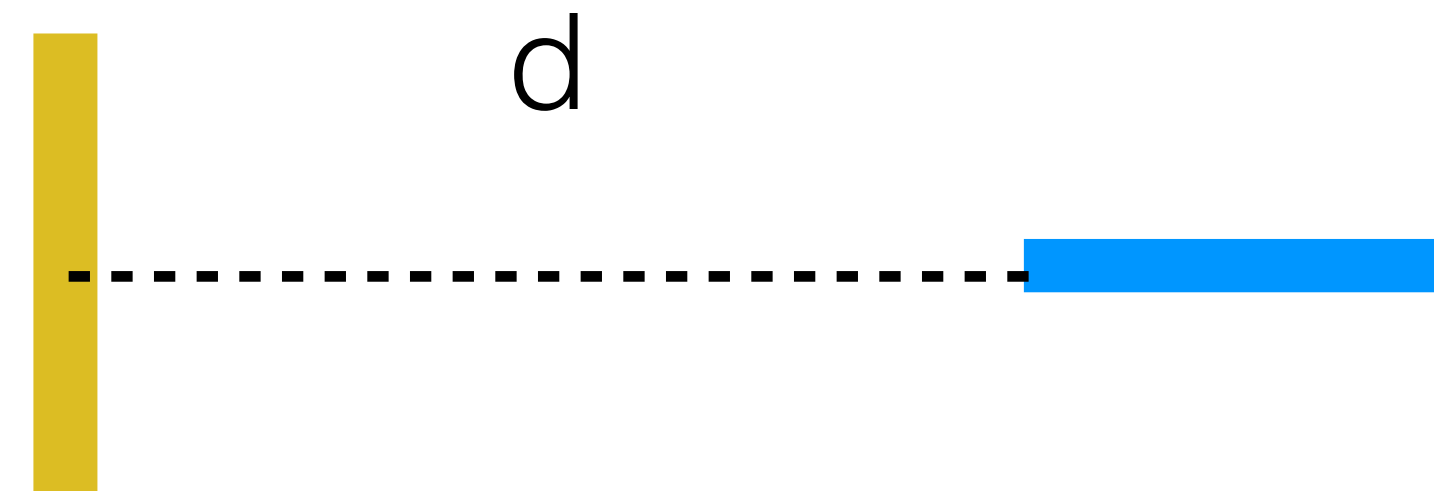
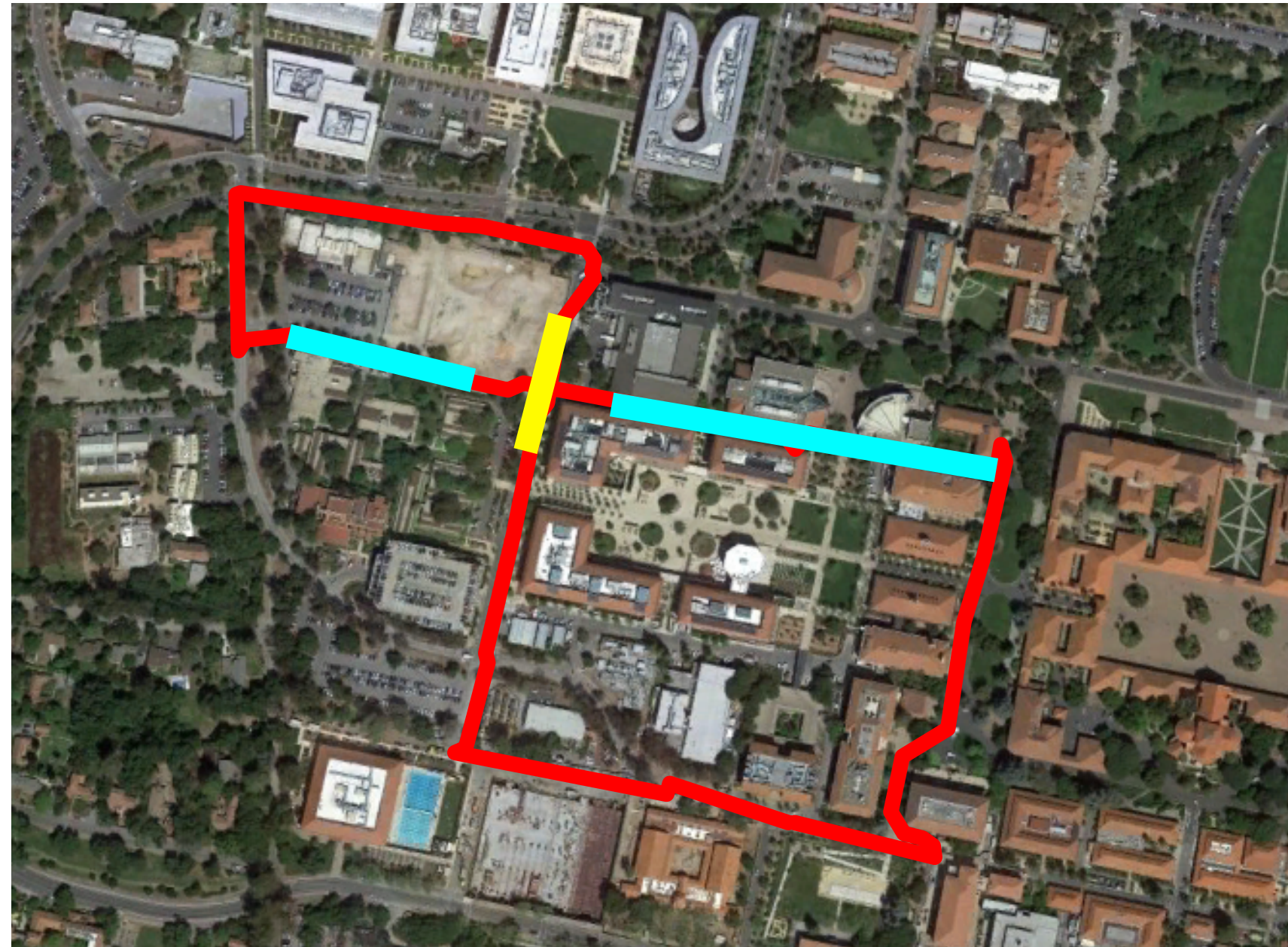
collinear channels yield  
Rayleigh waves



directly across channels yield  
Love waves as  $d$  grows

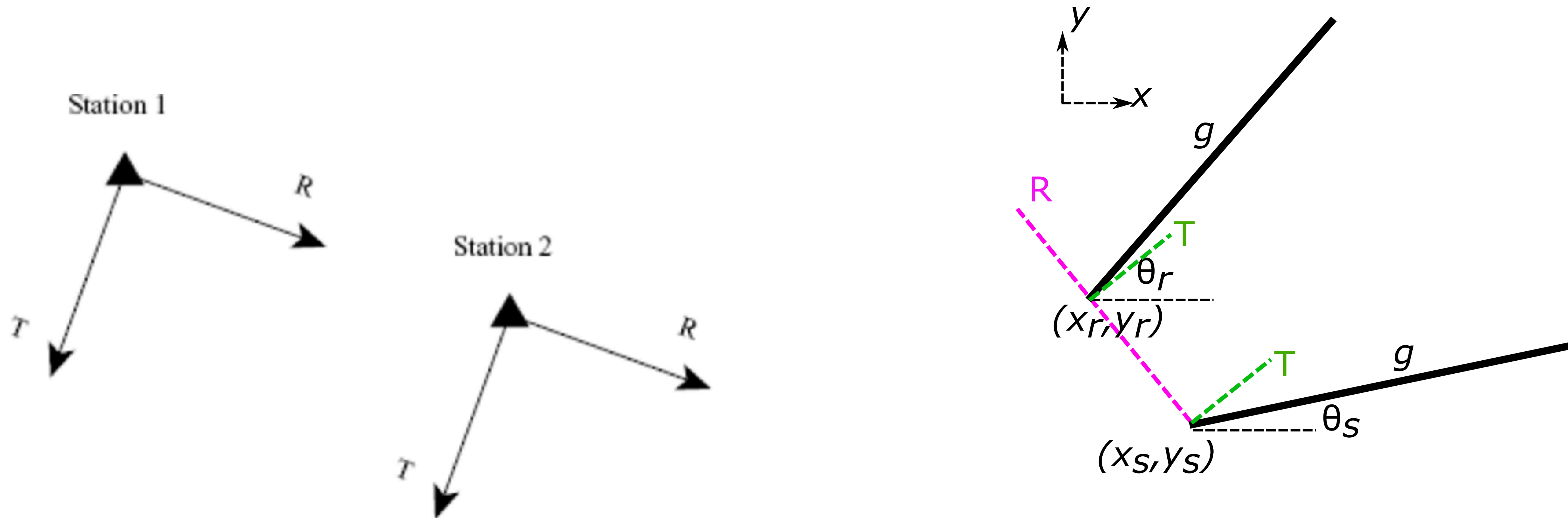


# Orthogonal In-Line Fibers are Another Simple Case

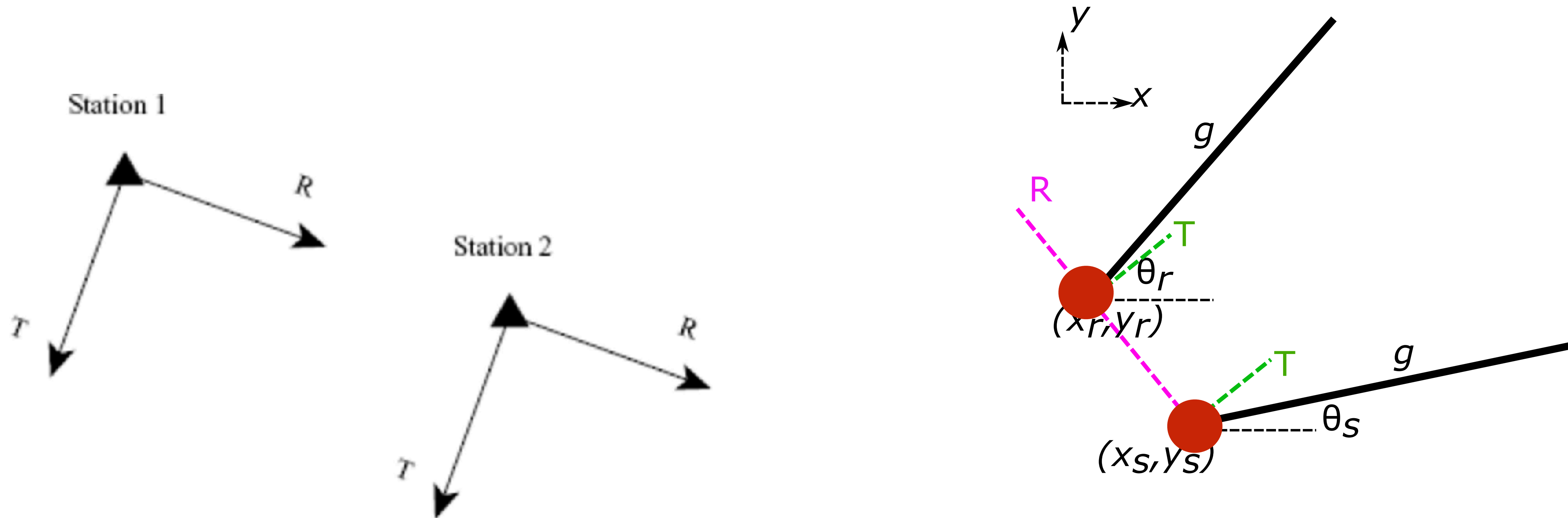


converted Rayleigh/Love waves as  $d$  grows

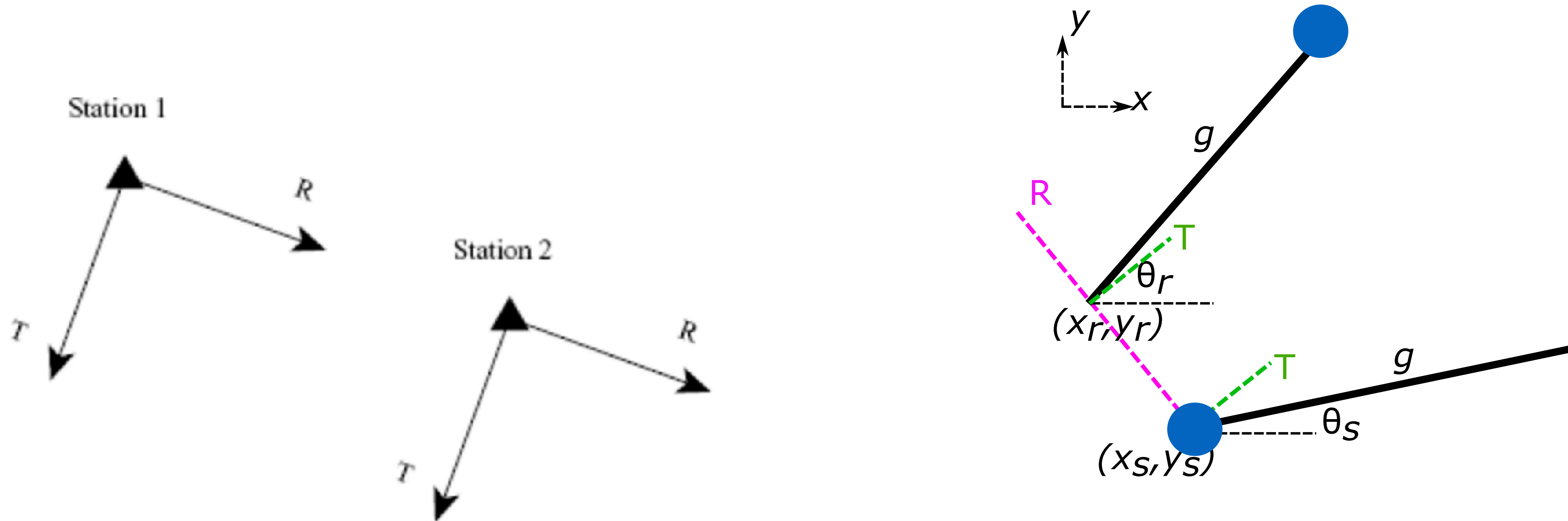
More generally, DAS cross-correlations are linear combinations of cross-correlations of improperly rotated geophones.



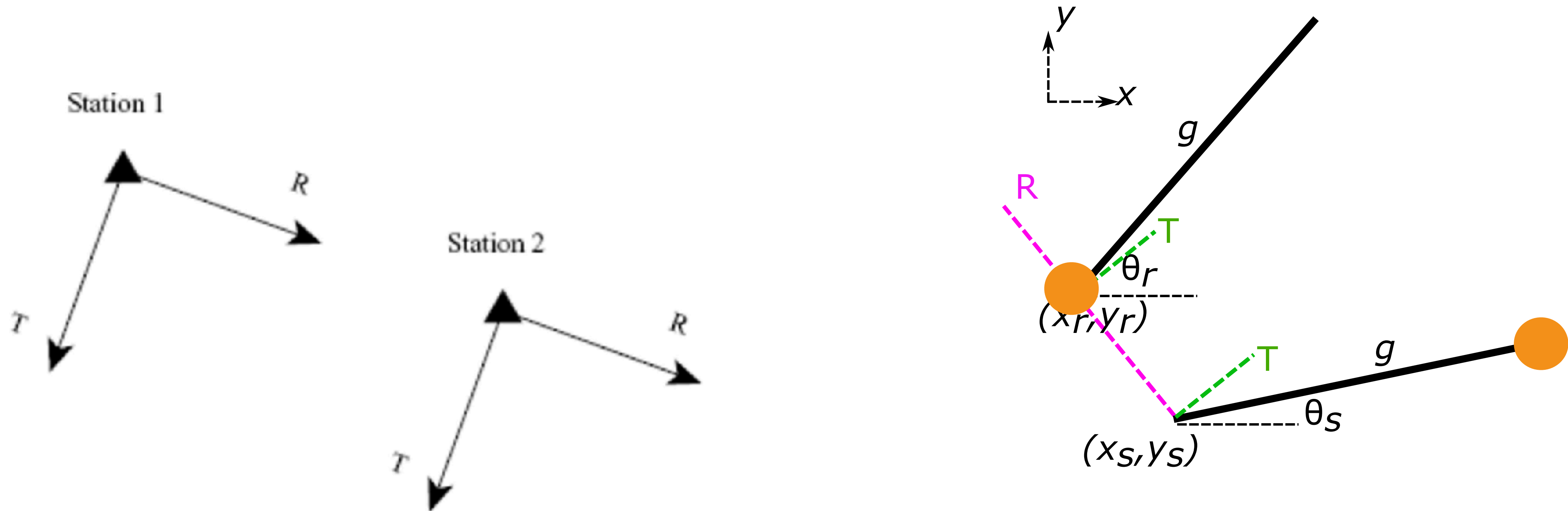
More generally, DAS cross-correlations are linear combinations of cross-correlations of improperly rotated geophones.



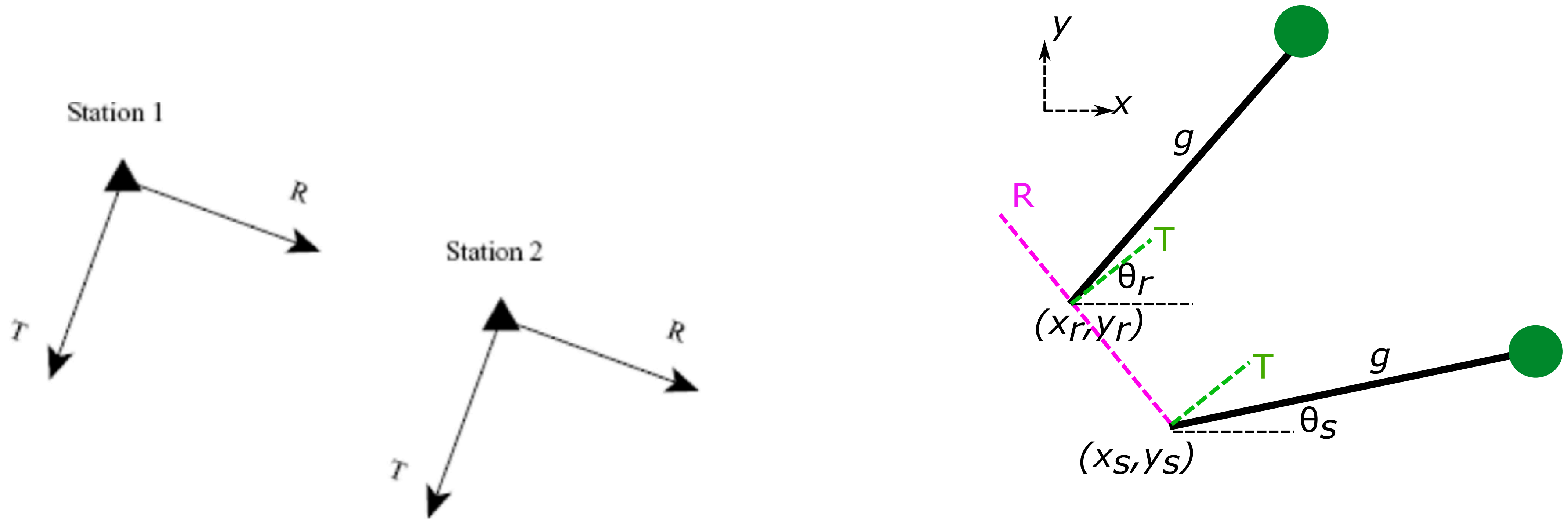
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# Outline

Ambient noise interferometry background

2D DAS interferometry theory

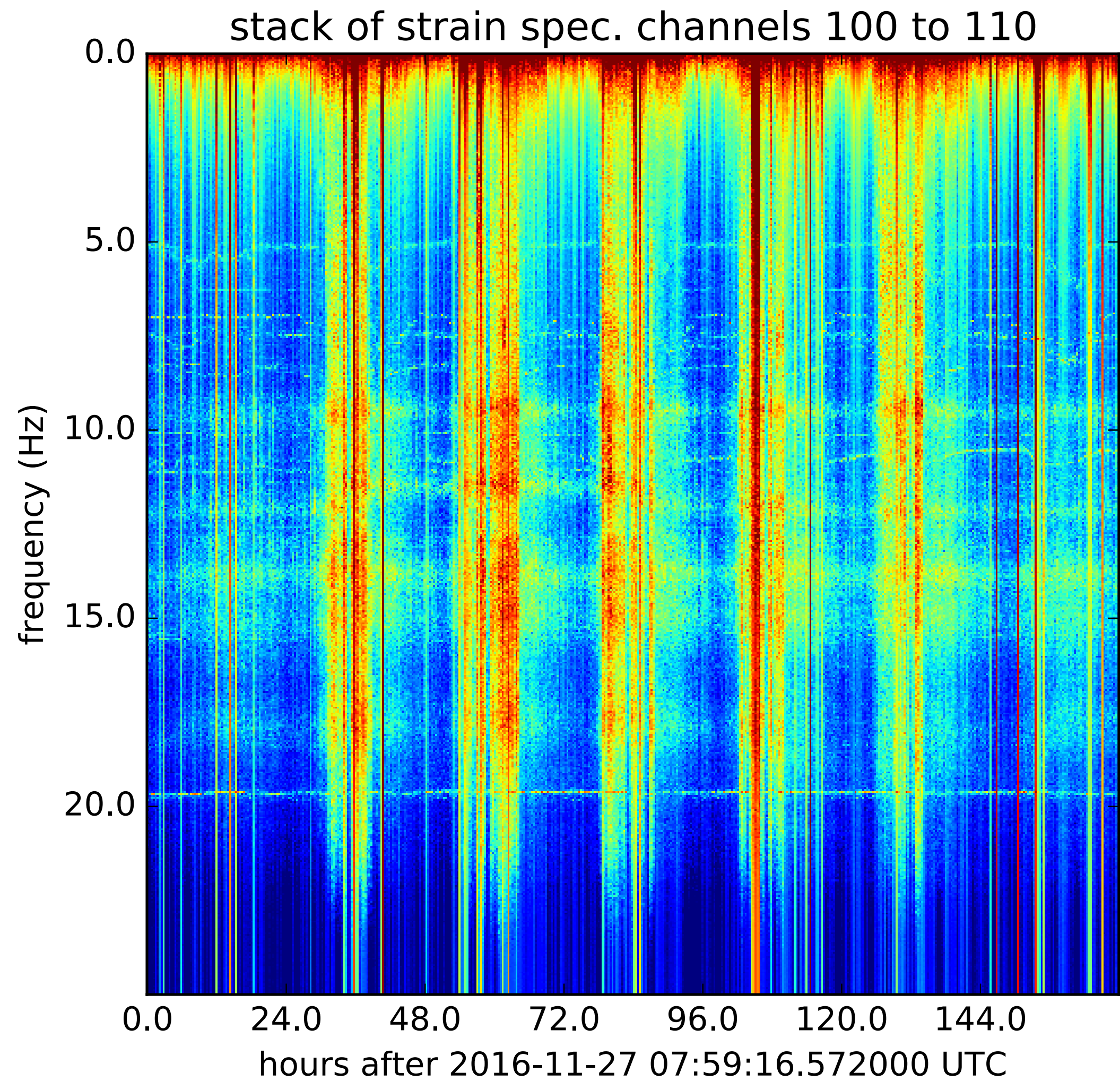
**Practical challenges**

2D Examples

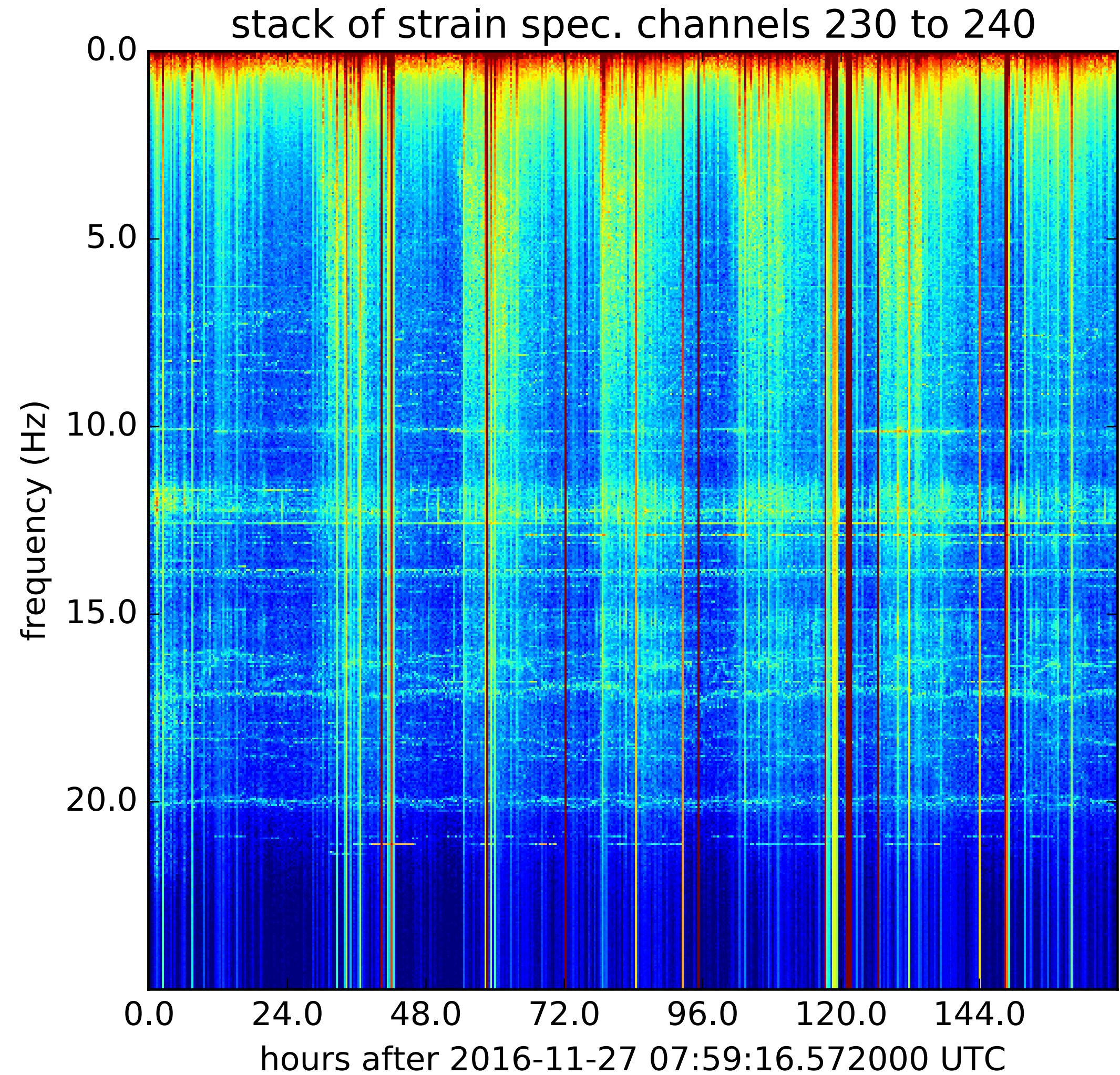
Summary and directions forward



# Traffic, Localized Noise Sources

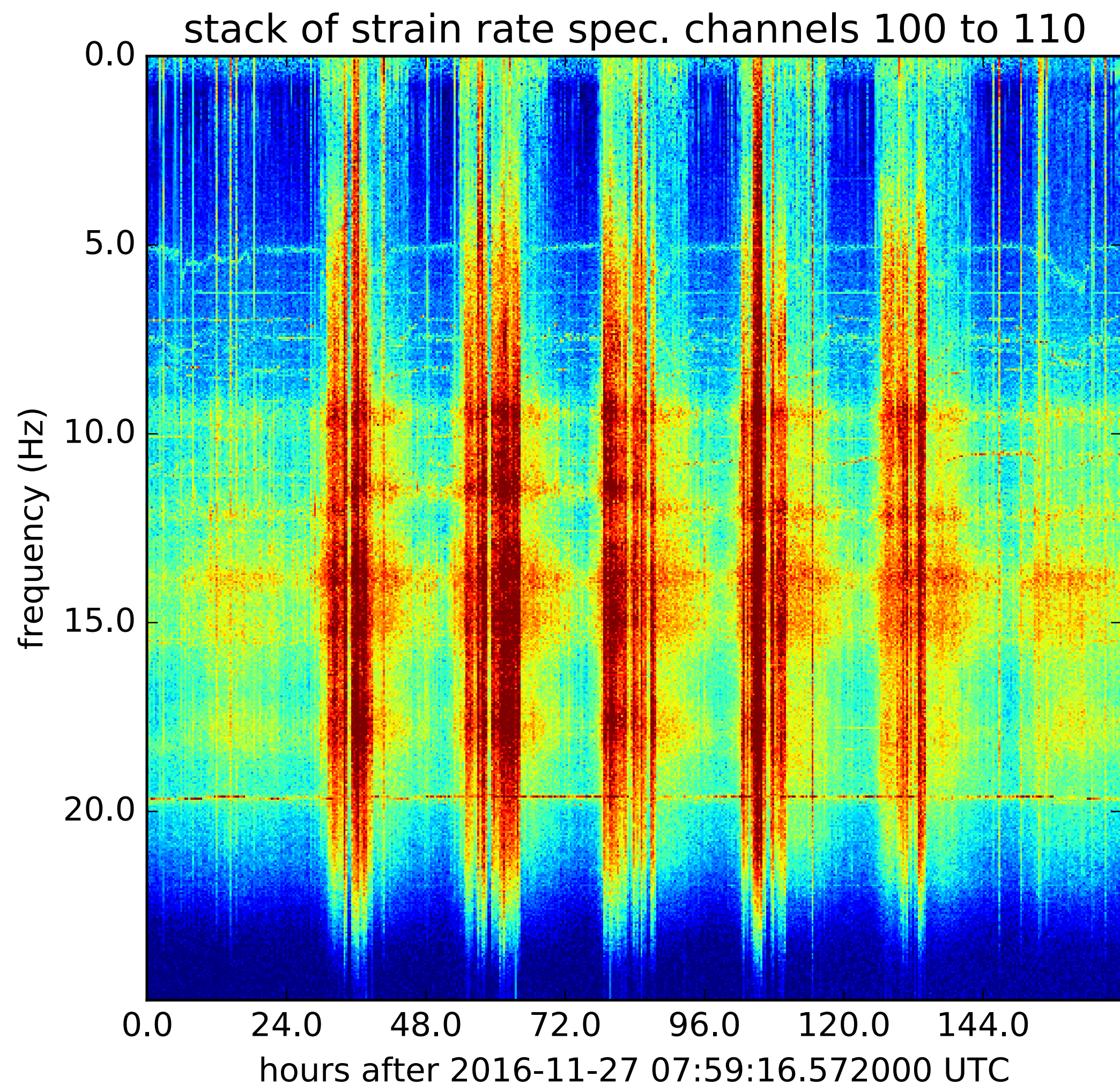


along Campus Dr.

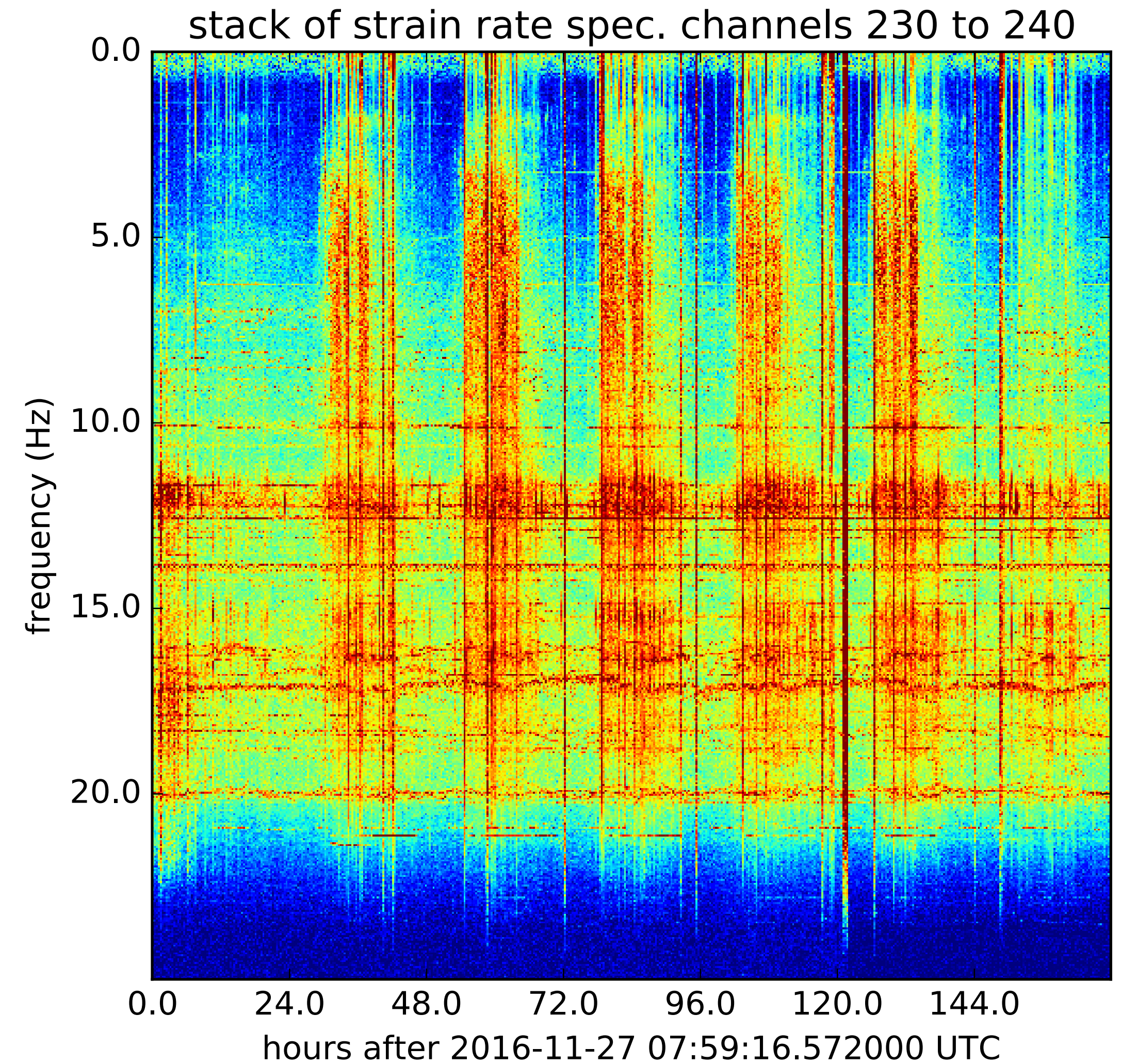


along Via Pueblo

# Traffic, Localized Noise Sources

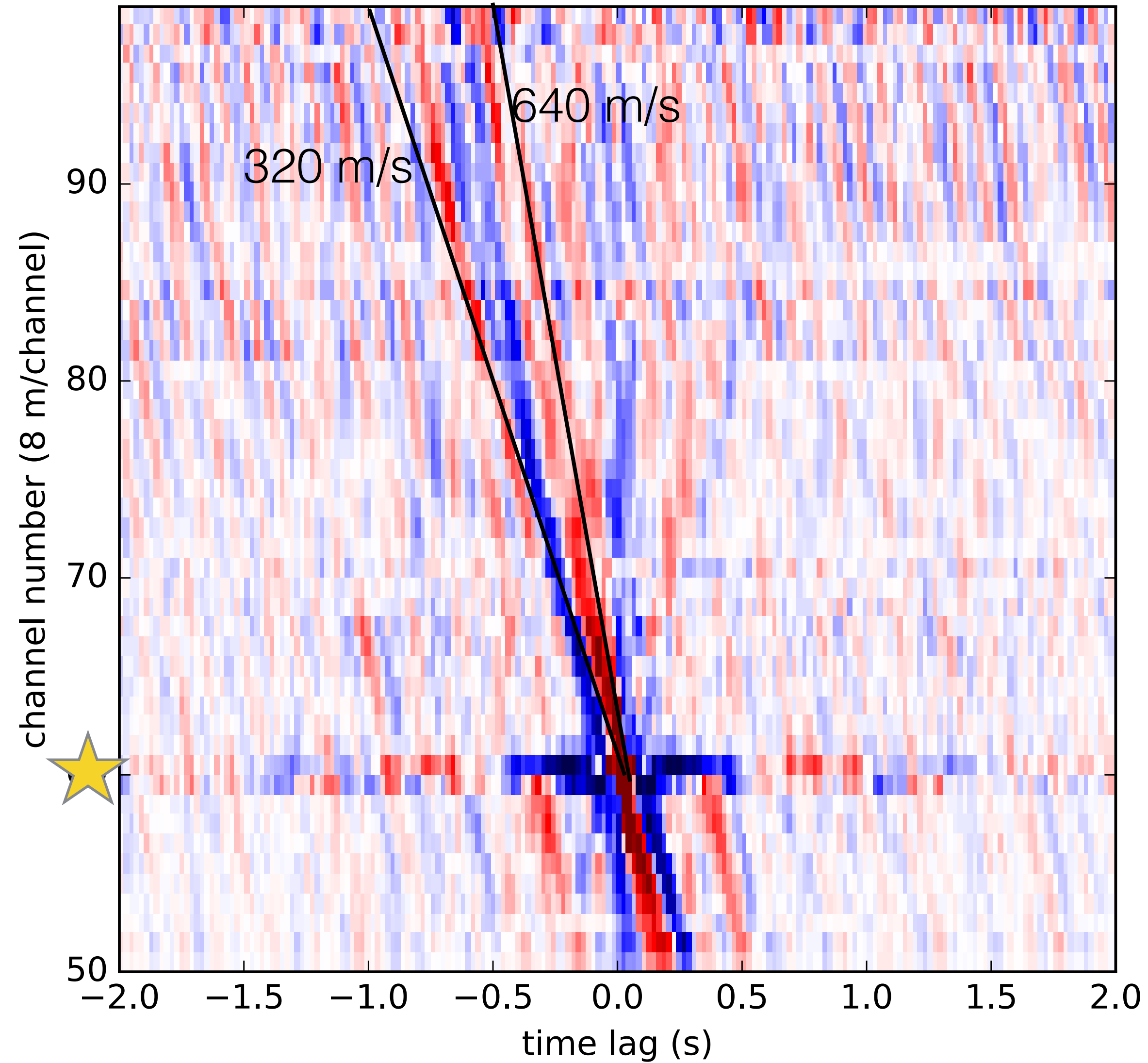
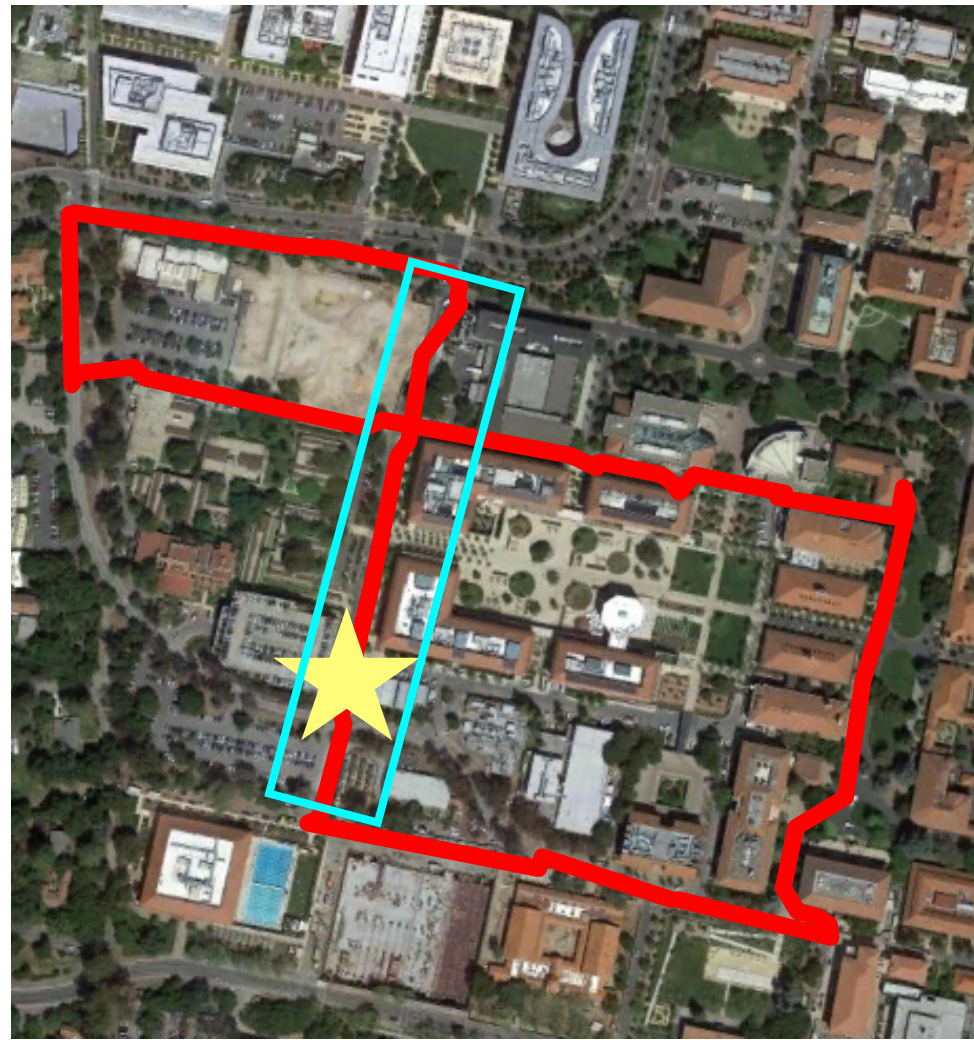


along Campus Dr.



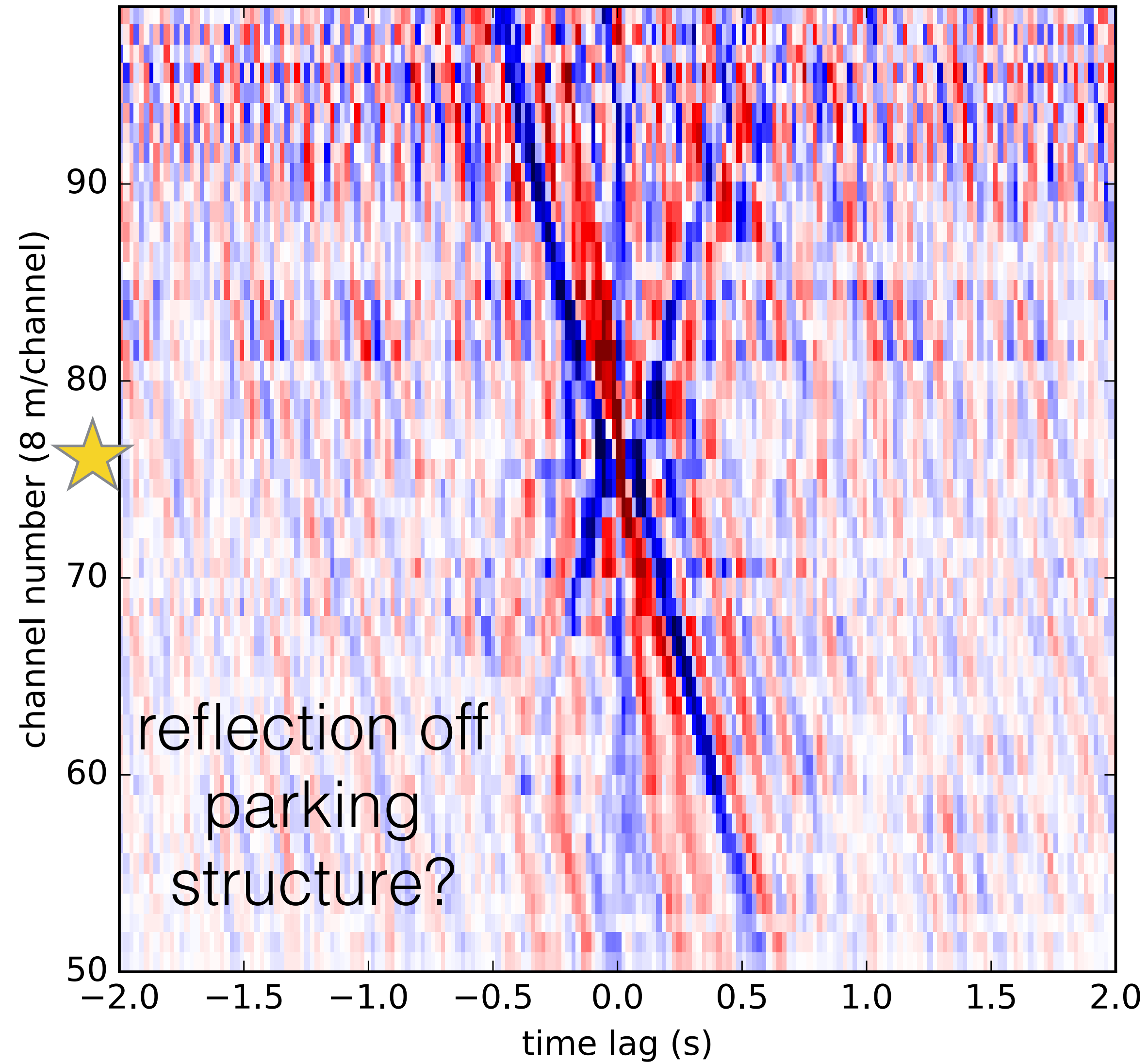
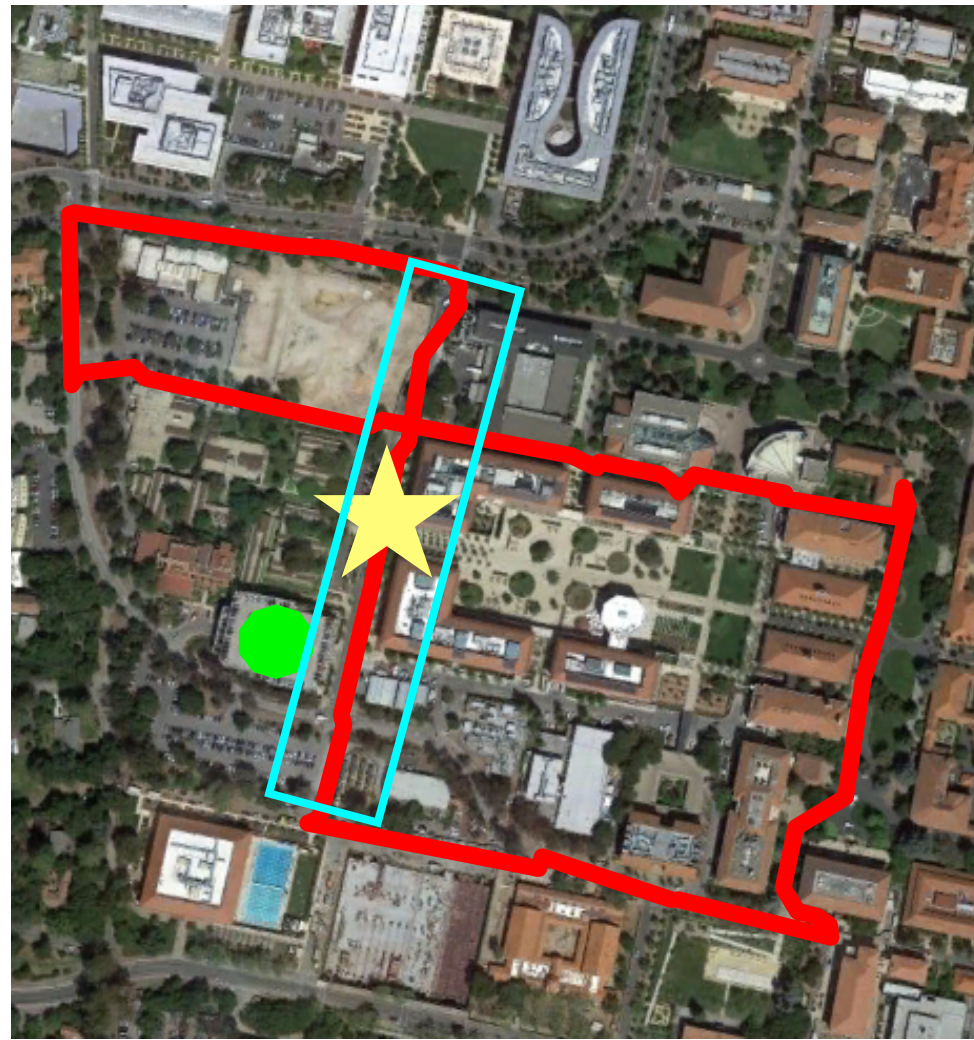
along Via Pueblo

# Virtual Source Channel 60

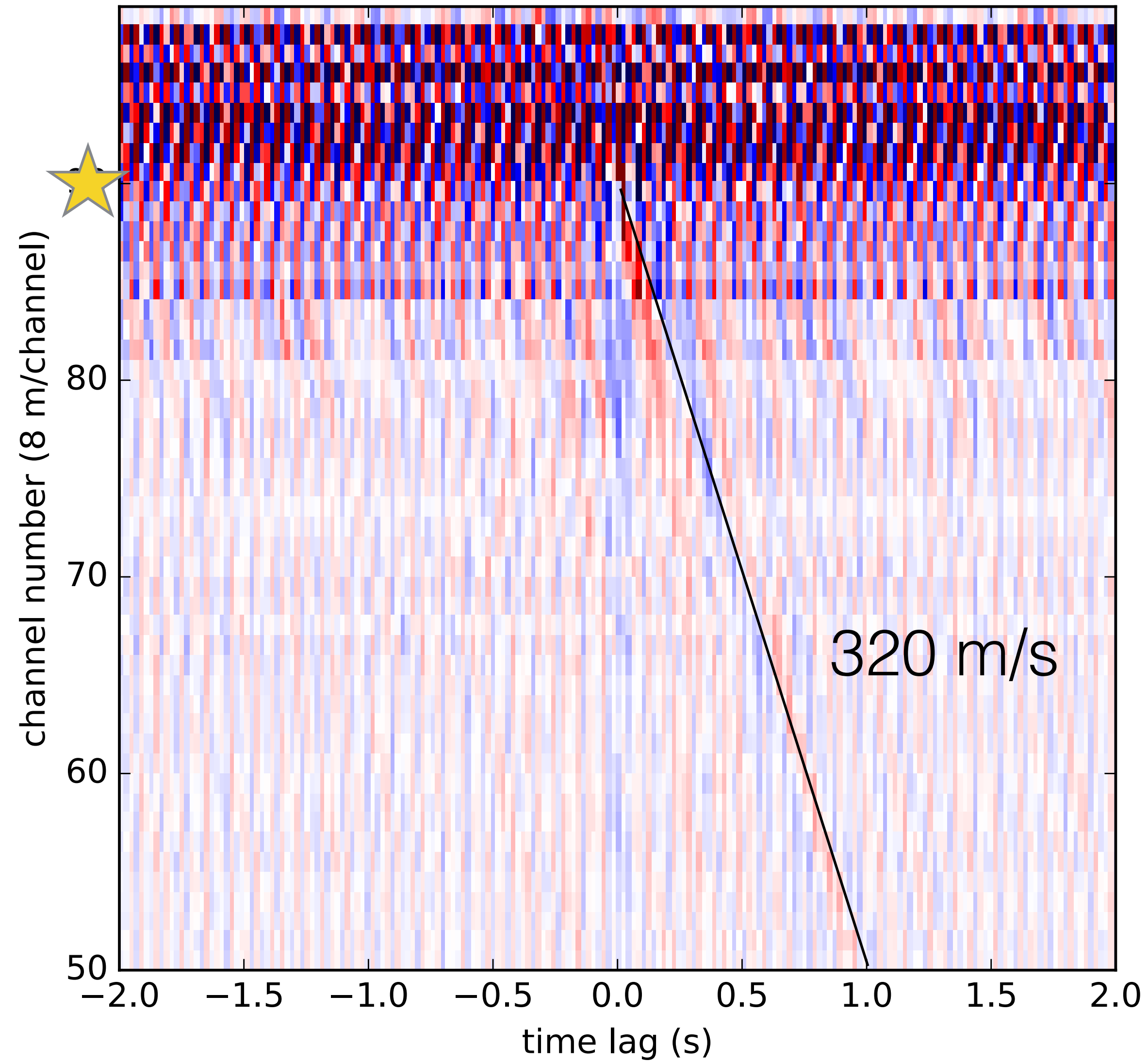
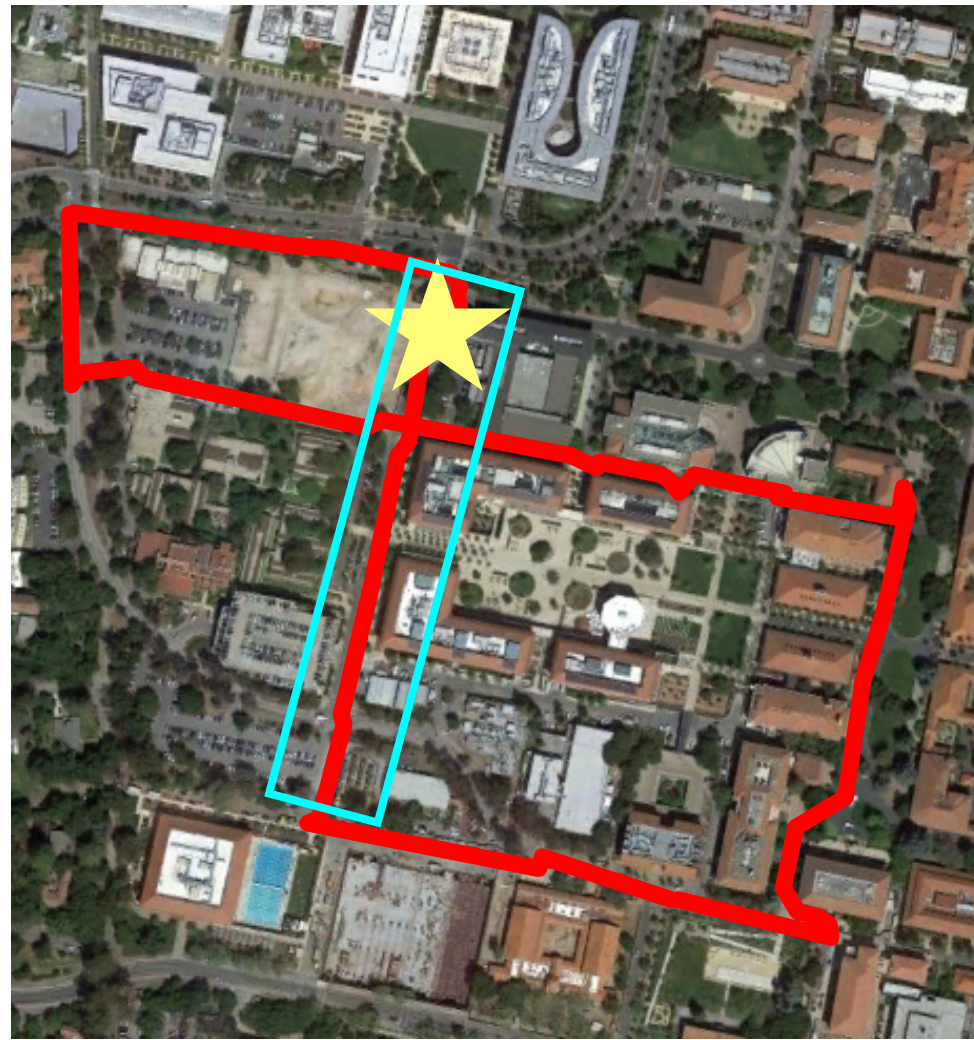


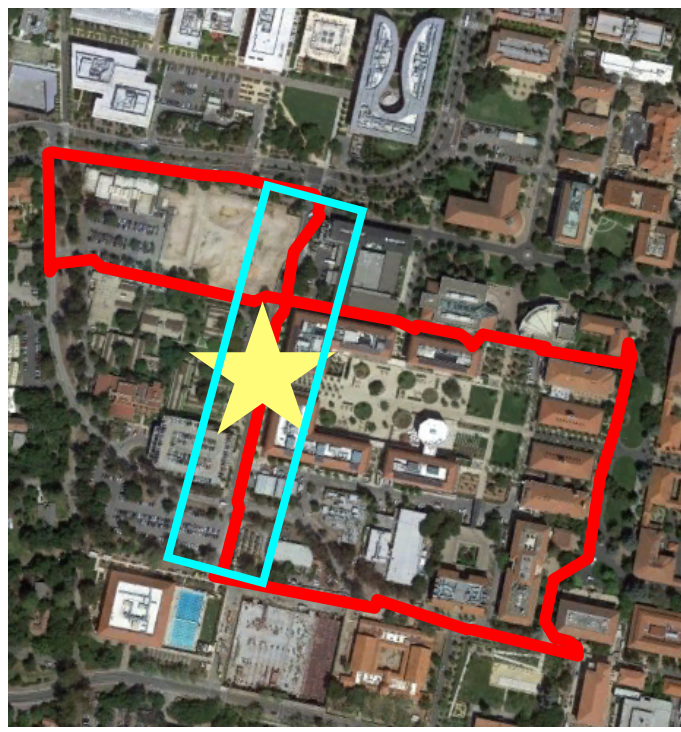
1 to 24 Hz

# Virtual Source Channel 75



# Virtual Source Channel 90

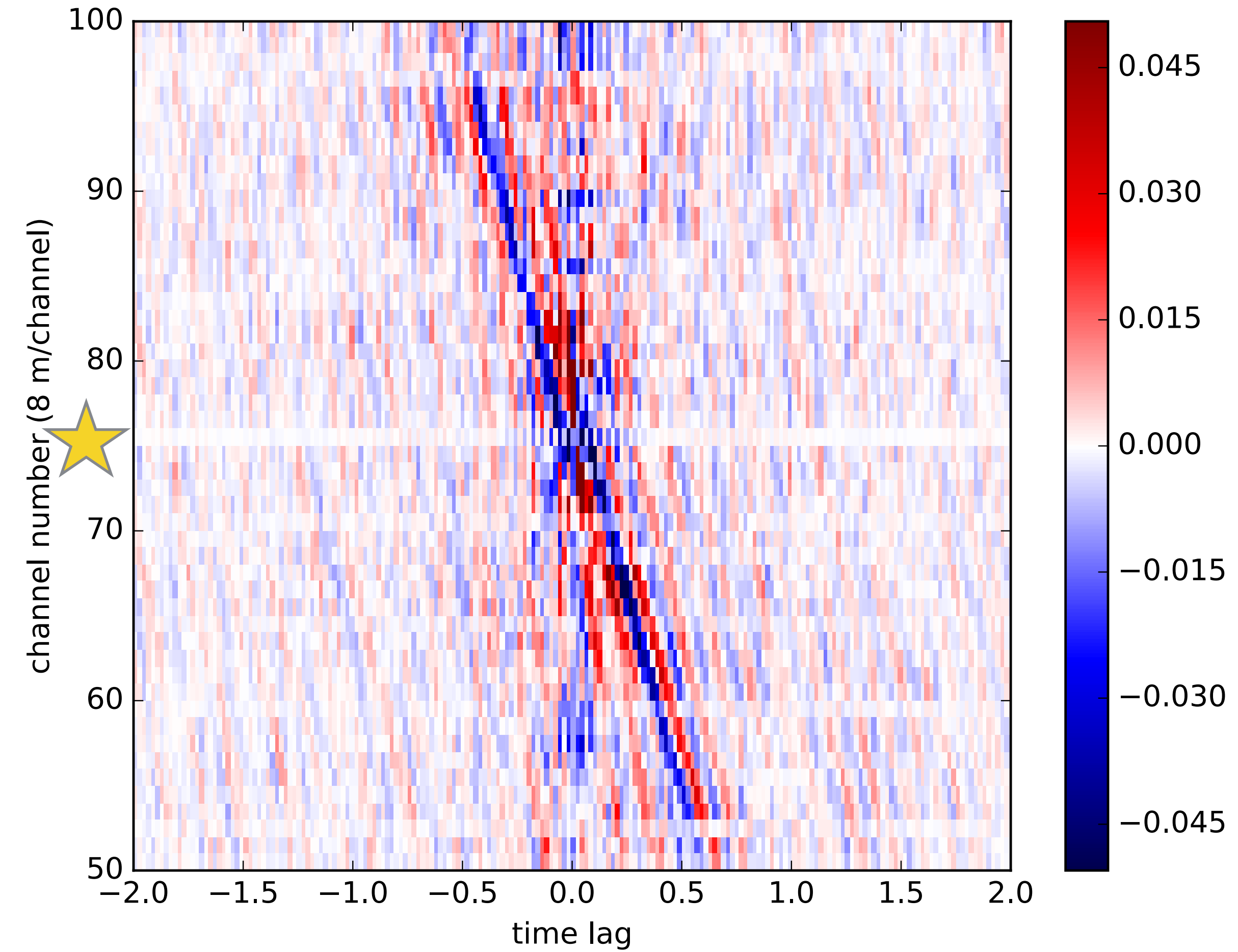
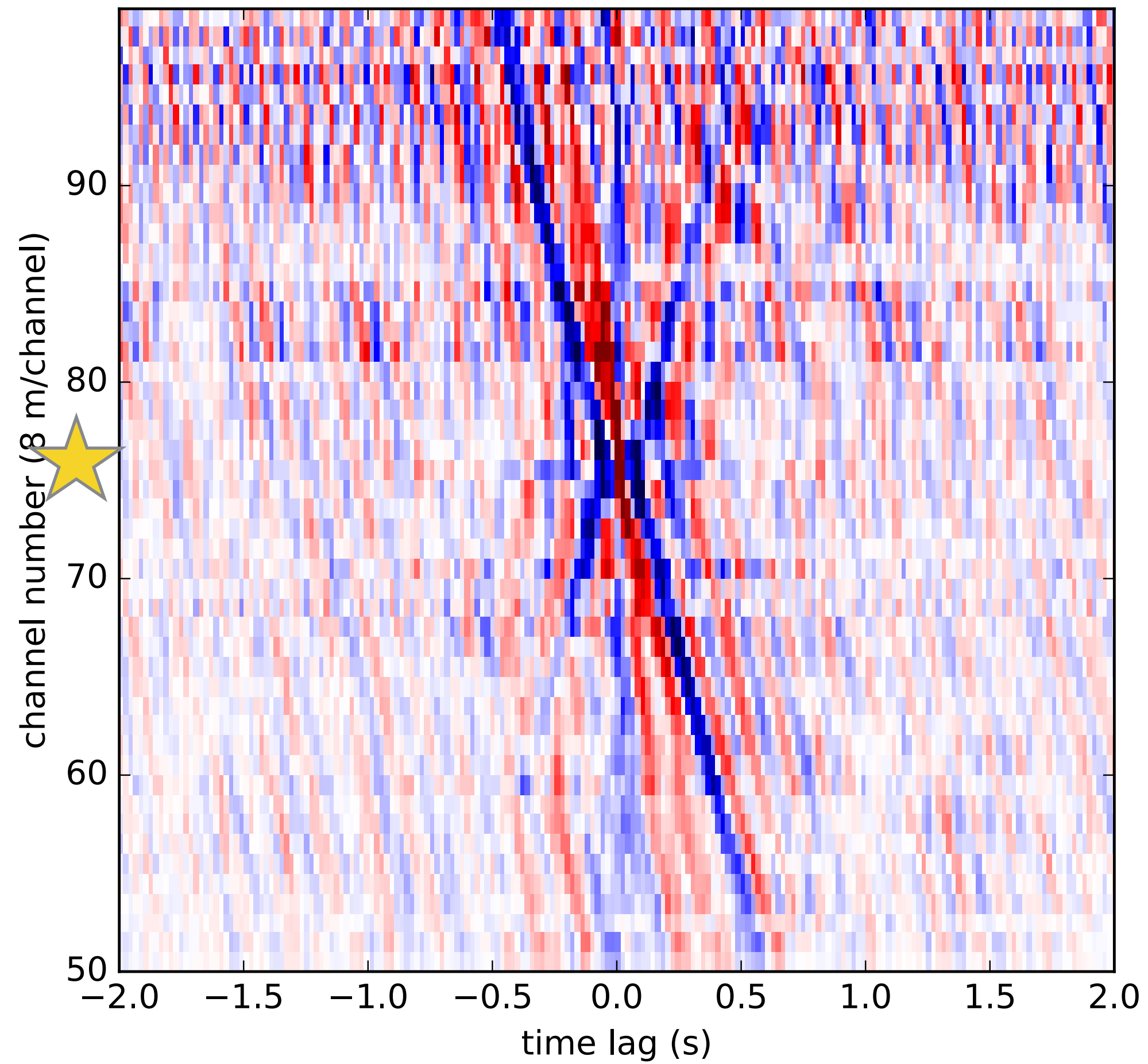




# Cross-Correlation or Coherence?

cross-correlation

cross-coherence



# Outline

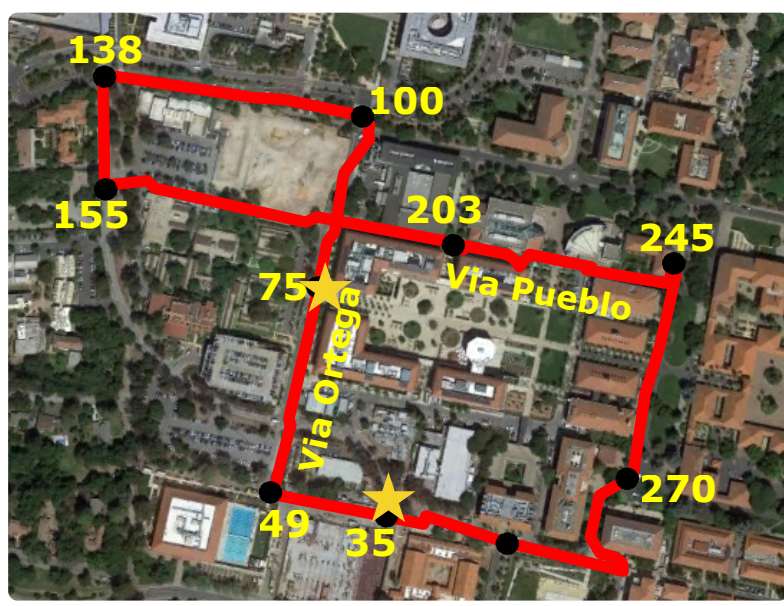
Ambient noise interferometry background

2D DAS interferometry theory

Practical challenges

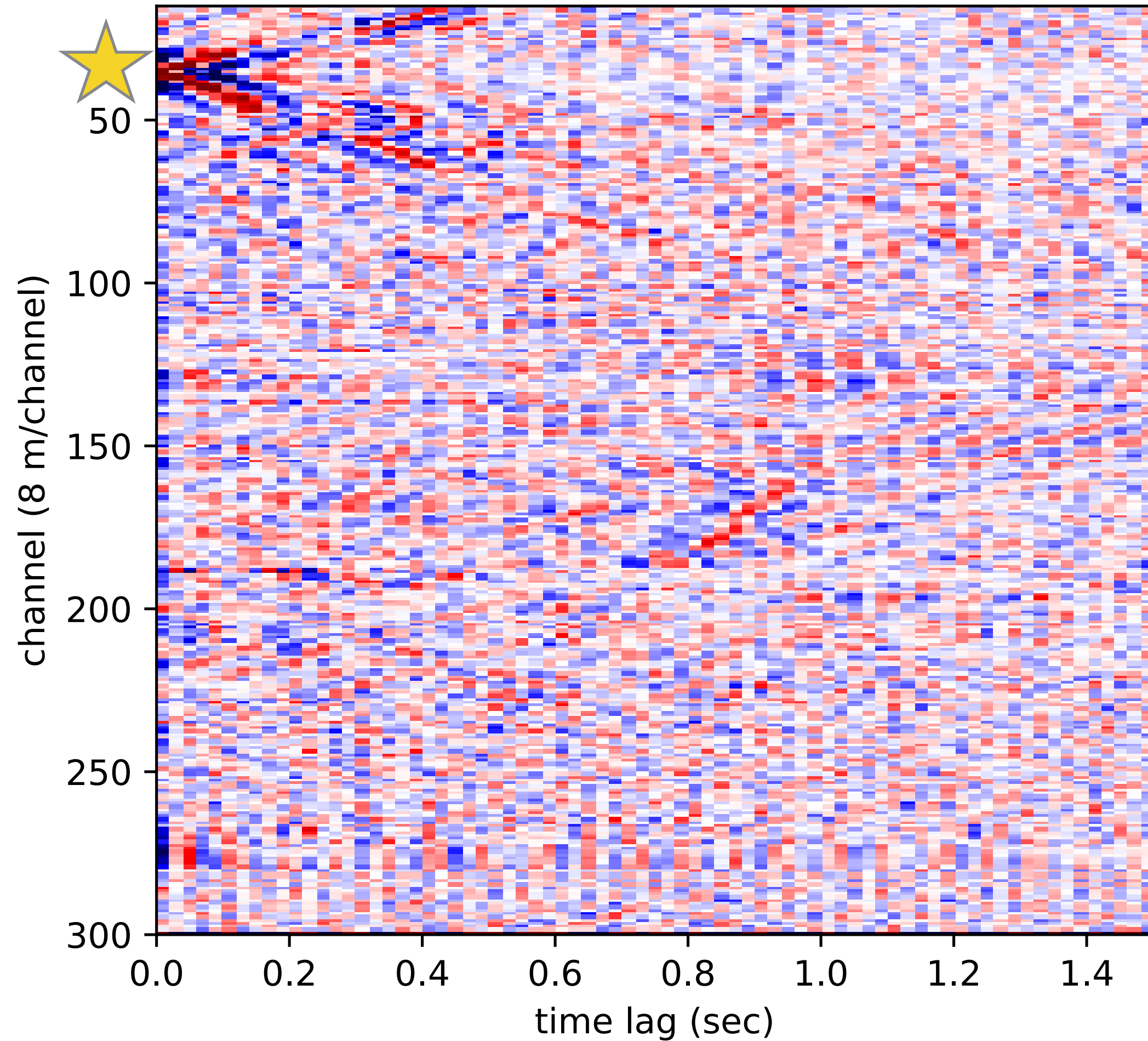
**2D Examples**

Summary and directions forward

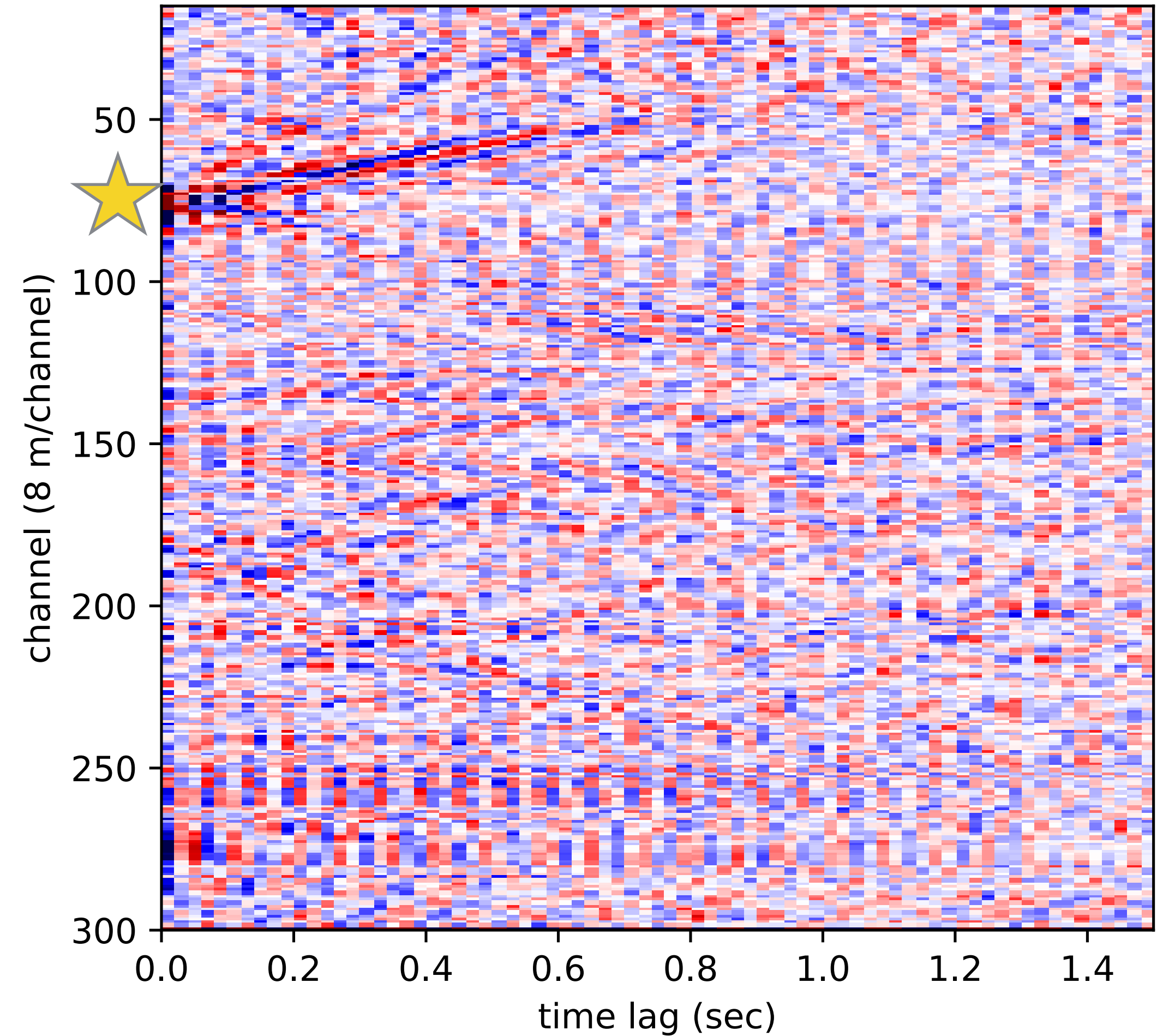


# 1-bit cross-correlation, 1 day

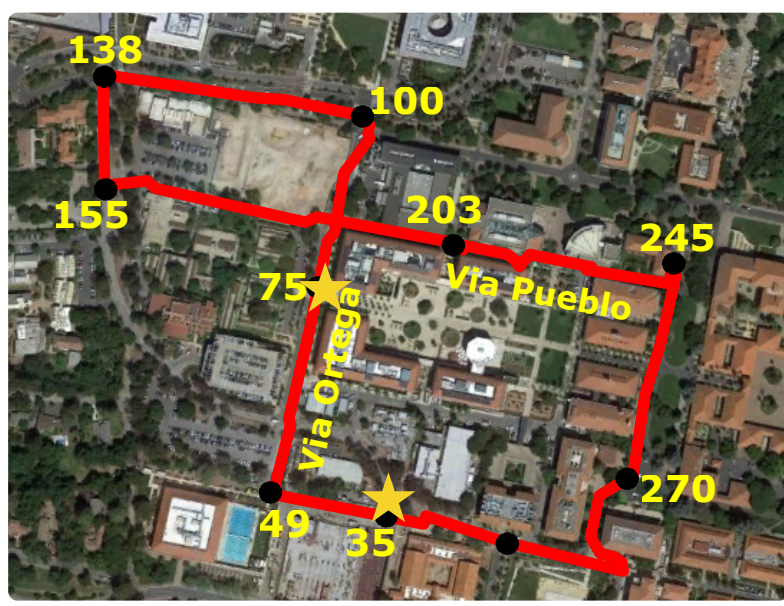
one bit cross-correlation, virtual source 35



one bit cross-correlation, virtual source 75

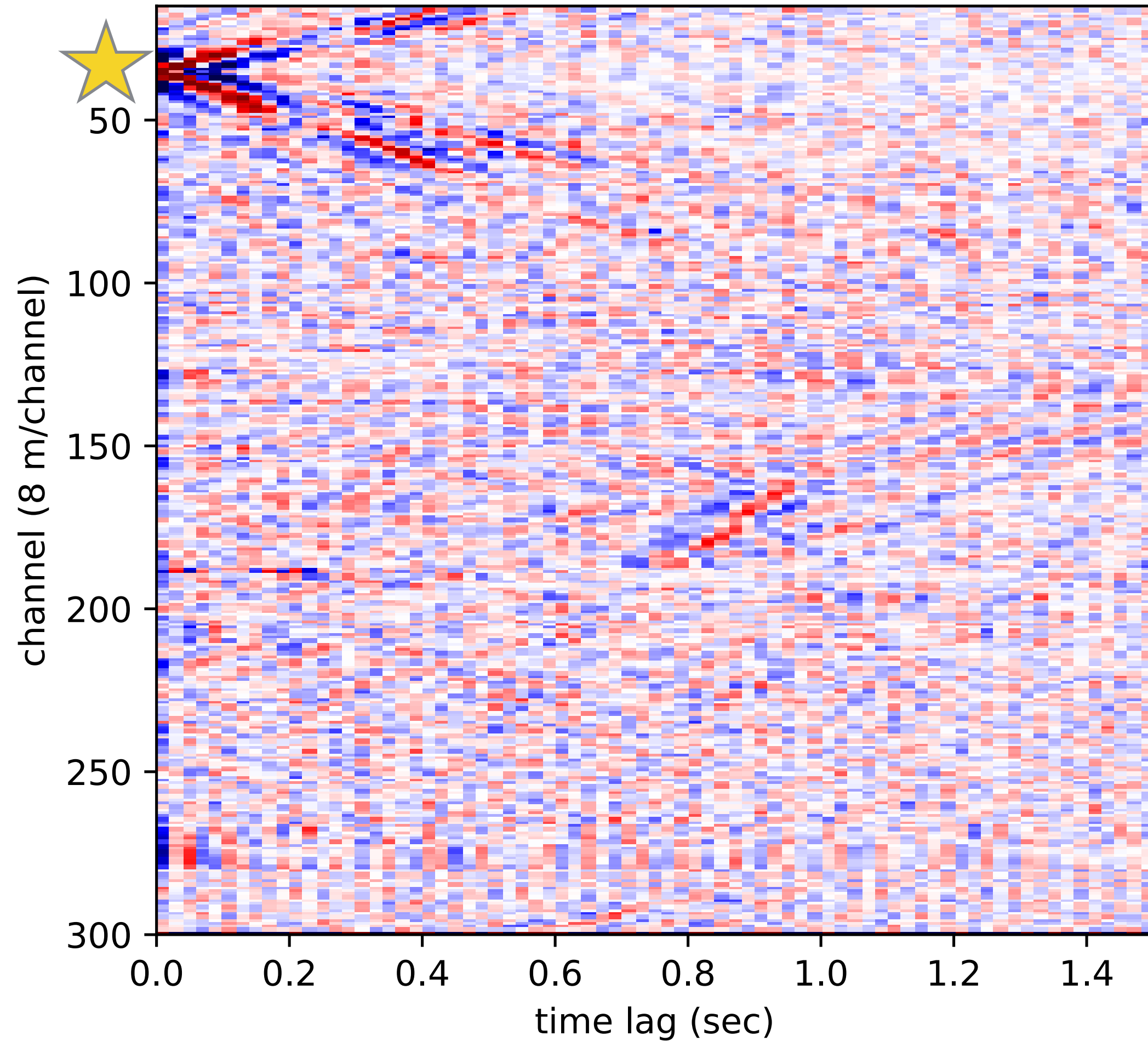




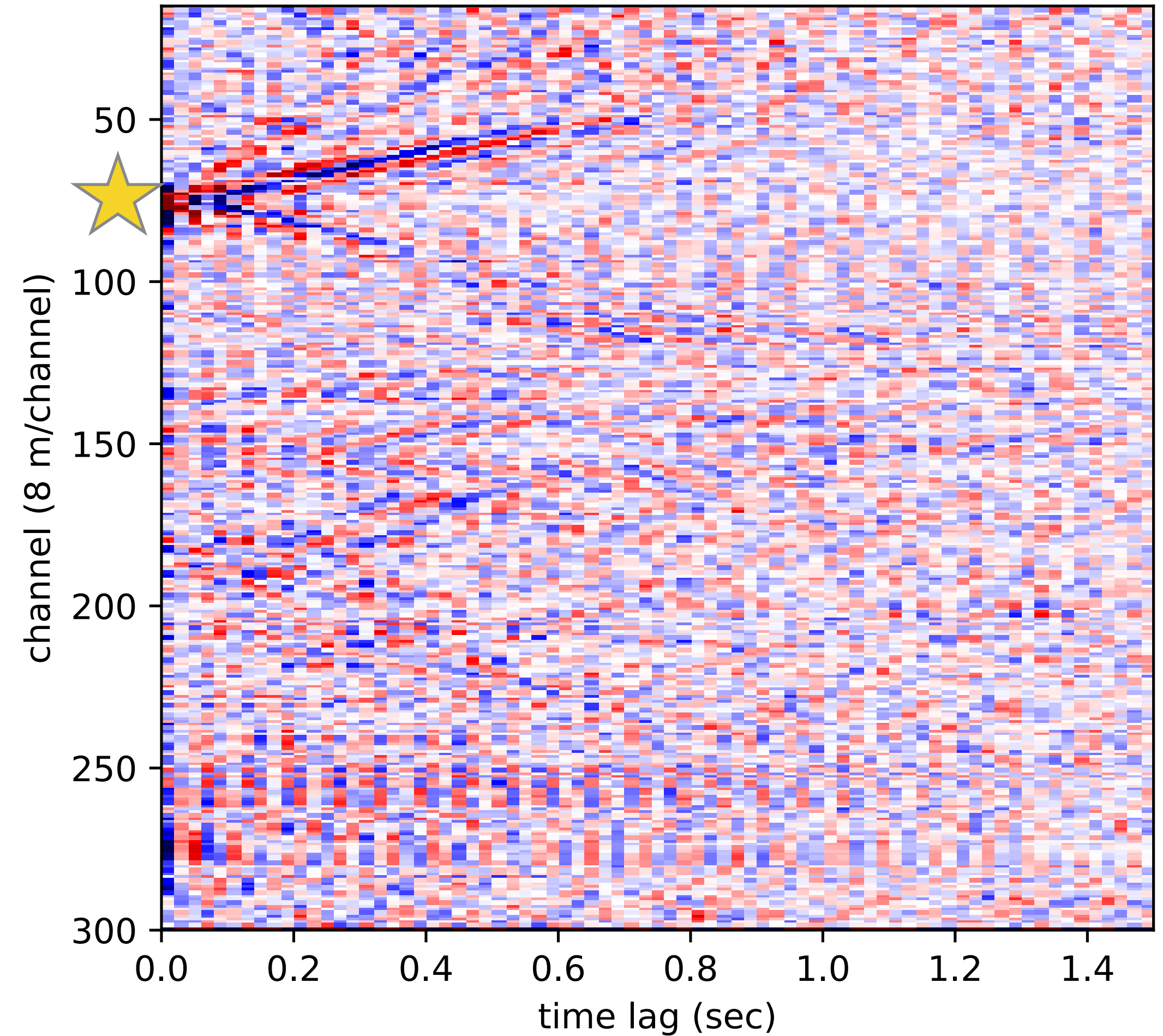


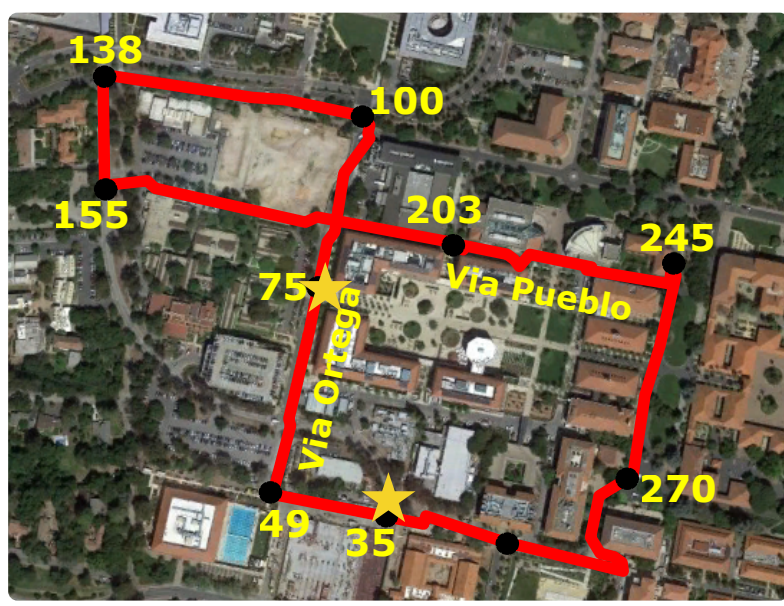
# 1-bit cross-correlation, 3 day

one bit cross-correlation, virtual source 35



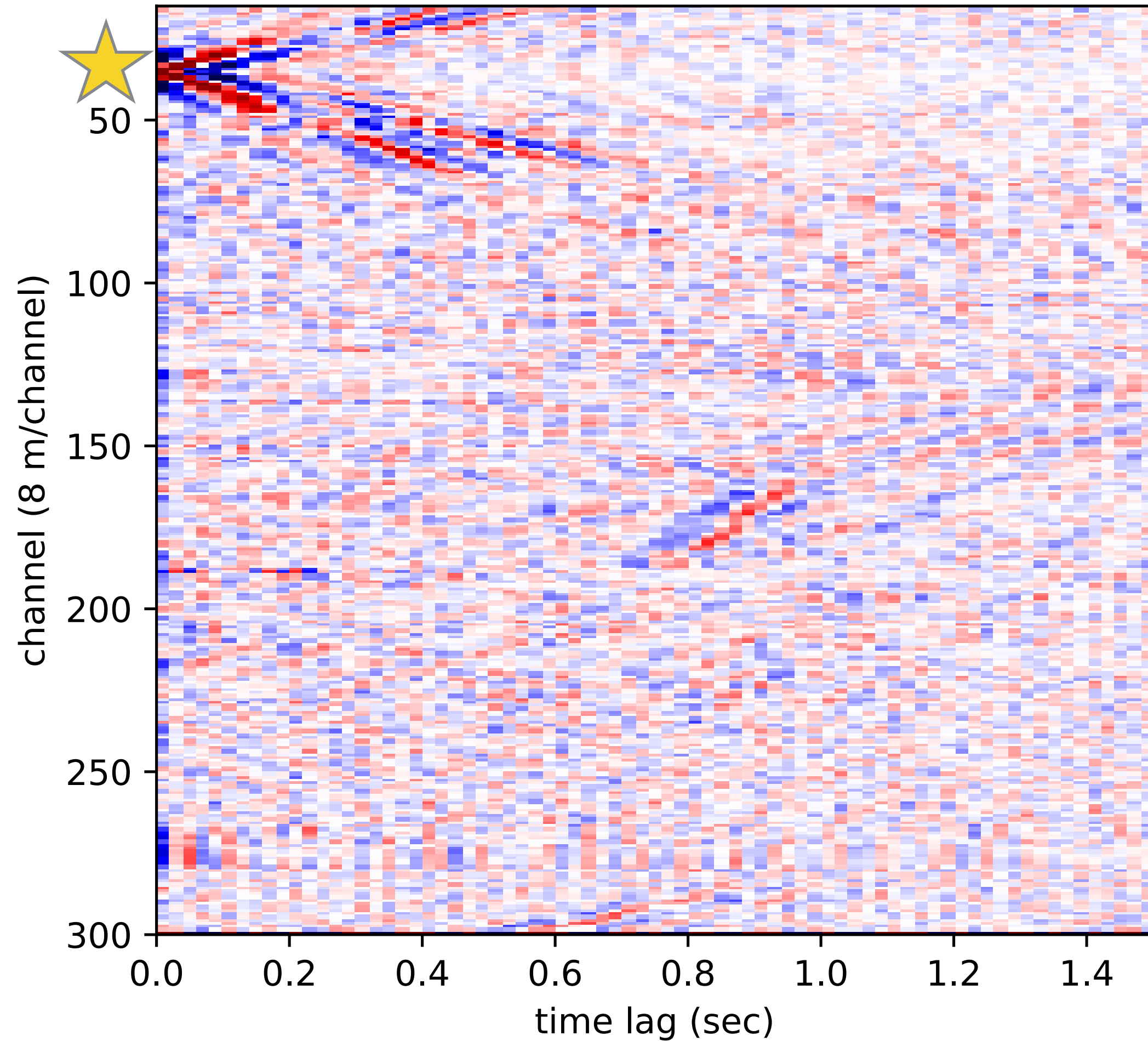
one bit cross-correlation, virtual source 75



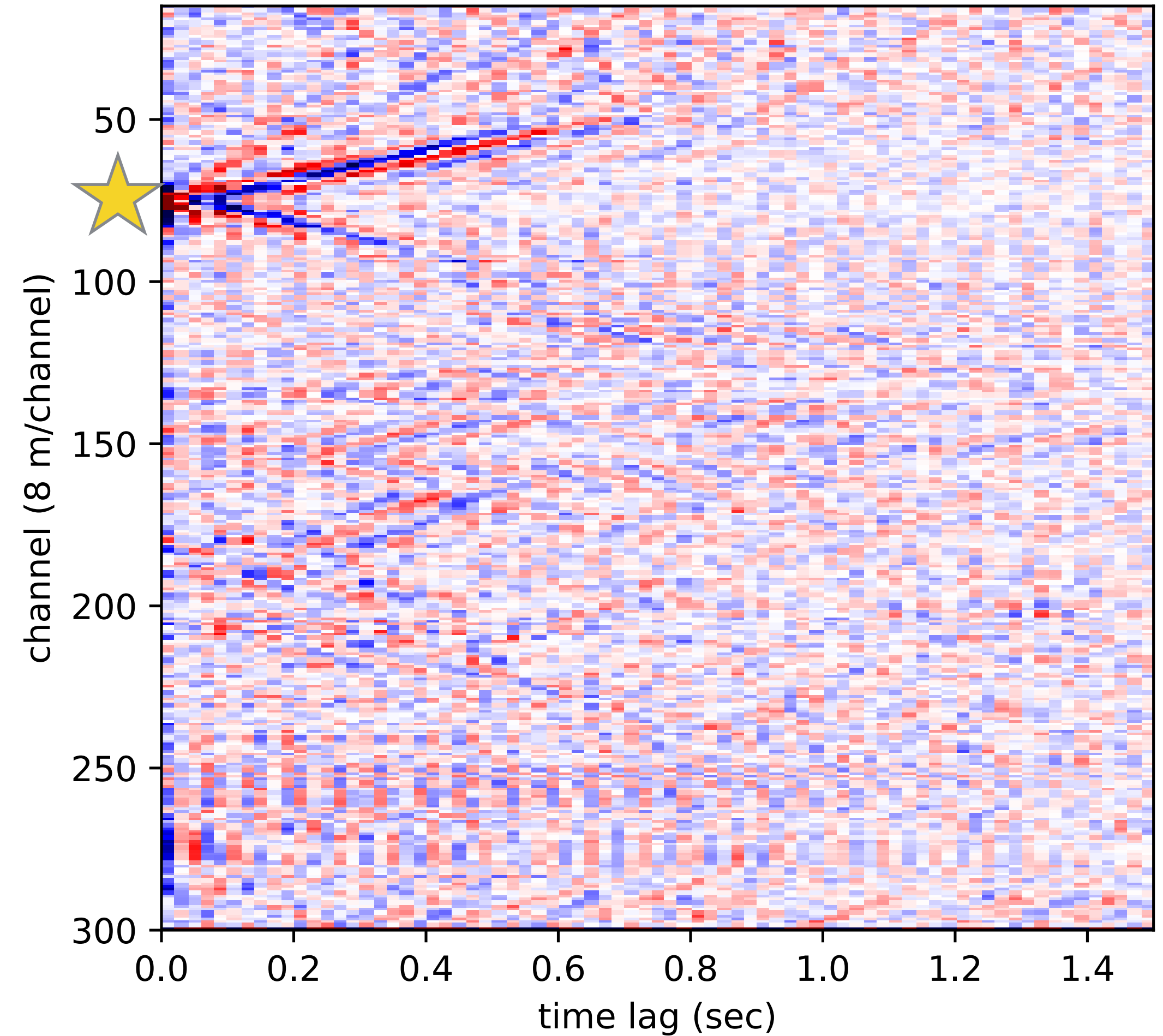


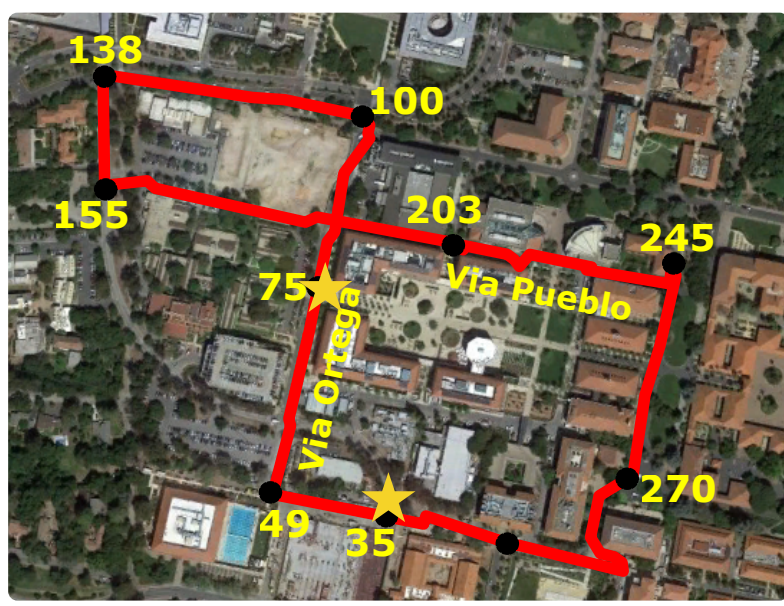
# 1-bit cross-correlation, 5 day

one bit cross-correlation, virtual source 35



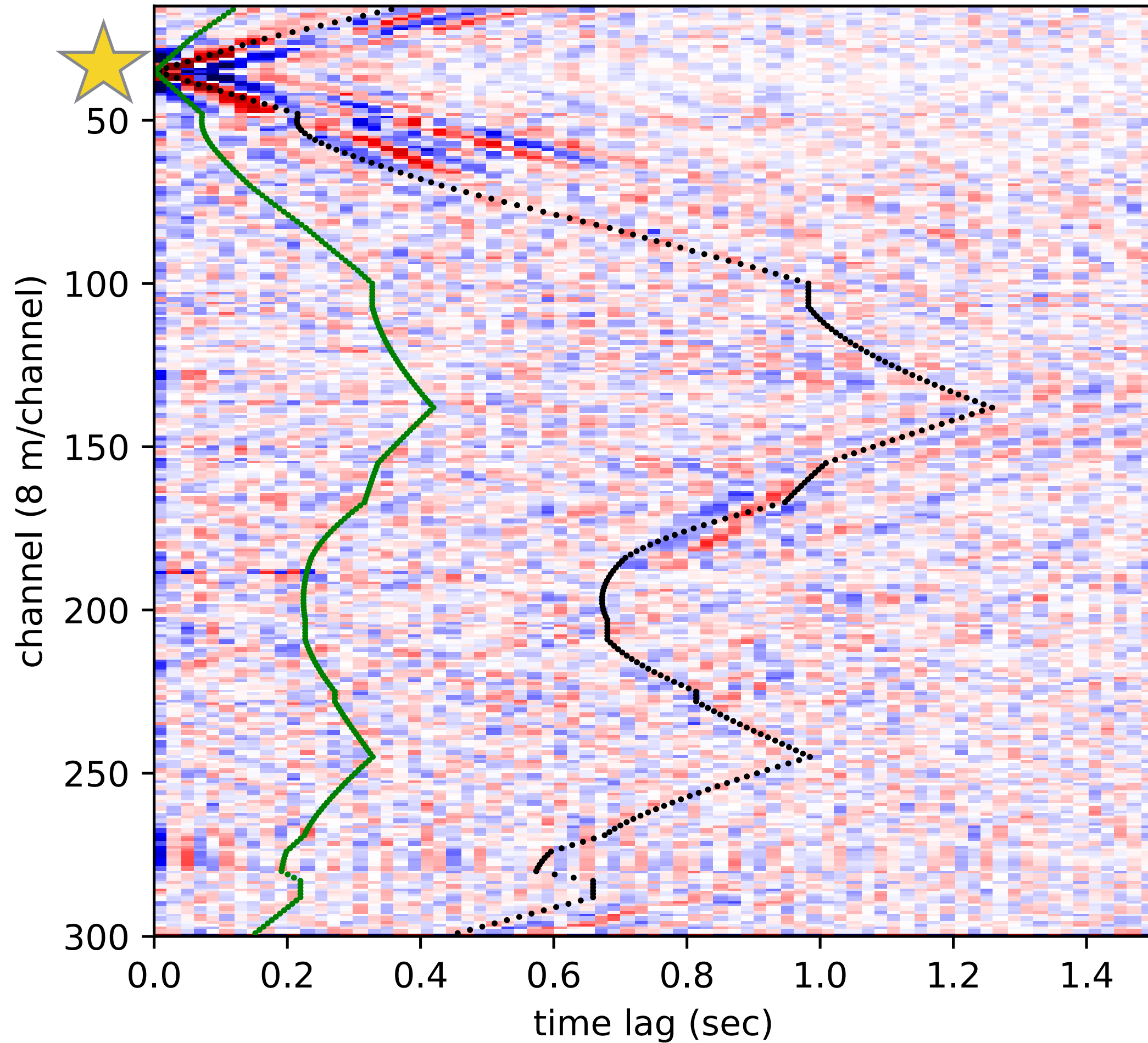
one bit cross-correlation, virtual source 75





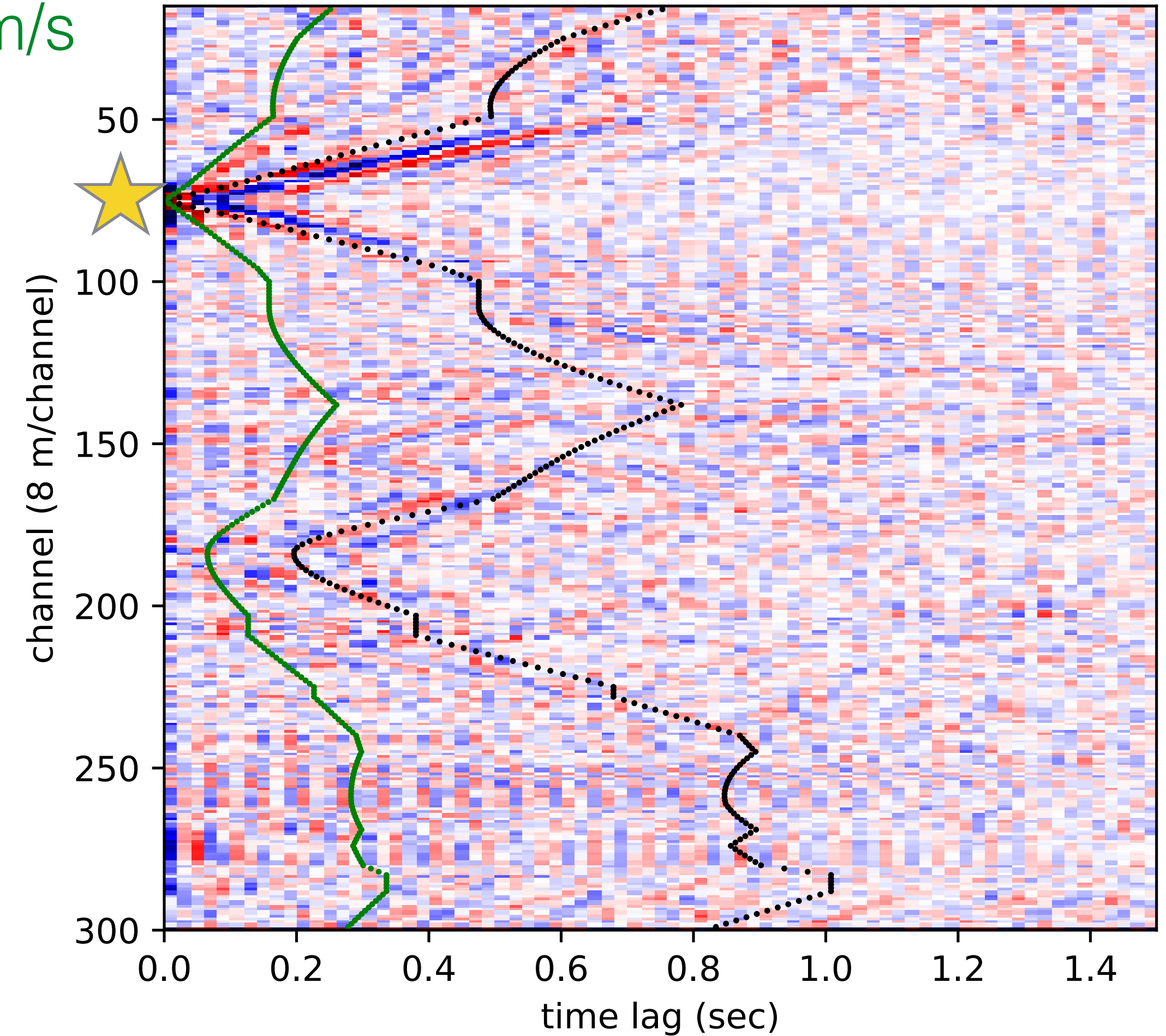
# 1-bit cross-correlation, 5 day

one bit cross-correlation, virtual source 35

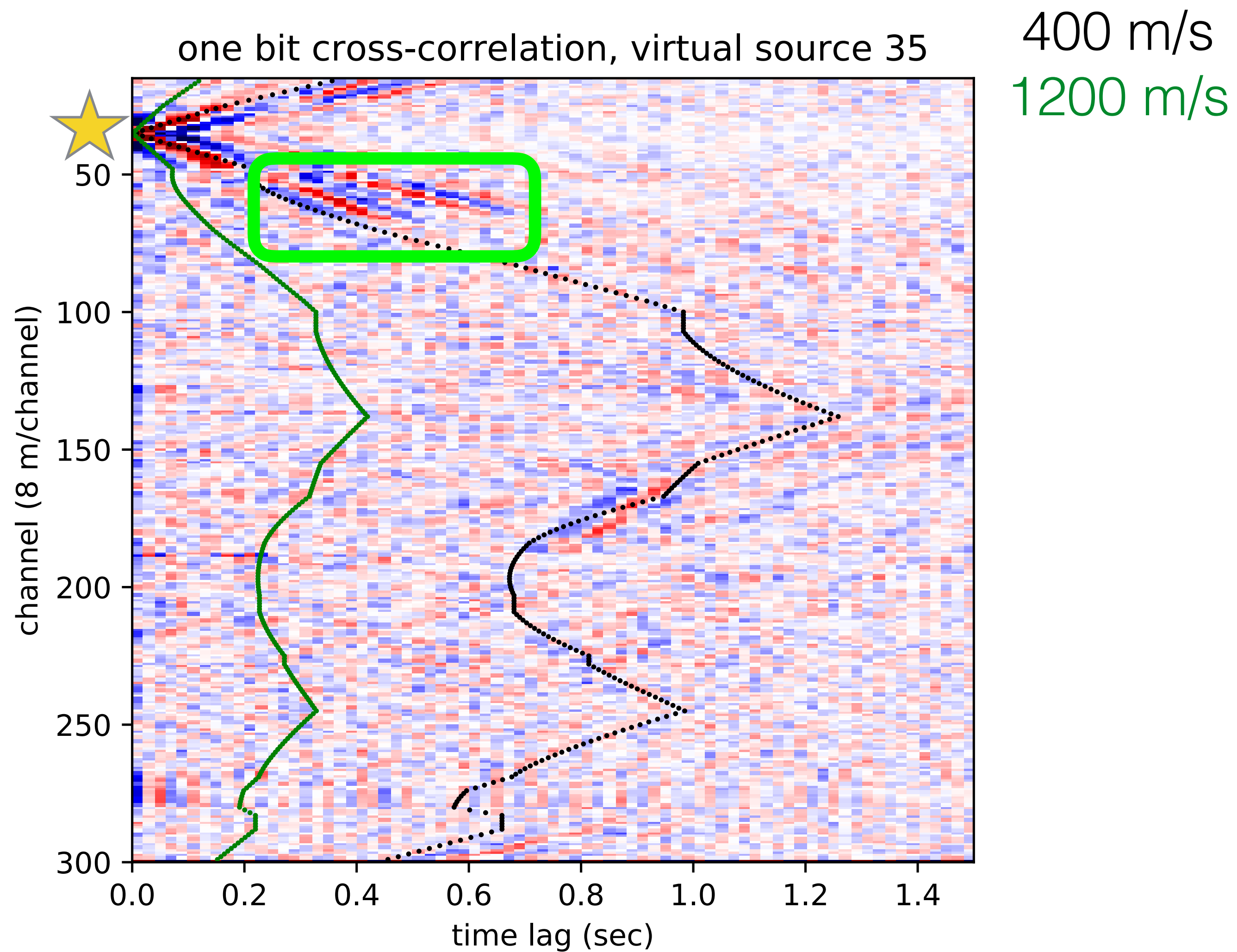


400 m/s  
1200 m/s

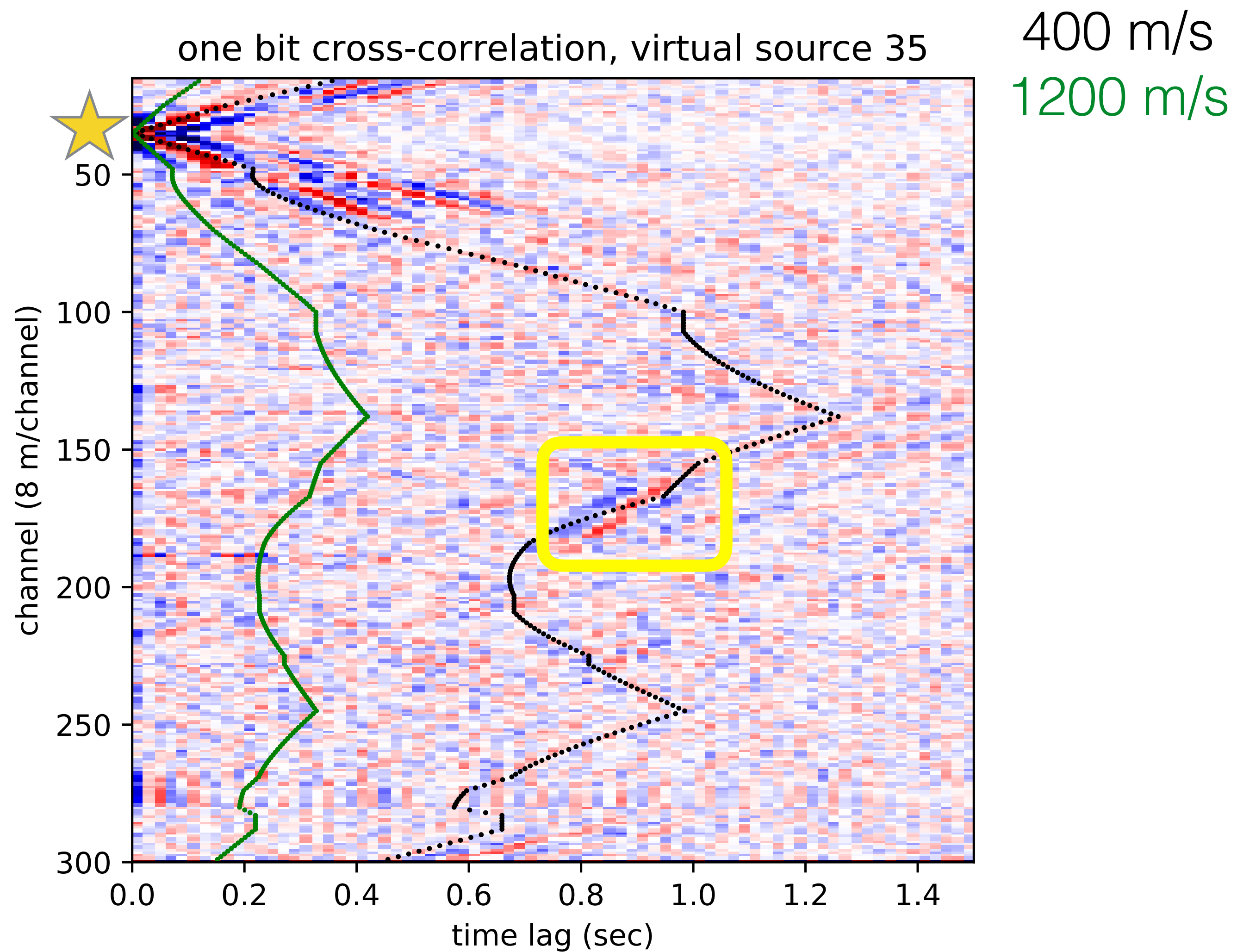
one bit cross-correlation, virtual source 75



# 1-bit cross-correlation, 5 day

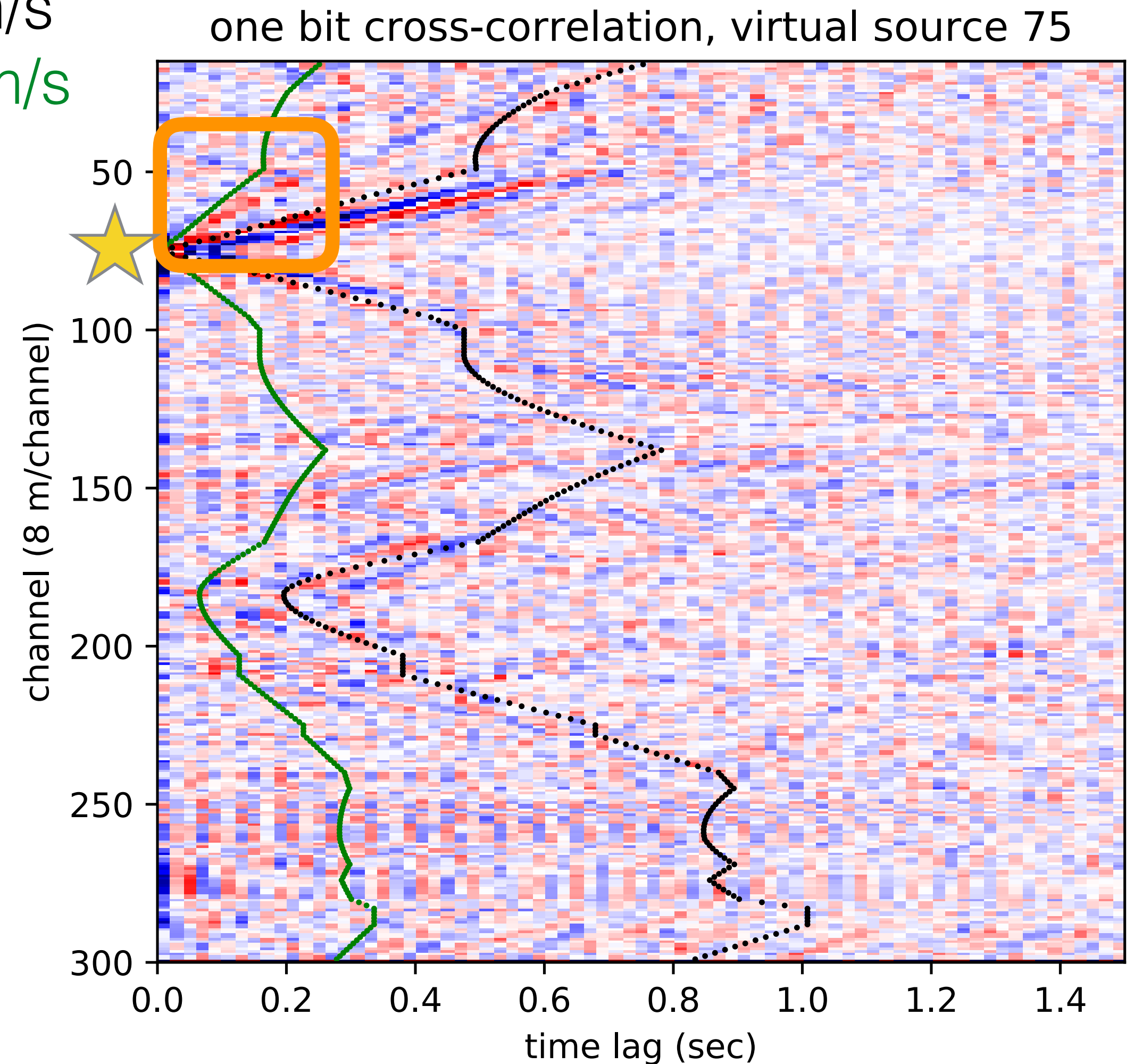


# 1-bit cross-correlation, 5 day



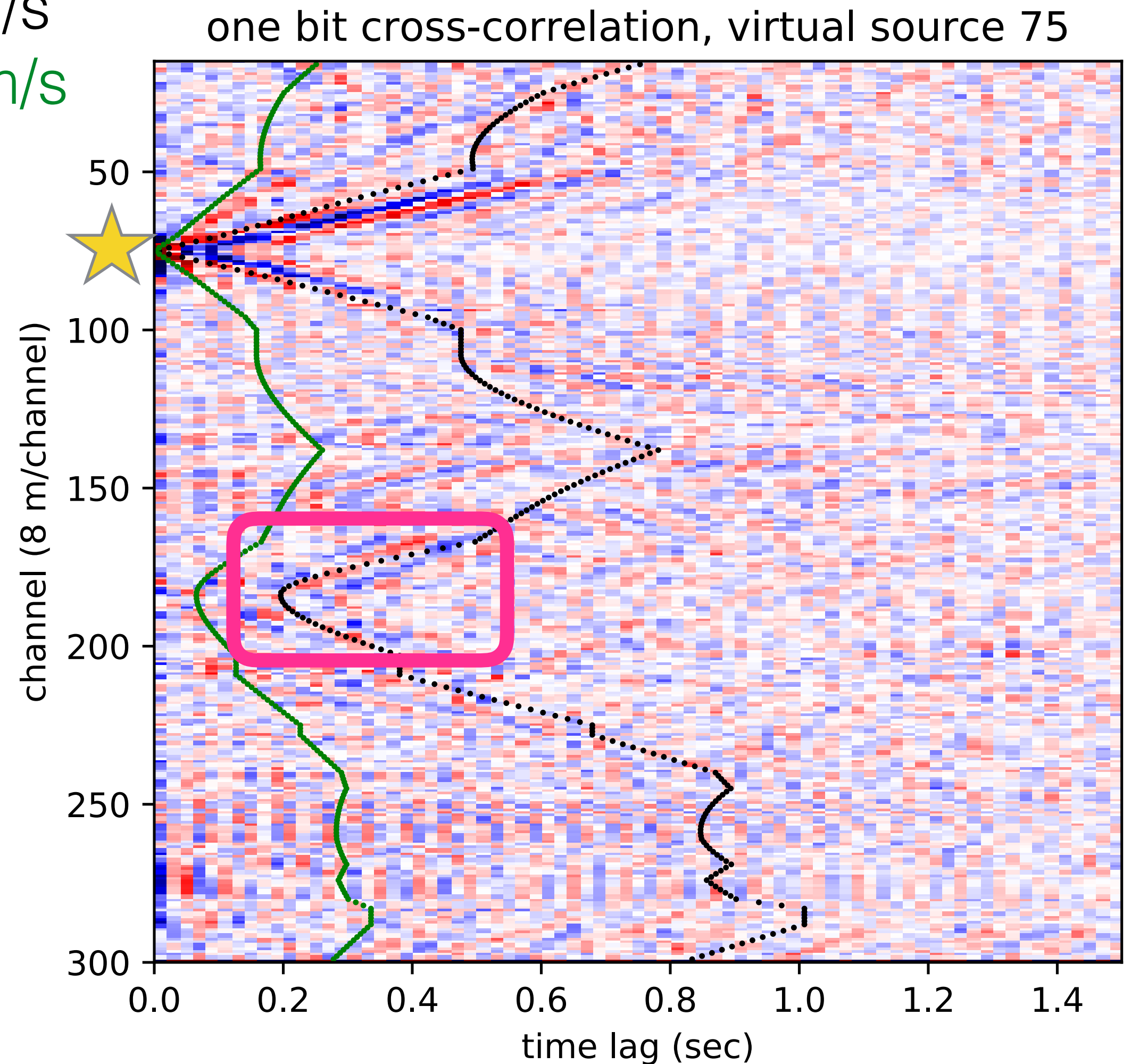
# 1-bit cross-correlation, 5 day

400 m/s  
1200 m/s



# 1-bit cross-correlation, 5 day

400 m/s  
1200 m/s



# Summary:

We can extract virtual source responses throughout 2D DAS arrays, greatly increasing the usable ray path coverage of passive DAS arrays.

The extracted responses show some features predicted by theory.

We are working towards a more automated, unified workflow.

# Open questions:

How do we reliably select Rayleigh and Love waves from mixed outputs?

Does this work at other sites (Fairbanks, AK or Richmond, CA)?

How can we use the R-T and T-R components for near surface imaging?



# Acknowledgements

## **Advice and useful discussions:**

Bob Clapp, Jason Chang, George Papanicolaou, Jonathan Ajo-Franklin (LBL),  
Nate Lindsey (Cal), Shan Dou (LBL)

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Schlumberger Innovation Fellowship (E. Martin)

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SERDP grant RC-2437 (permafrost thaw tests, LBL and Corps of Engineers)

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Carson Laing (OptaSense)

Martin Karrenbach

Stewart Levin

Chris Castillo

Ethan Williams

Shanna Chu

Jon Claerbout



**Schlumberger**



## **Computing, Equipment, and Resources:**

Stanford Center for Computational Earth and Environmental Science

Stanford IT (fiber team)

Stanford SEES IT

OptaSense (ODH-3 Interrogator Unit)

Subsea Systems (GPS trigger timing)

**OptaSense**<sup>®</sup>  
a QinetiQ company

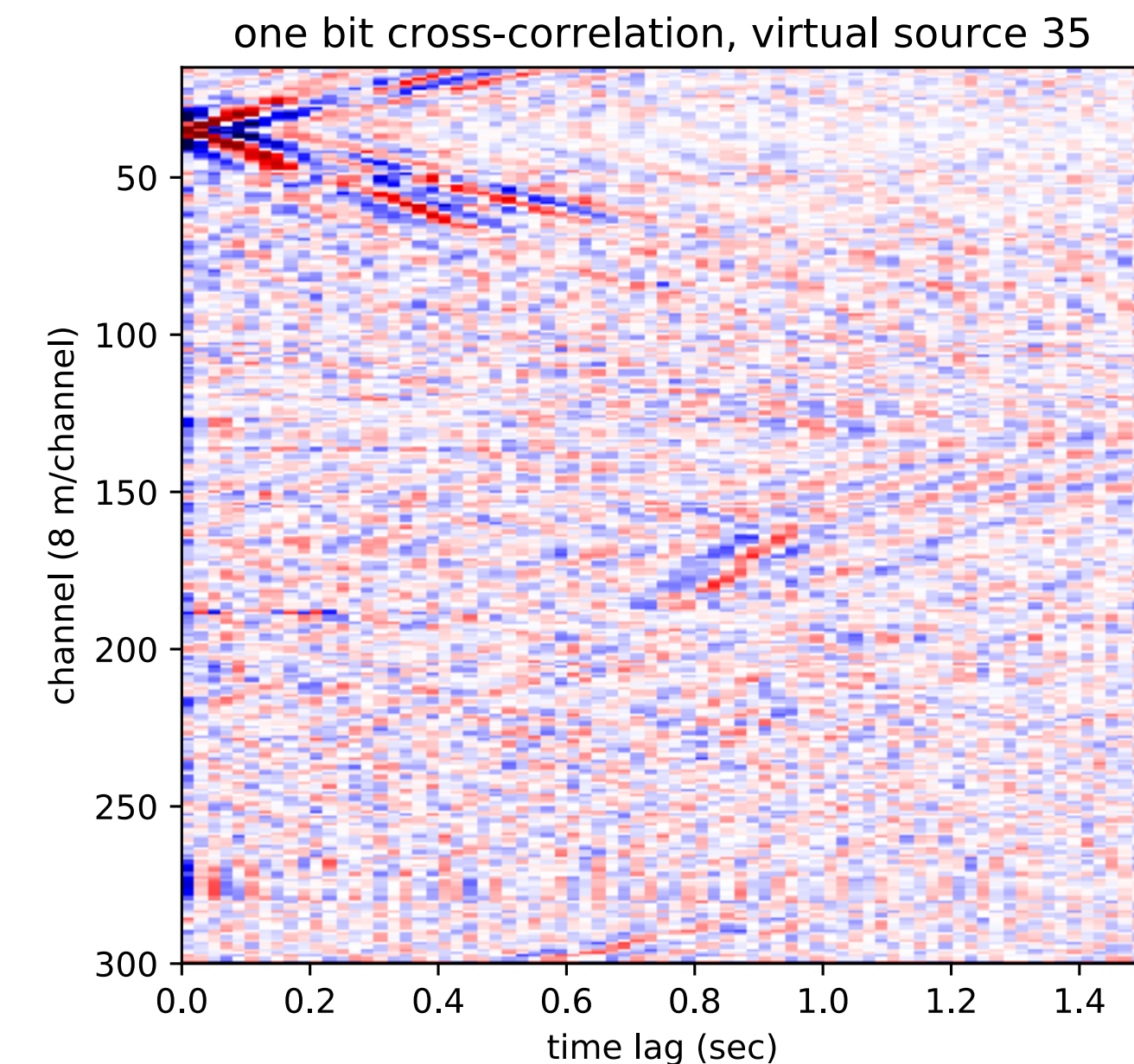
# Summary:

We can extract virtual source responses throughout 2D DAS arrays, greatly increasing the usable ray path coverage of passive DAS arrays.

The extracted responses show some features predicted by theory.

We are working towards a more automated, unified workflow.

# Questions?



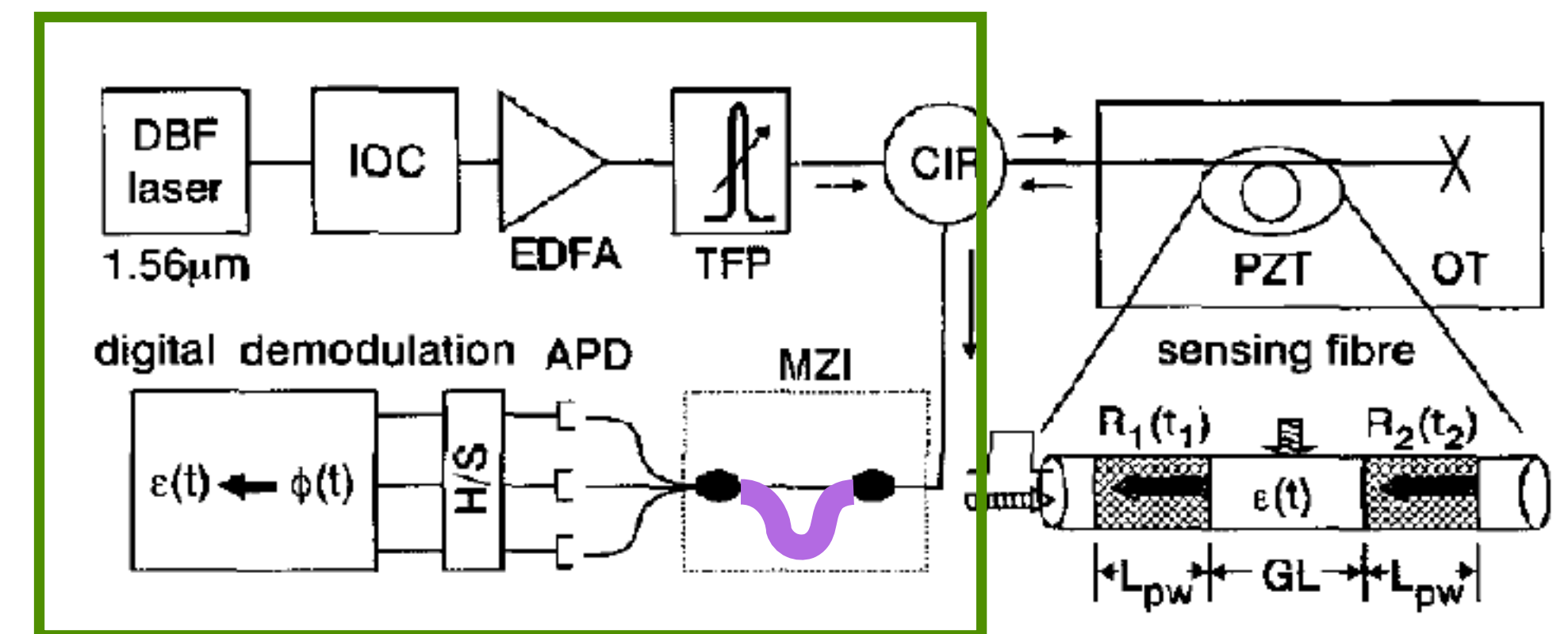
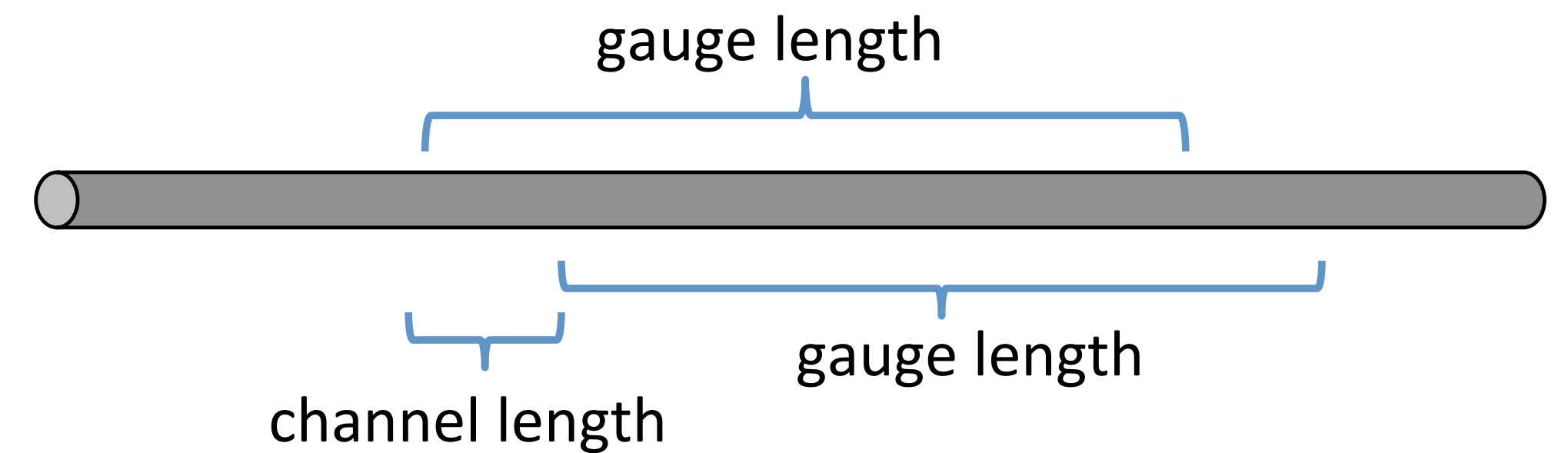
# Extra information

- Benefits/drawbacks of DAS
- Earthquake recordings and sensitivity
- More on permafrost thaw tests
- Infrastructure related artifacts

# benefits and drawbacks of DAS

Lower cost per sensor  
High repeatability of sensor locations  
Cover large range (not moving subsets)  
Flexible sensors  
**High density that can be changed**

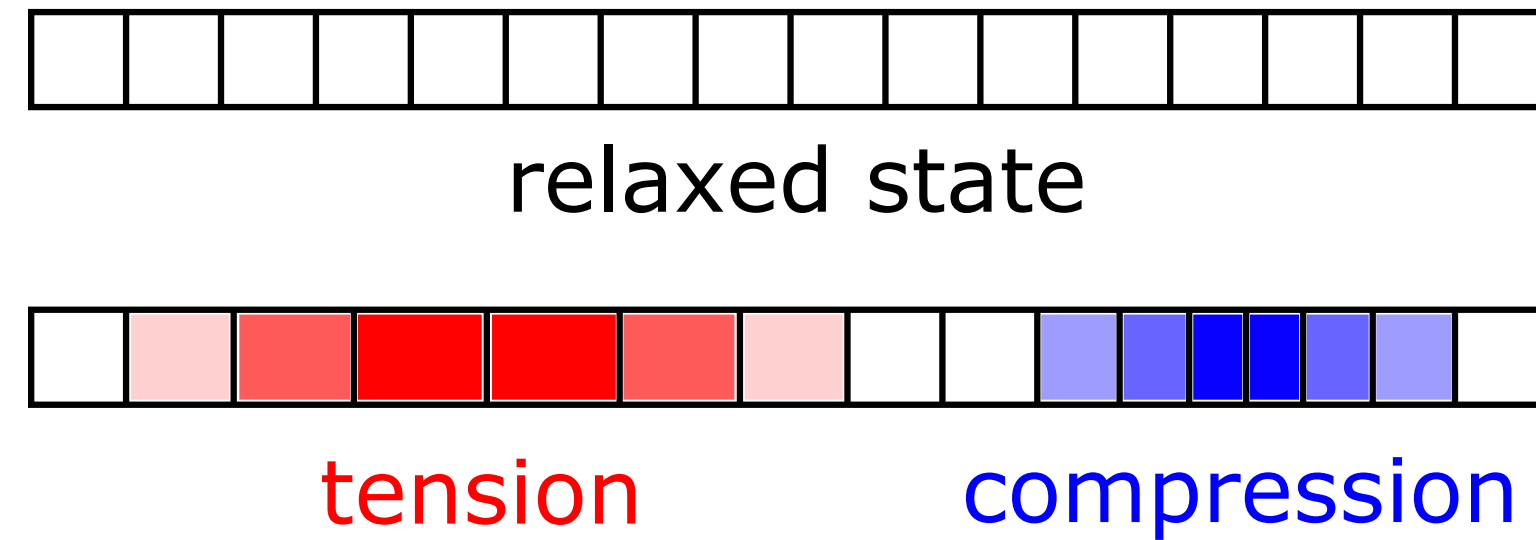
Lower sensitivity to broadside waves  
Blind to certain frequencies  
Some laser drift noise



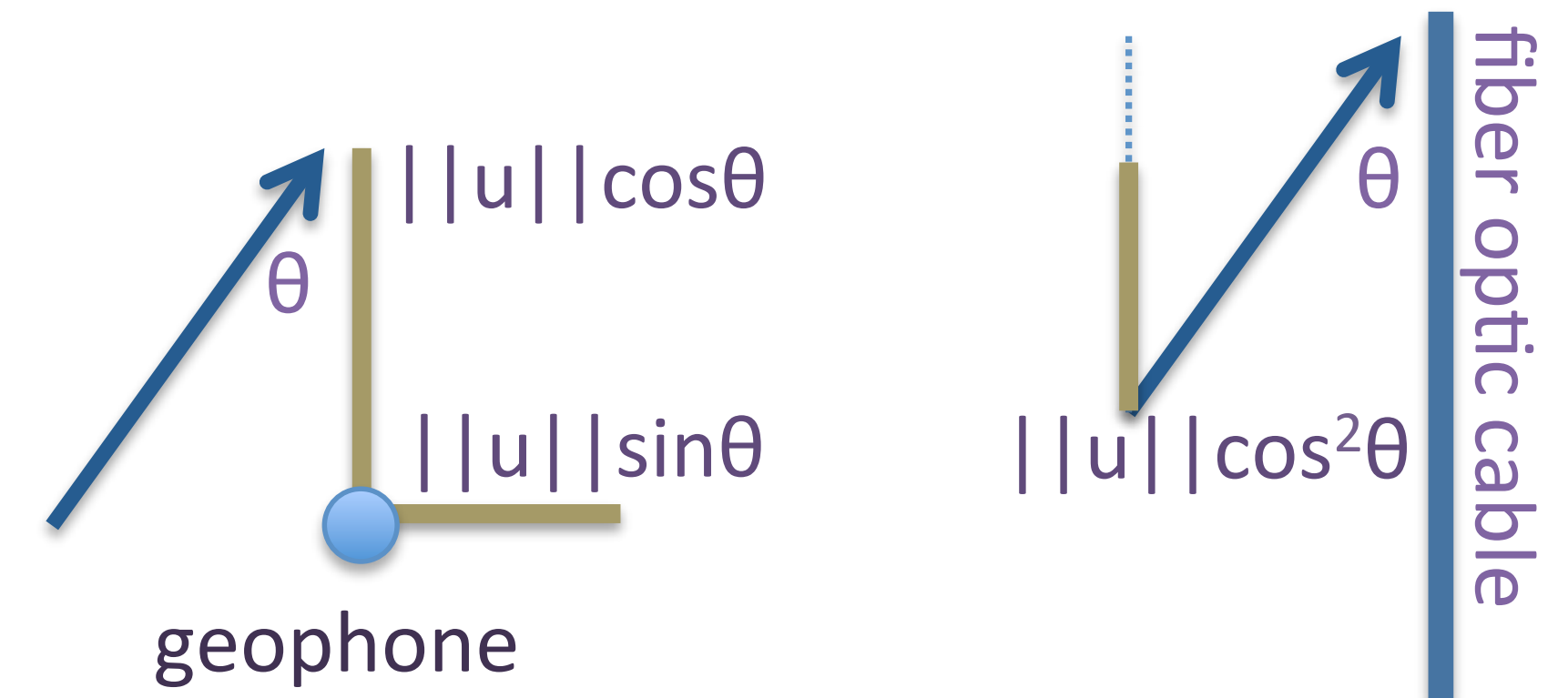
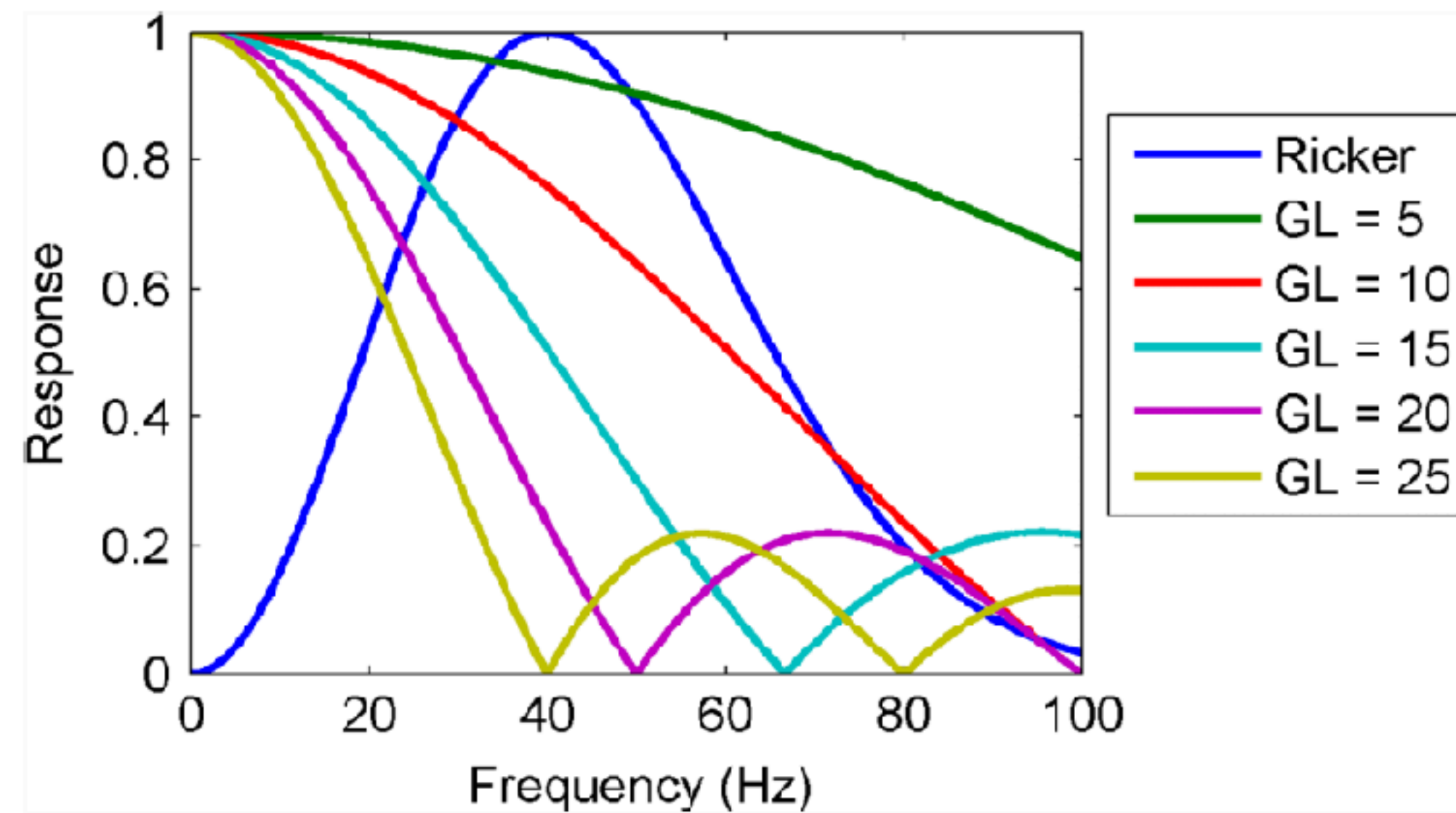
interrogator unit

# Limitations of DAS

Blind frequencies

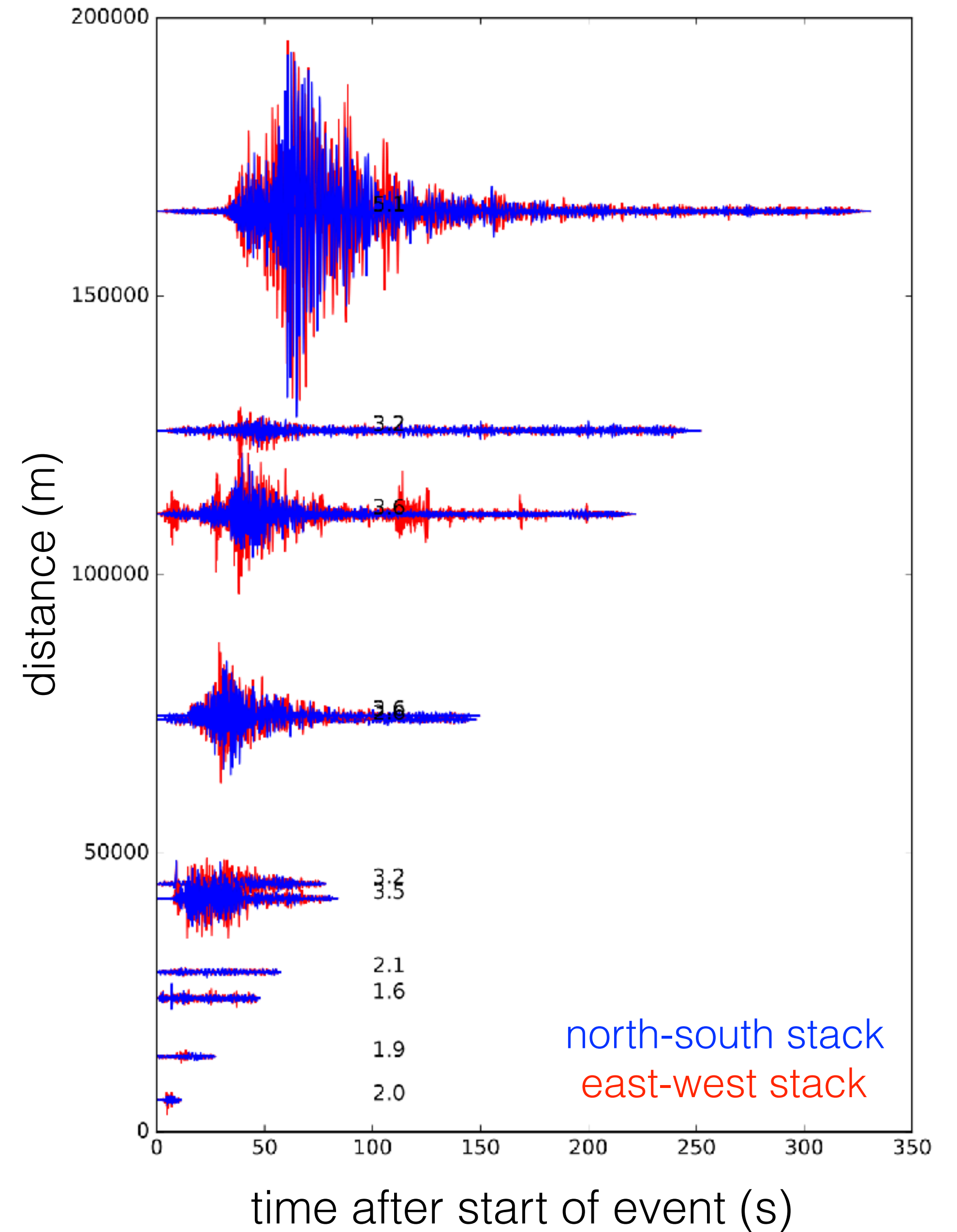
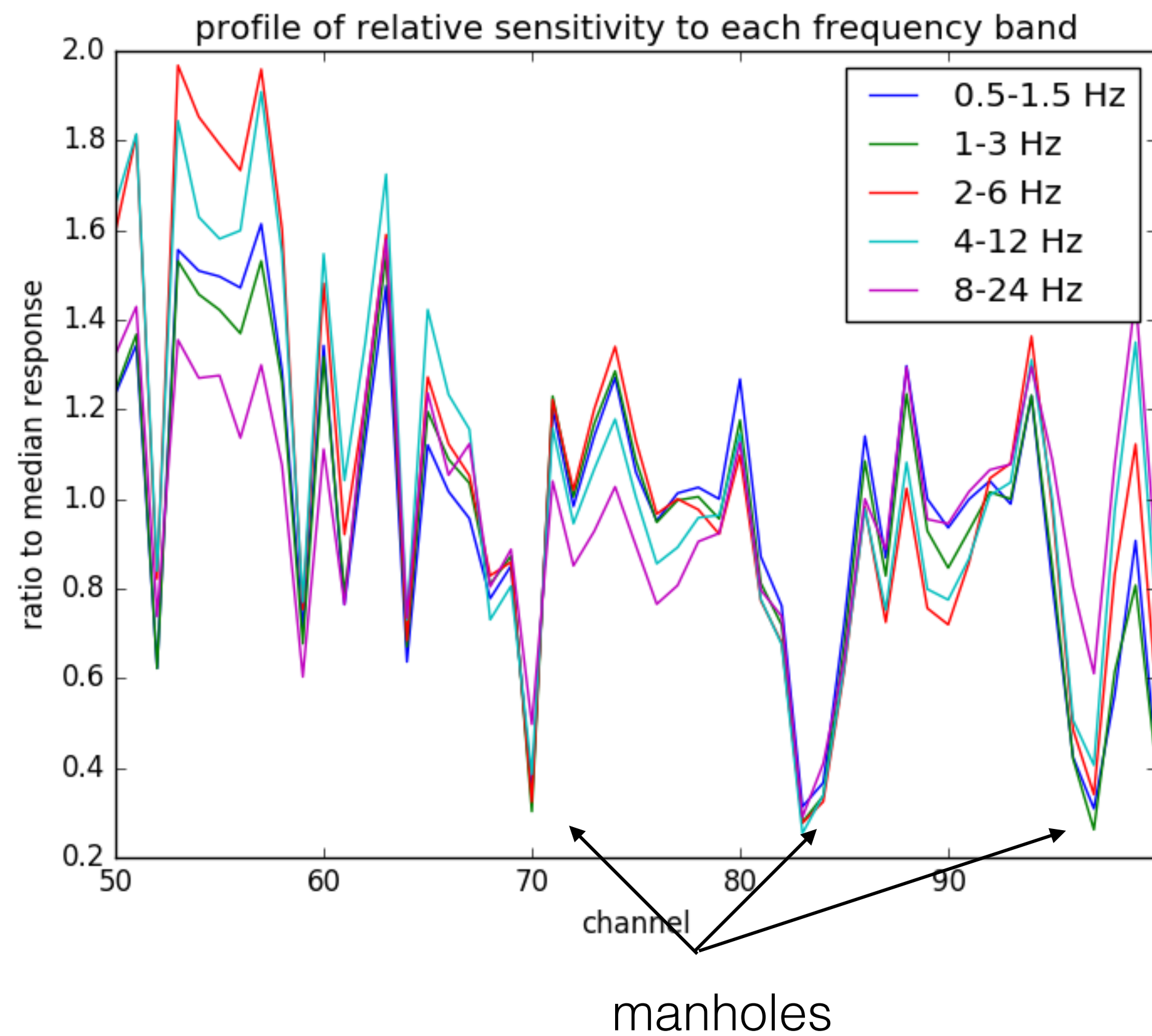


Lowered sensitivity to waves coming at an angle ( $\cos^2$  vs  $\cos$ )

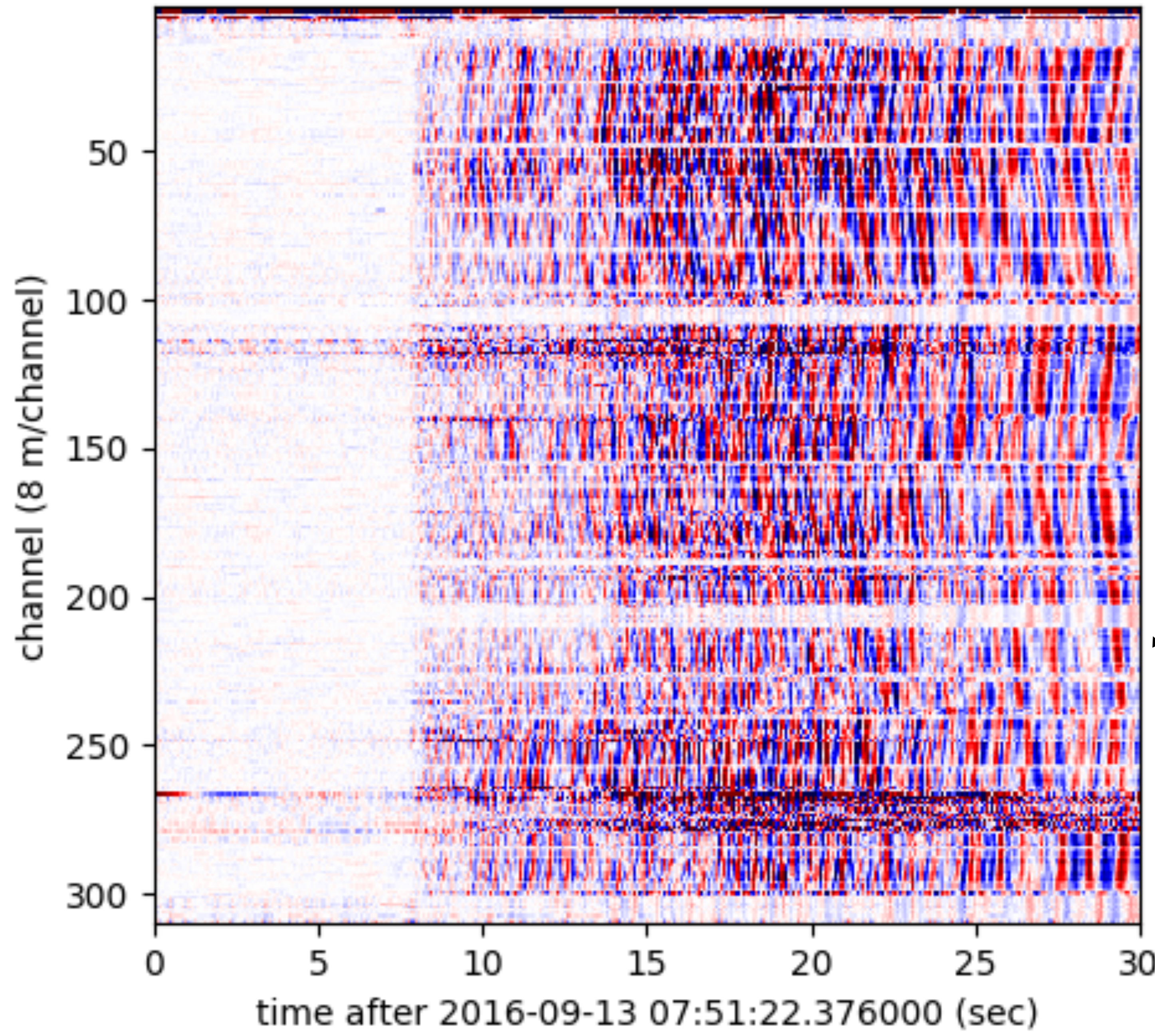


# Nearby Earthquakes

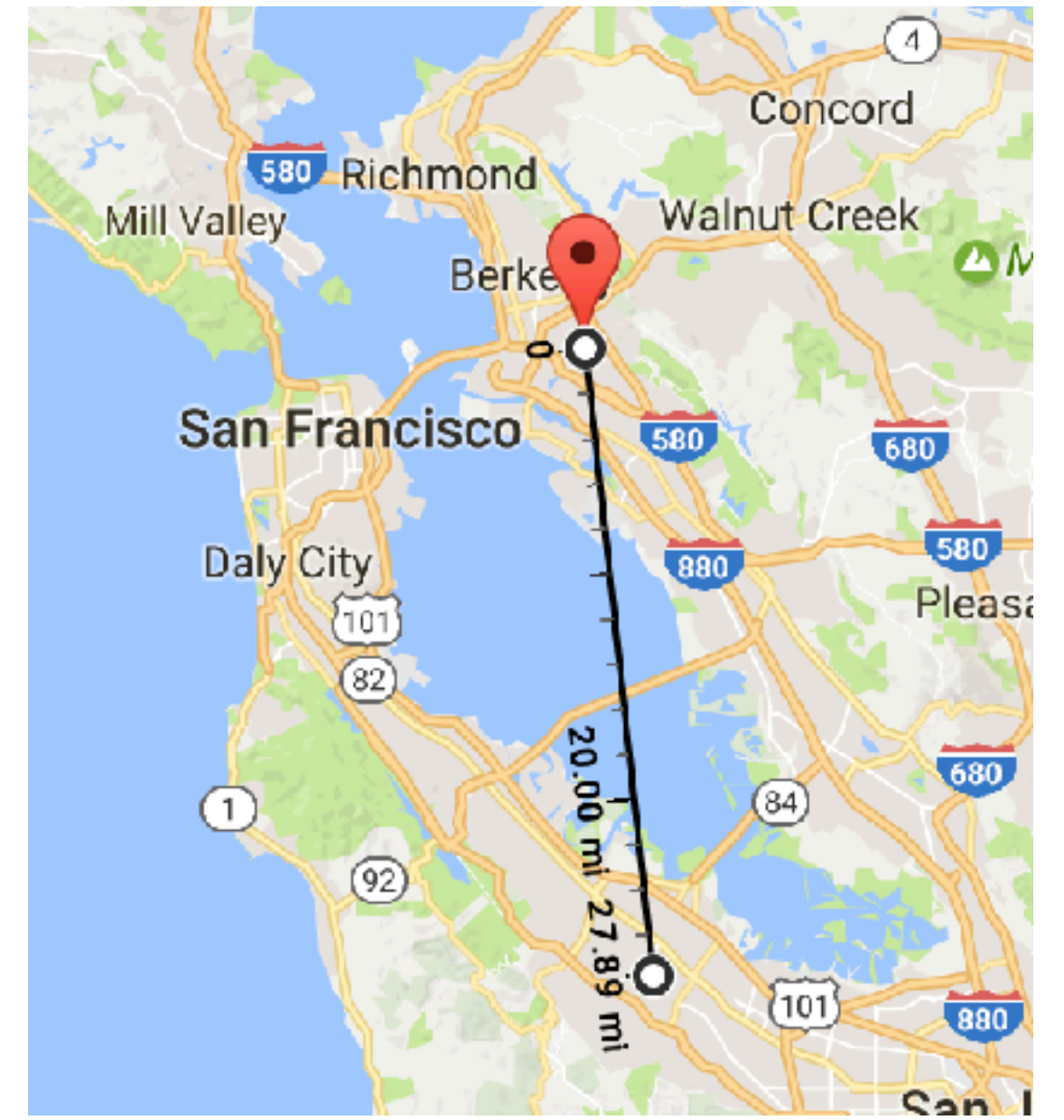
heterogeneous response



P S



# Piedmont M 3.5

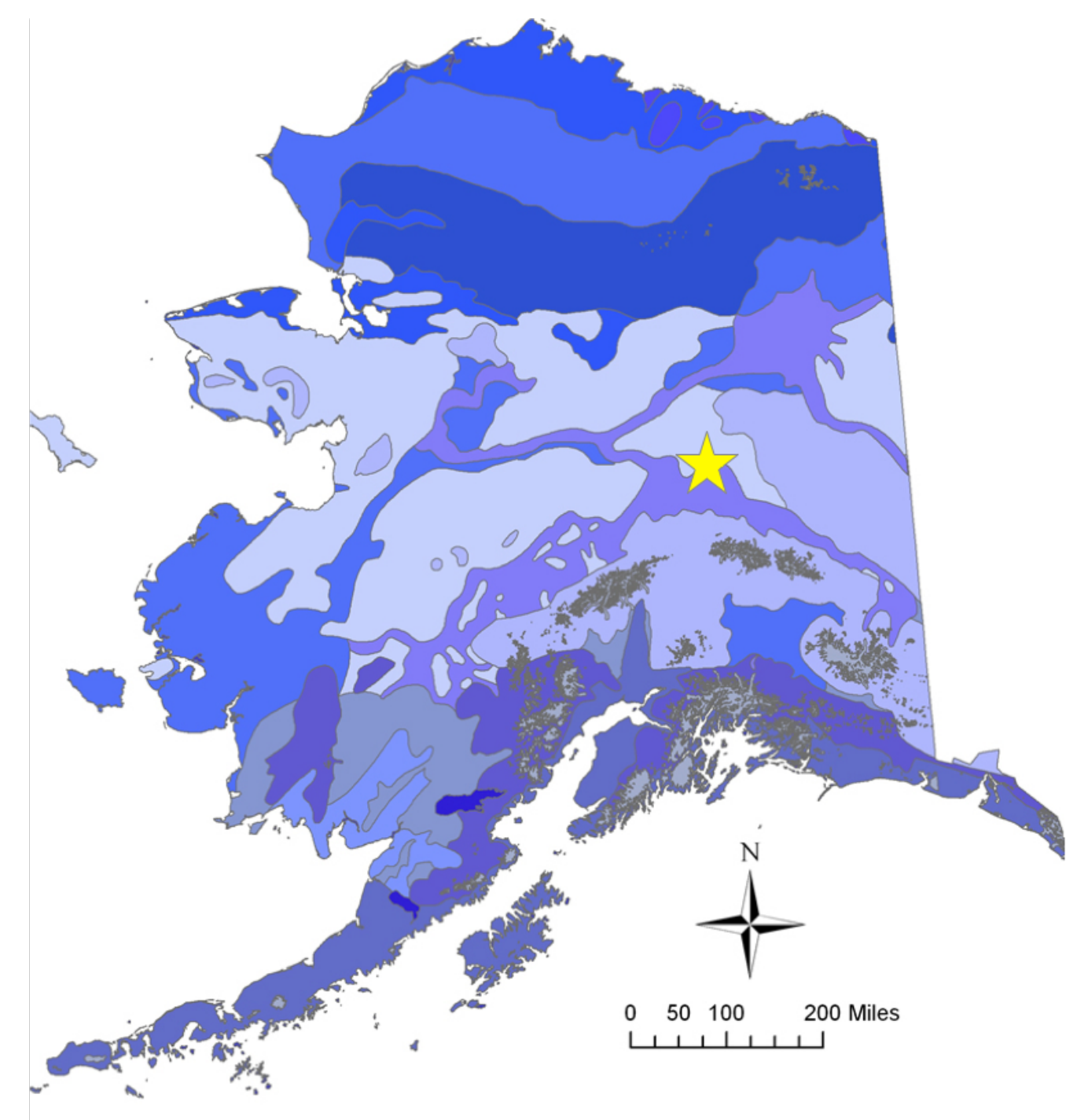


150 ft fiber loops  
in manholes

# Developing Smart Infrastructure for a Changing Arctic Environment Using Distributed Fiber-Optic Sensing Methods

PI: Jonathan Ajo-Franklin, LBNL

Co-PI: Anna Wagner, CRREL



Map from Alaska Public Lands Information

**Goal:** low-cost frequent monitoring of the near surface

**Method:** passive seismic collected by trenched fiber optics with low-cost per sensor



Jonathan Ajo-Franklin, LBNL



Tom Daley, LBNL



Barry Freifeld, LBNL



Michelle Robertson, LBNL



Craig Ulrich, LBNL



Nate Lindsey, UC Berkeley, LBNL



Shan Dou, LBNL



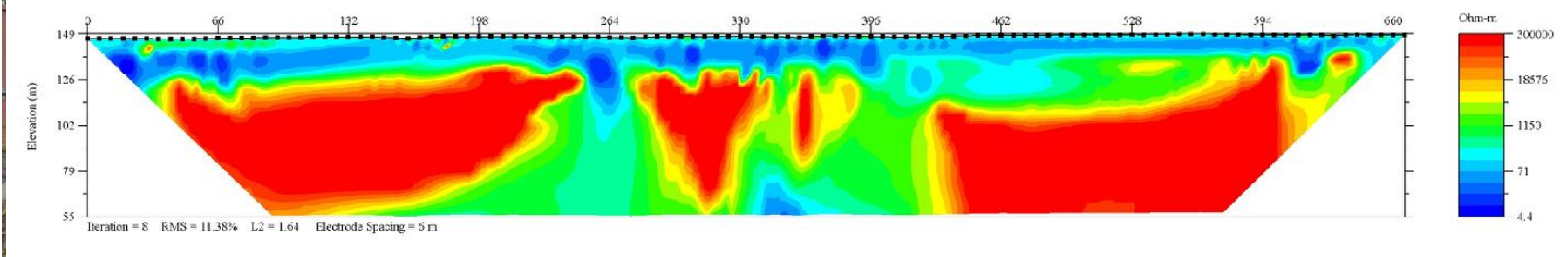
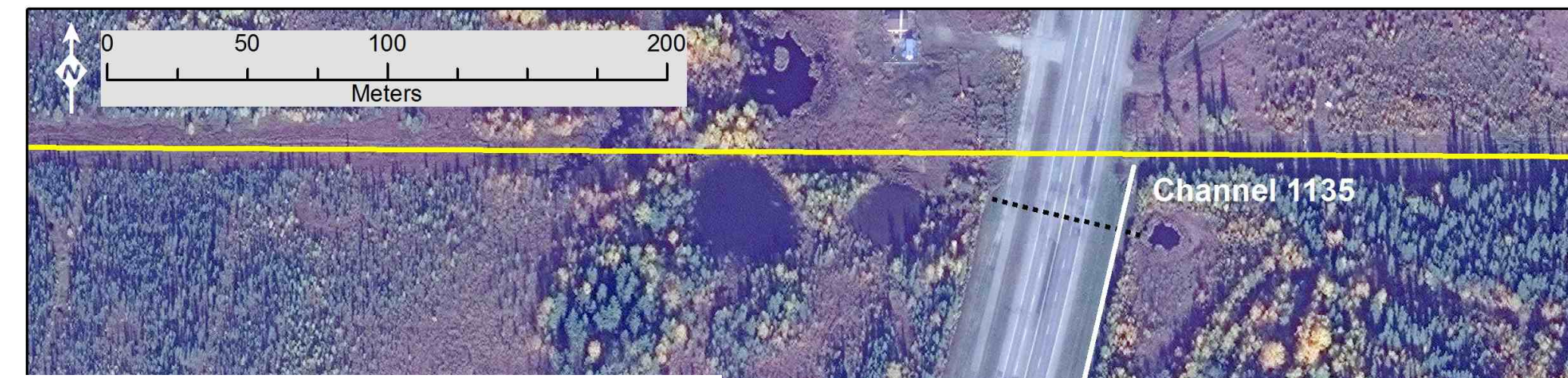
Anna Wagner  
US Army Corps of Engineers  
Cold Regions Research & Engineering Lab



Kevin Bjella



# Site

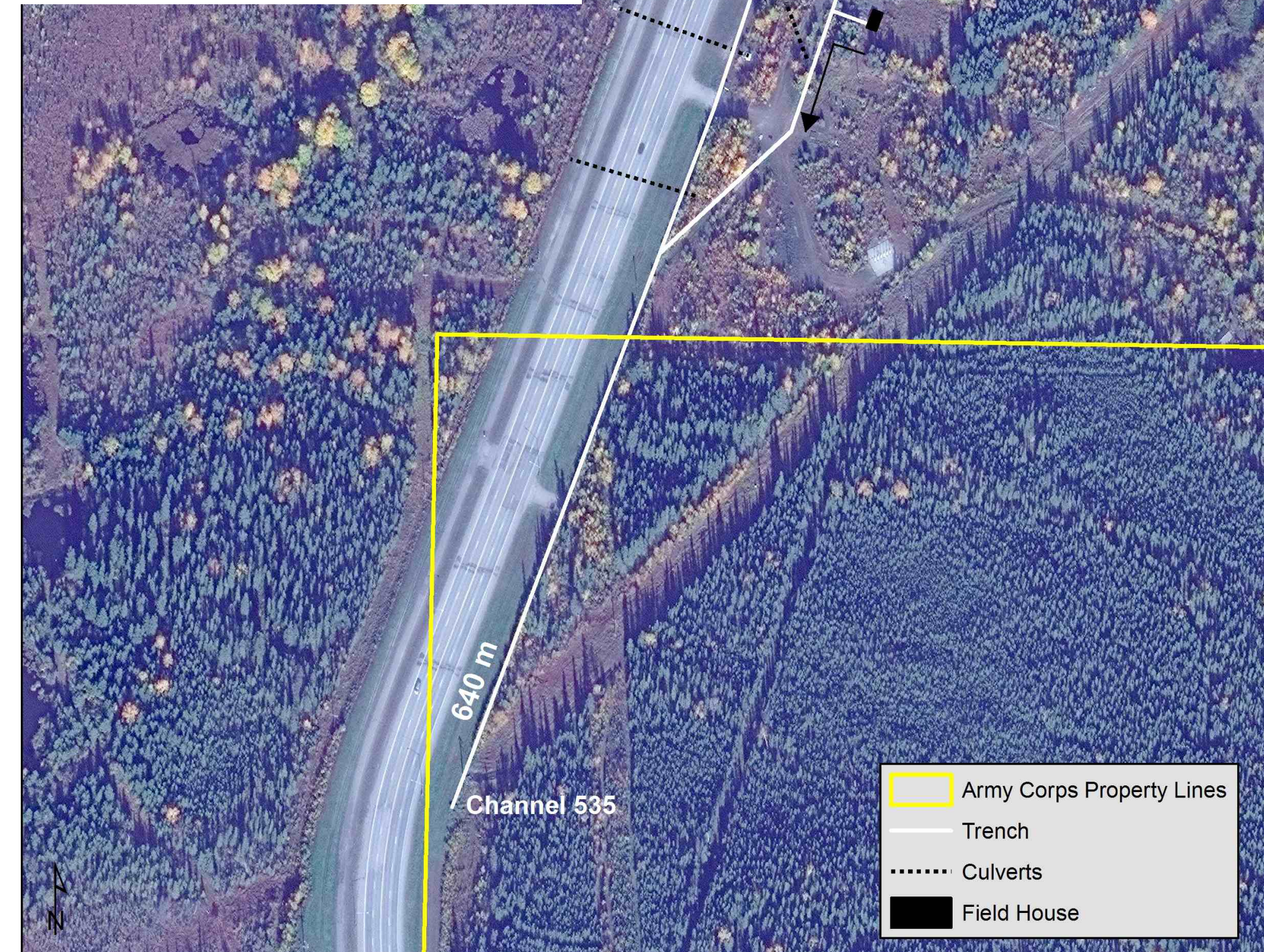


patchy permafrost  
wooded area  
1 mi north of Fairbanks  
highway 400 m east

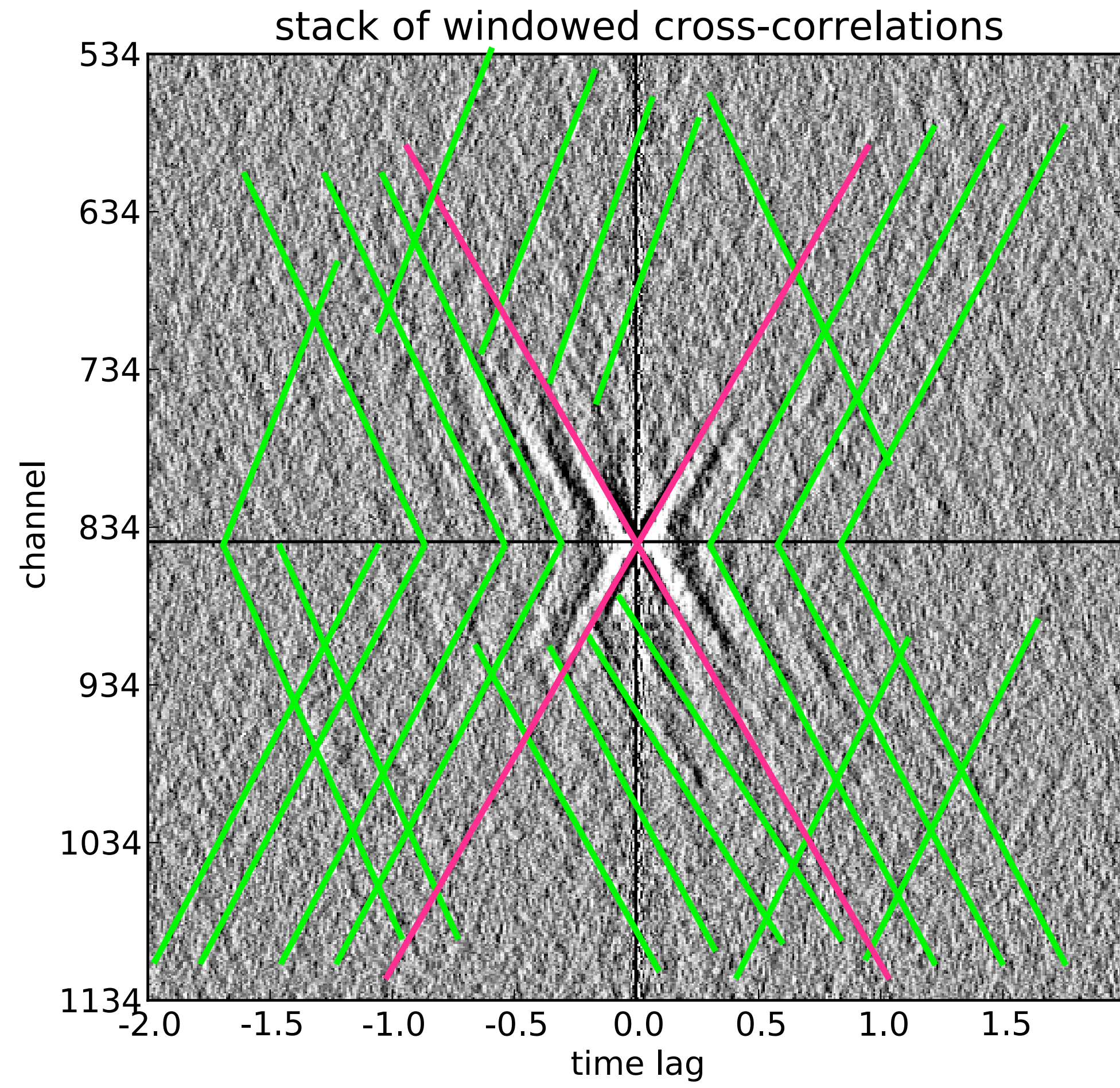
passive recording



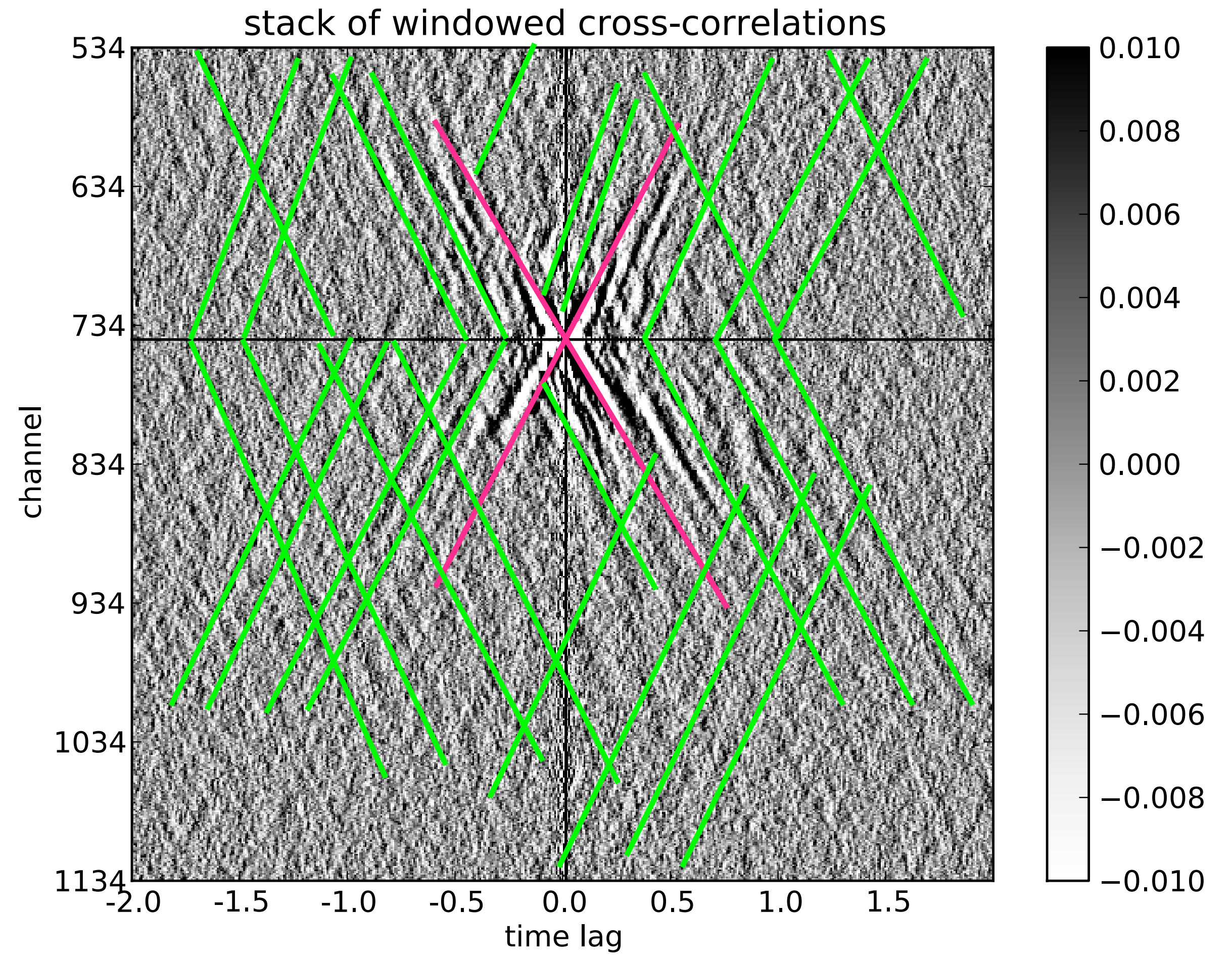
1 m channel spacing  
10 m gauge length  
1 kHz recording



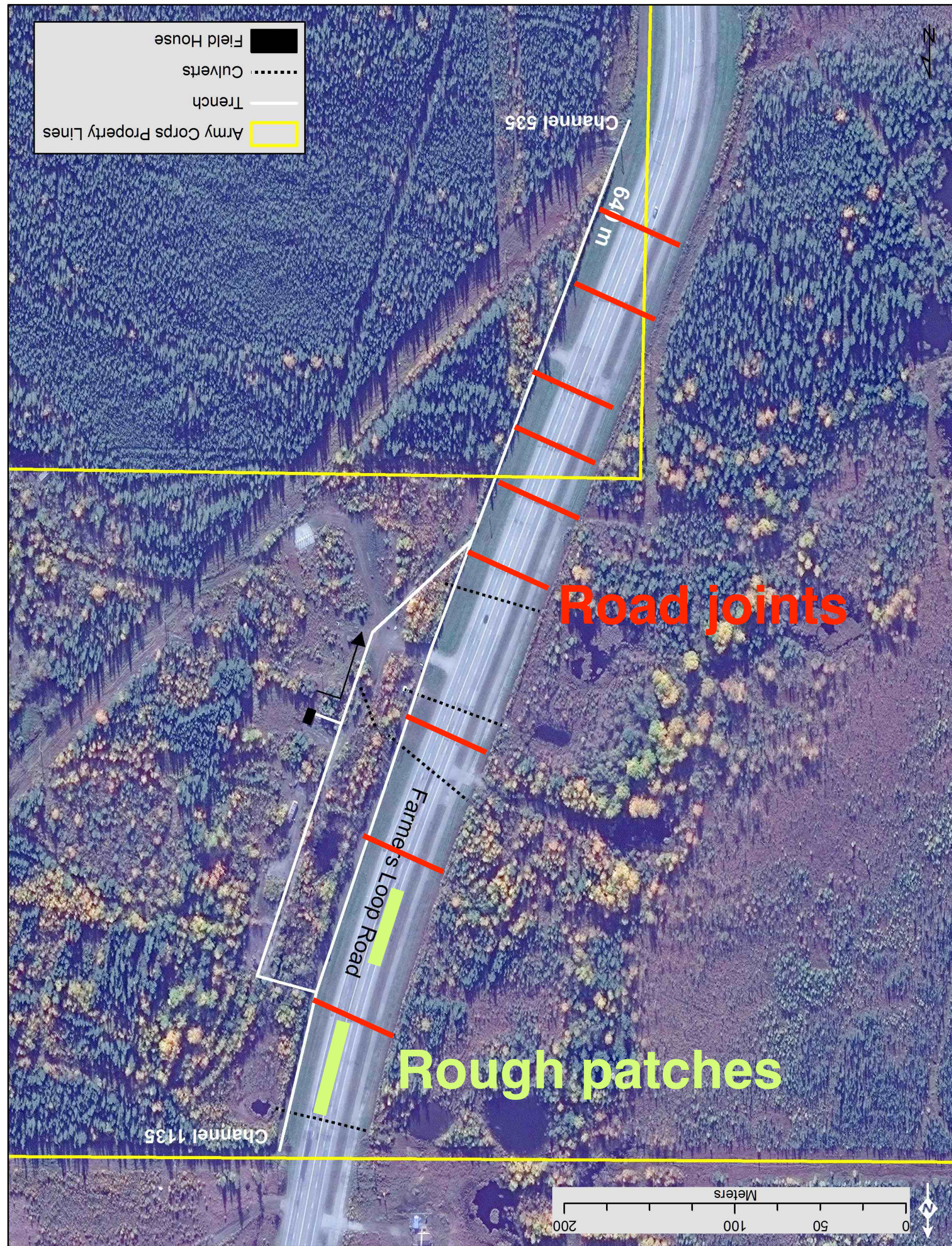
# Cross-correlations



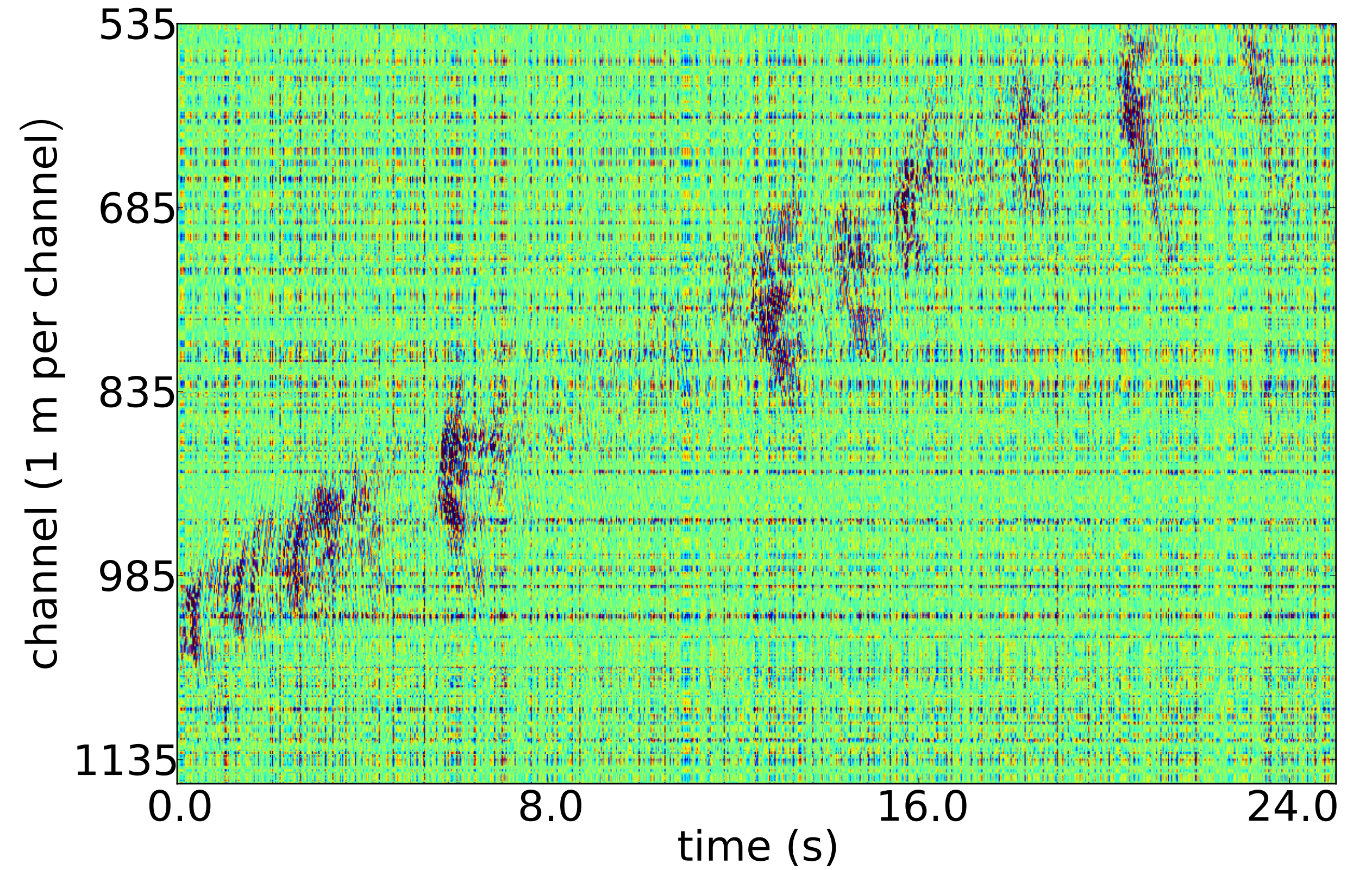
Channel 844



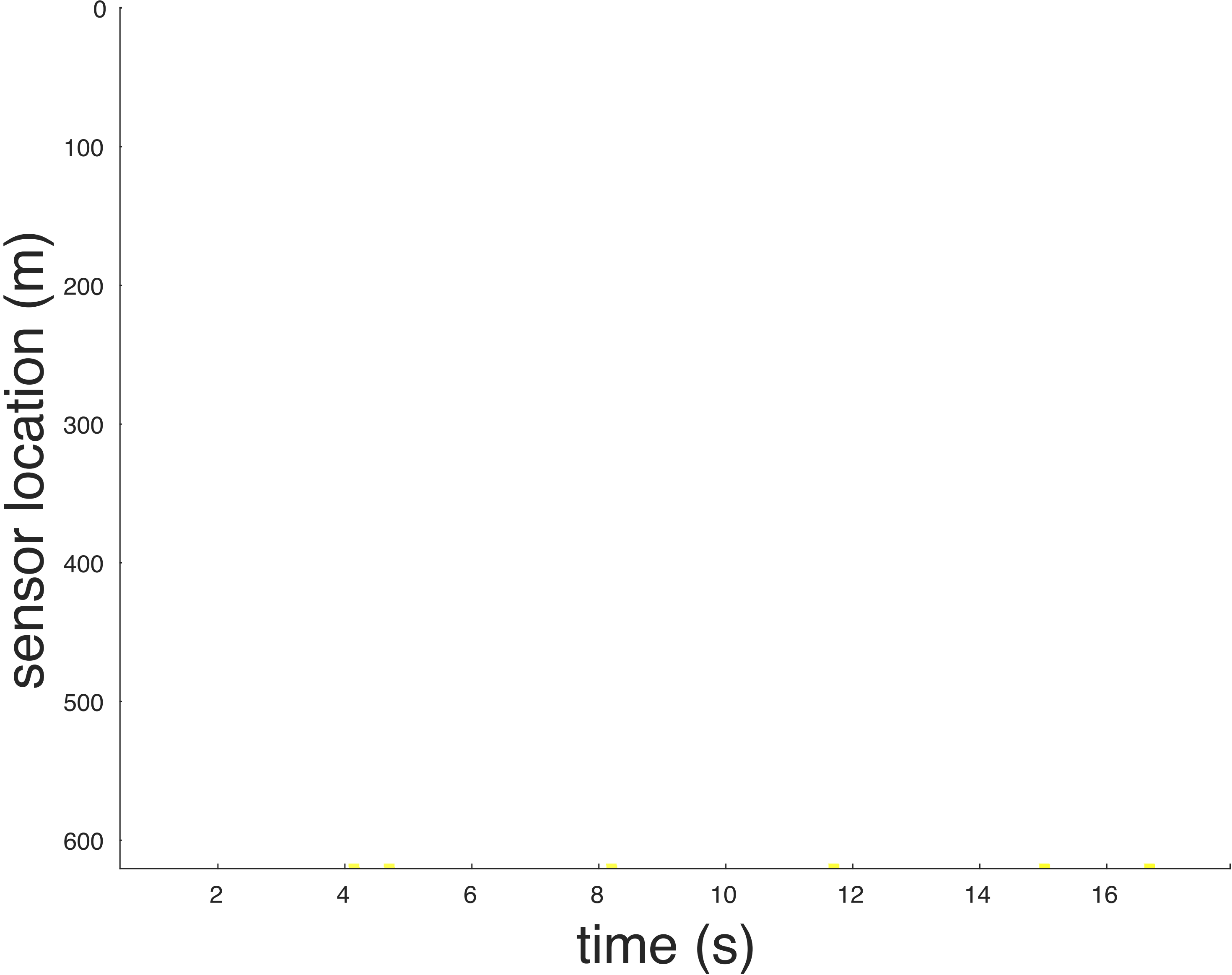
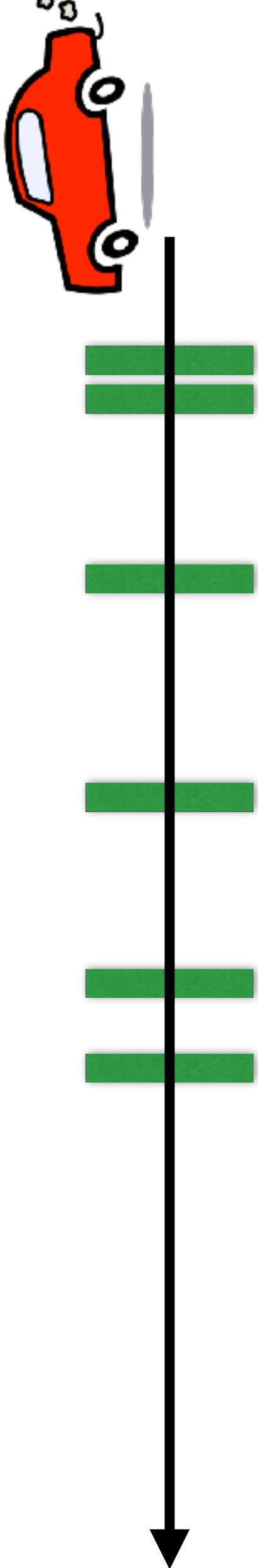
Channel 745



Issue: Theory of ambient noise assumes uncorrelated noise sources.

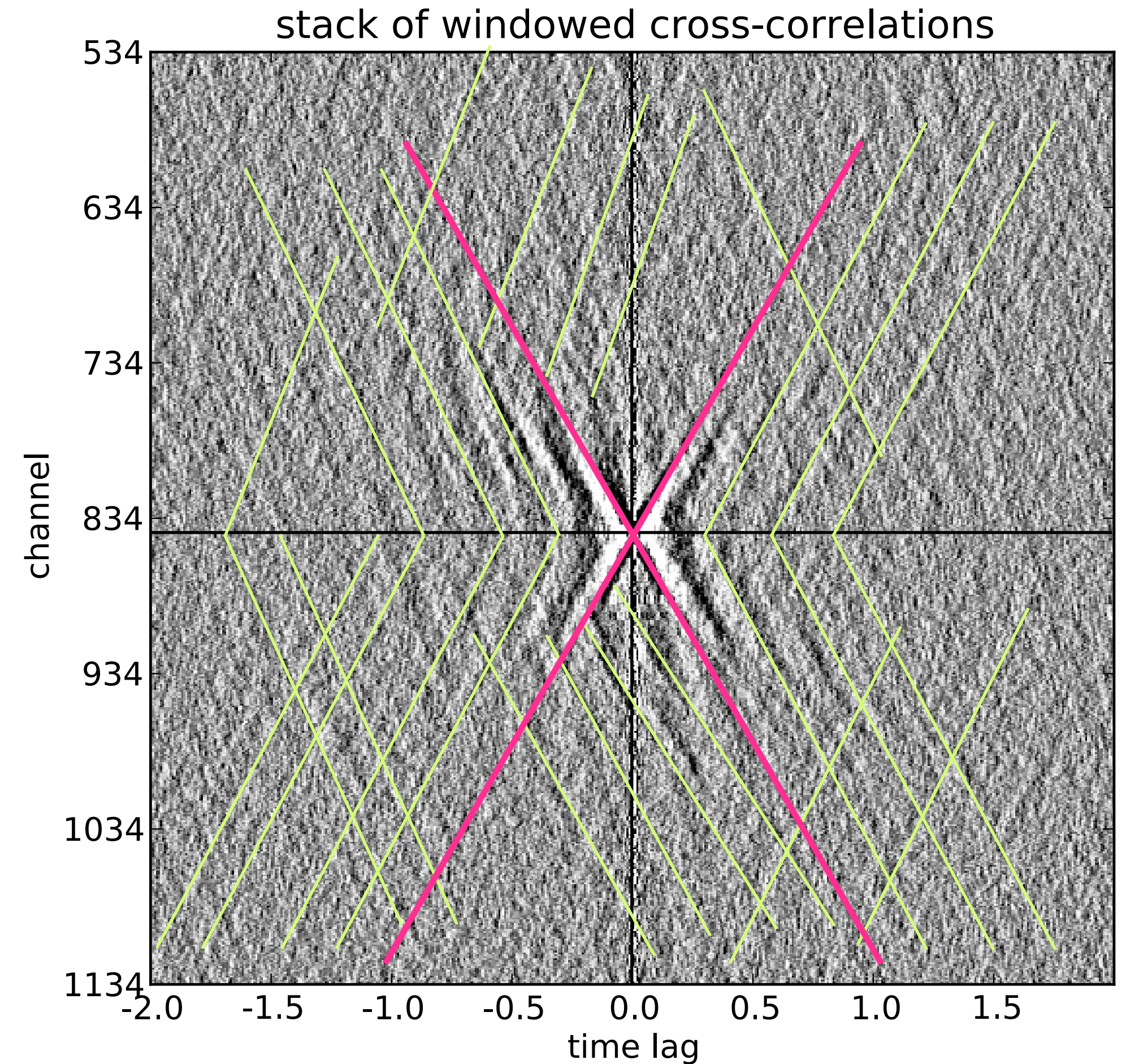
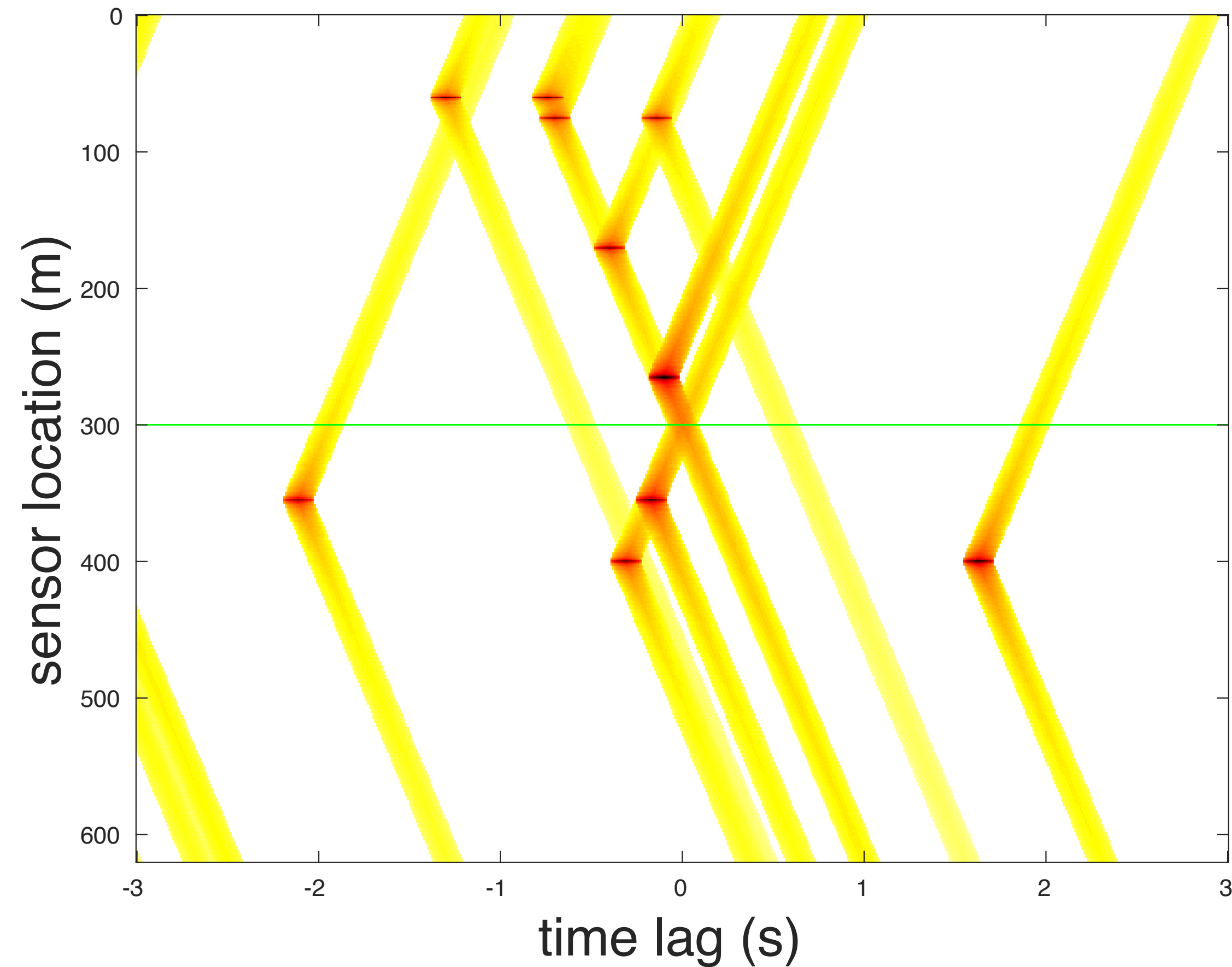


# Time records



# Bumps were probably the cause of artifacts in cross-correlations

**Cross-correlation Virtual Source Ch 300**



Channel 844